

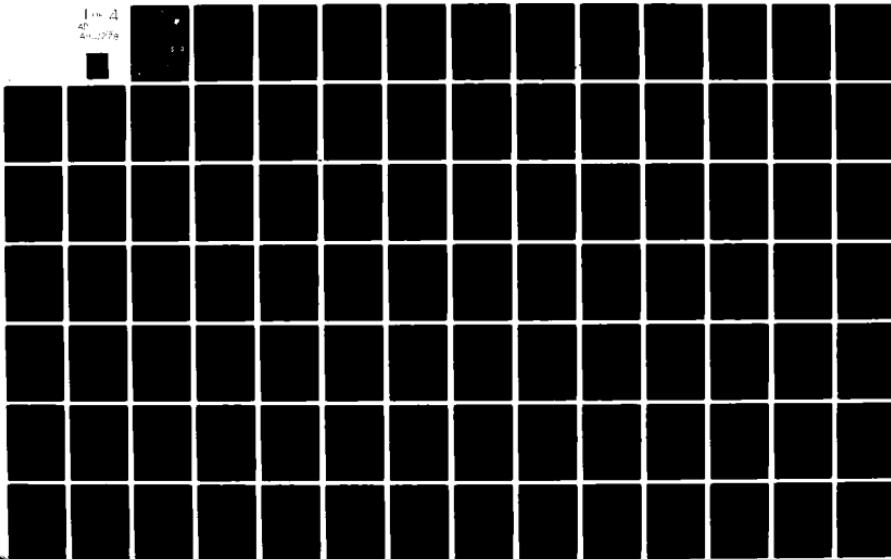
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Final Technical Report
June 1976

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ENDO ATMOSPHERIC-EXO ATMOSPHERIC RADAR MODELING
(Computer Program Documentation)

General Dynamic

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20. ABSTRACT (Continue on reverse side if necessary and identify by block number) This effort is concerned with the development and implementation of a set of digital computer programs that will augment the RADC digital computer radar simulation model procured under Contr F30602-72-C-0393 (01707201). The computer programs shall consist of a sequence of subroutines that correspond to separate functions such as a chaff model, target model, propagation effects and clutter model. The original radar simulation model will be expanded to include a bi-static capability and will include ECM and phase coded pulse compression re-		

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ceiver techniques. In addition, an interactive system has been designed for the simulation. Using an interactive display, an engineer would be able to understand what is happening by being able to observe results at several intermediate points in the problem. A picture is worth a thousand words. For example, an antenna pattern or waveform response to a target is more meaningful than a long table of numerical listings. Parts of the simulation were used by RADC for Deep Space Surveillance Radar (DSSR) waveform analysis, generating antenna patterns and tradeoffs involving phase shifter bit-size for the Advanced Space Defense Program (ASDP). The RADC radar simulation model is being used to support Seek Sail, Cobra Judy, Digital Coded Radar and Seek Sentry.

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Vol I, Pt 2 contains Section 8 (Pages 8-1 thru 8-174).

Vol I, Pt 3 contains Section 8 (Pages 8-175 thru 8-418).

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Vol II, Pt 2 contains Sections 9 and 10 (Pages 9-1 thru 9-234 and Pages 10-1 thru 10-4).

Vol III contains Sections 1 thru 6 (Pages 1-1 thru 1-2, 2-1 thru 2-22, 3-1 thru 3-53, 4-1 thru 4-141, 5-1 thru 5-3 and 6-1).

Vol IV, Pt 1 contains Appendices A-K and Appendix M.

Vol IV, Pt 2 contains Appendix L.

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S E C T I O N 1

I N T R O D U C T I O N

This volume of the final technical report contains the descriptions of the computer programs and subprograms which constitute the Radar System Simulation Model.

The simulation model computer program is divided into two distinct phases: (1) Data initialization activity, and (2) Simulation activity. In terms of software, each phase is composed of one main and a group of subprograms.

The subprograms are divided into five distinct groups: Stimulus/transfer function modules, connection modules, peripheral modules, supervisory modules and subordinate modules. These groups are more fully described in the sections devoted to each group.

The flow charts and cross reference tables for the entire Radar System Simulation Model are located in Part 2 of this volume.

The module descriptions, program listings, flow charts and cross reference tables have all been cross indexed and are located in Section 10. This section has been included in both parts of the volume for convenience.

S E C T I O N 2

S I M U L A T I O N D A T A L O A D E R E X E C U T I V E (M A I N - 1)

The simulation data loader serves as the interface between the user and the segment of the computer program which performs the simulation. This segmentation was necessary since input data in a format convenient to the user must be converted to a form suitable for use by the simulation modules. The punch cards which define the simulation to be performed are of two types: simulation control cards and module parameter data cards. The simulation control cards determine what operations are to be performed in the simulation activity. This includes not only the scheduling of modules for execution but also the movement of data to and from temporary storage, and the modification of parameters for multiple executions of a simulation model configuration. Each control card with the exception of ENDPAS, ENDCFG, and ENDJ0B is converted into a control word by the control word generator and placed in the control word block. Each control word contains the code number of the operation to be performed, the module to be executed and data set reference number if required. The module parameter data cards define the parameters of the simulation modules to be executed in the simulation. Each module requiring input data has a unique name-list which contains the input parameters.

Figure 2-1 is a block diagram of the Initializer load module. In the block diagram the data flow paths are shown as solid lines and control paths are shown as dashed lines. Control normally is retained by the Simulation Data Loader Executive but control transfer does occur to the subprograms CLINT and PHENC. The blocks containing the letter M represent data transfers between two storage areas. Arrows are used to indicate the direction of data flow. The blocks containing C&M perform a search operation to determine if the word stored in a buffer is a member of a reference dictionary. If the search is successful, the data in the buffer is transferred to the storage area designated by an arrow. The function served by certain blocks in the diagram are evident from their titles. Those blocks requiring further explanation are discussed in the following paragraphs.

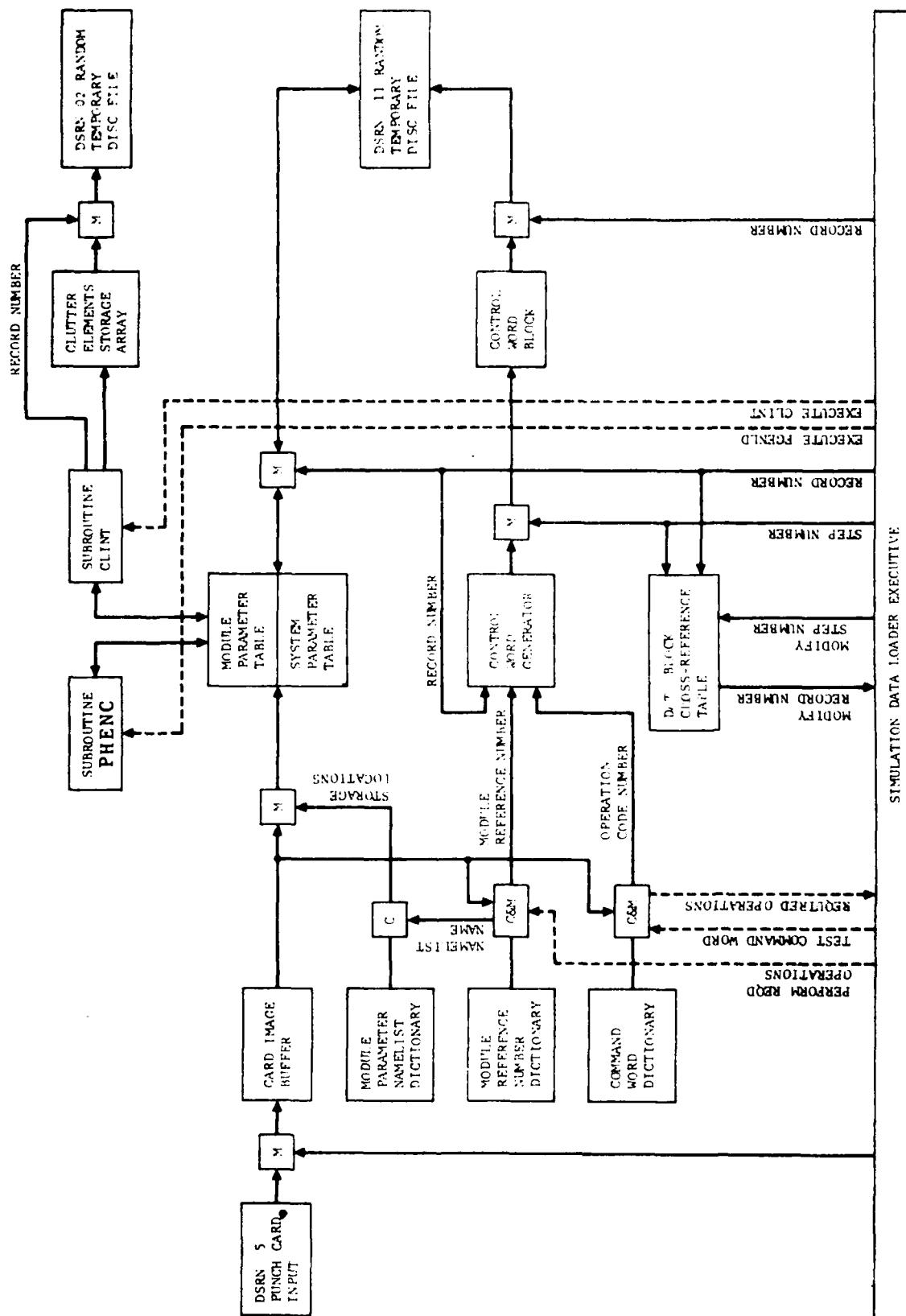


Figure 2-1 DATA INITIALIZATION LOAD MODULE FUNCTIONAL BLOCK DIAGRAM

The Module Parameter Namelist Dictionary serves the function of directing the input data to the proper location within the Module/System Parameter Table. Appendix B contains a list of the parameters in each namelist and the storage location assigned to each parameter. The namelist name is the same as the Module Reference Number, i.e., the namelist for module 101 is NL101.

The Module Reference Number Dictionary is a cross reference between Module Reference Numbers and the overhead operations which must be accomplished prior to execution of a module. For example, to generate a phase encoded waveform requires that the user supplied data be preprocessed by subroutine PHENC.

The Command Word Dictionary is a cross reference between input command words and the operations to be performed in the simulation. The control word is entered in columns 1 through 6 of the simulation control card. The following is a list of the command words and the corresponding operation initiated by each:

EXEC This command word schedules execution of the module corresponding to the number appearing in columns 15 through 17 of the control card. No input data cards are required.

LDEEXEC This command word is the same as EXEC with the additional requirement that input data is read. The namelist name for entering the data is the same as the module reference number contained in columns 15 through 17 of the simulation control card.

MODIFY This command word causes the data loaded in a previous step to be modified. This is typically used to change parameters when multiple simulation passes are to be made. The step number to be changed is entered in columns 10 through 12 of the simulation control card, right adjusted. The Module Reference Number is entered in columns 15 through 17 of the simulation control card.

ENDPAS This command word signifies the end of a pass through a simulation configuration.

<u>ENDCFG</u>	This command word signifies the end of a configuration.
<u>ENDJOB</u>	This command word signifies the end of a simulation job.
<u>STOREX</u>	This command word causes the contents of the XT signal storage array to be stored on a temporary data set, usually a disc file. The Data Set Reference Number is entered in columns 11 and 12 of the simulation control card.
<u>STOREY</u>	Same as STOREX except the contents of signal storage array YT are stored.
<u>STOREA</u>	Same as STOREX except the contents of auxiliary storage array XA are stored.
<u>STOREB</u>	Same as STOREX except the contents of auxiliary storage array XB are stored.
<u>LOAD X</u>	This command word causes the data located in a temporary file to be loaded into the signal storage array XT. The Data Set Reference Number is entered in columns 11 and 12 of the simulation control card.
<u>LOAD Y</u>	Same as LOAD X except the signal storage array YT is loaded.
<u>LOAD A</u>	Same as LOAD X except the auxiliary storage array XA is loaded.
<u>LOAD B</u>	Same as LOAD X except the auxiliary storage array XB is loaded.
<u>REWIND</u>	This command word causes a temporary file to be rewound. For a disc file this moves the access pointer to the beginning of the data set. The Data Set Reference Number is entered in columns 11 and 12 of the simulation control card.

The output from the data loader are stored on temporary storage files. Data Set Reference Number 11 contains the control word block which controls the simulation activity and the module/system parameter tables used to define the modules and system characteristics. Data Set Reference Number 2 contains the clutter scatterer parameters.

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INITIAL LISTING

AUTOFLOW CHART SET - FWE/SCL RADSIM

FOR THIS ACTUAL

VERSION

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120	*				122
121	*	(EQUIVALENCE (ITEMP(401), PW))	1,(ITEMP(401), FSTRT)	1,	123
122	*	(ITEMP(421), CHKP)	1,(ITEMP(421), FMBW)	1,	124
123	*	(ITEMP(441), NWRTX)	1,(ITEMP(441), SWW)	1,	125
124	*	(ITEMP(461), NSURP)	1,(ITEMP(461), SW2M)	1,	126
125	*	(ITEMP(481), KISTIM)	1,(ITEMP(481), FALTIM)	1,	127
126	*	(ITEMP(100), TSTART)	1,(ITEMP(100), PCLOC1)	1,	300
127	*	(ITEMP(201), WTX(1,3))	1,(ITEMP(216), UPK1)		
128	*	(ITEMP(129), VPEAK)			
129	*	(ITEMP(144), ECDEF)	1 + (ITEMP(143), MODEPH),		
130	*	(ITEMP(164), NSR)	1, (ITEMP(165), APY(1))		
131	*				130
132	*	(EQUIVALENCE (ITEMP(101), NTAPS))	1,(ITEMP(101), ECDEC)	1,	131
133	*	(ITEMP(194), TAPSPC), (ITEMP(202), INFTE),			
134	*	(ITEMP(201), ITAPES,1)	1,(ITEMP(201), ITAPES,1)	1,	132
135	*				133
136	*	(EQUIVALENCE (ITEMP(103), XLSB))	1,(ITEMP(103), NEEDS)	1,	134
137	*	(ITEMP(204), INDEX)	1,(ITEMP(204), ALGES)	1,	135
138	*				136

141 EQUIVALENCE (ITEMP(108), HLT) , (ITEMP(107), HLT) 1, 137 2-11
 142 * (ITEMP(109), ANUTOT) , (ITEMP(104), TCRINT) 1, 138
 143 * (ITEMP(110), RSIM) , (ITEMP(111), NSCAT) 1, 139
 144 * (ITEMP(112), TGTVEL) , (ITEMP(201), TSCAT(1,1)) 140
 145 EQUIVALENCE (ITEMP(170), NCELL)
 146 EQUIVALENCE (ITEMP(145), GAIN)
 147 EQUIVALENCE (ITEMP(160), SHTG) , (ITEMP(111), SHPHAS) 1, 142
 148 * , (ITEMP(182), TJIT) 1, 143
 149 144
 150 EQUIVALENCE (ITEMP(146), CFREQ) , (ITEMP(147), XWLLNG) 1,
 151 * (ITEMP(148), SEDENS) 1
 152 EQUIVALENCE (ITEMP(145), RADIUS) , (ITEMP(146), NSAM) 1,
 153 * (ITEMP(147), NDF2) , (ITEMP(201), FSAM(1,1))
 154 EQUIVALENCE (ITEMP(199), NSEC) , (ITEMP(201), FFCDEF(1,1)),
 155 * (ITEMP(251), FFCDEF(1,1))
 156 EQUIVALENCE (ITEMP(171), JRNU) ,
 157 * (ITEMP(172), JKSIM) , (ITEMP(173), JMAZ) 1,
 158 * (ITEMP(174), JHGT) , (ITEMP(175), JERF) 1,
 159 * (ITEMP(176), JFMBW) , (ITEMP(177), JPW) 1,
 160 * (ITEMP(178), JFO) , (ITEMP(179), JSTART) 1,
 161 * (ITEMP(156), JVEL) , (ITEMP(157), JPEROU)
 162 1
 163 NAMLLIST/NL101/ IADD1, IRND, JRND, UMLAN, UEXT, SIGMA, XMLAN, NRAND, 146
 164 * IODUMP
 165 NAMLLIST/NL102/ UMLAN, UEXT, SIGMA, XMLAN, IODUMP
 166 NAMLLIST/NL104/ NAVG
 167 NAMLLIST/NL105/ NAVG
 168 NAMLLIST/NL106/ NAVG
 169 NAMLLIST/NL108/ NAVG

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ADULT LLLW CHART SET - FNU/SCL RAISEIM

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CONTENTS

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100 NAMELIST/NL204/ NC,SIMRW,DEFIN,TIME,SLDUR,CLINFO 2-13
100 NAMELIST/NL205/ NTYPER
200 NAMELIST/NL206/ NTYPER
200 NAMELIST/NL207/ NTYPER
200 NAMELIST/NL301/ SIMBH,N2,FS,KFFU,ILDUMP,ICINV,ICFUR,SIMFU,WSCAN 176
200 * ,NREPLT,NUMFT,TIME,ANTAZO,ANTELU,AZEST,EL-ST,INPAZ,APTEL, 177
200 * ,ANTAZ,ANTELU,RNGCEL,TL,FI,LAMBDA,NPFS,FK1,IPRIP
200 NAMELIST/NL302/ NECS,NRWPB,EWPH,WNLVLL,WCLANG,RNEXT,ENO,AZEXT, 179
200 * ,AZCMM,ELAZ,ELD,NN,RNGCEL,ILDUMP
200 * ,KN,NEK5,MULC,DELAZ,DELEL,ICFLG,LCFLP,RCELL
200 NAMELIST/NL303/ ST,ENG,LF,VIL,VLK,NAUTL,TH,TL,IFULLC
200 NAMELIST/NL304/ ST,ENG,LF,VIL,NSKF,NAUTL,TH,TL,IFULLC
200 NAMELIST/NL305/ ST,ENG,LF,VIL,VLK,NAUTL,TH,TL,IFULLC
200 NAMELIST/NL306/ ST,ENG,LF,VIL,VLK,NAUTL,TH,TL,IFULLC
200 NAMELIST/NL307/ ST,ENG,LF,VIL,VLK,NAUTL,TH,TL,IFULLC,NSKP
200 NAMELIST/NL308/ ST,ENG,LF,VIL,VLK,NAUTL,TH,TL,IFULLC,NSKP
200 NAMELIST/NL310/ ST,ENG,LF,VIL,VLK,NAUTL,TH,TL,IFULLC,NSKP
200 NAMELIST/NL401/ TEN,NTEN
200 NAMELIST/NL402/ TEN,NTEN
200 NAMELIST/NL403/ FFR,FFI,FFR,FFI,IFFRN,IFFRU,IFFIN,IFFID,
200 * ,IFFRN,IFFRU,IFFIN,IFFID,NBITDF,MCUDF
200 NAMELIST/NL404/ FFR,FFI,FFR,FFI,IFFRN,IFFRU,IFFIN,IFFID,
200 * ,IFFRN,IFFRU,IFFIN,IFFID,NBITDF,MCUDF
200 NAMELIST/NL405/ FFR,FFI,FFI,FFI,FFI,FFI,IFFRN,IFFRU,IFFIN,IFFID,IFFIN, 196
200 * ,IFFID,IFFIN,IFFID,NBITDF,MCUDF
200 NAMELIST/NL406/ FFR,FFI,FFI,FFI,FFI,IFFRN,IFFRU,IFFIN,IFFID,IFFIN, 198
200 * ,IFFID,IFFIN,IFFID,NBITDF,MCUDF
200 NAMELIST/NL407/ NZ,SP,SE,F2KD,PEL

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PROBLEMS

MULTIFLOW CHART SET - FMC/SLL RAL-SIM

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- | | | |
|--|--|-----|
| | NAMELIST/NL403/ NTSAR,DX,RFFC,THTAS,NRCKS,NEPSG,IRPSG,NEPSK,
+ IRPSK,IRCKS,IODUMP,NPLS,TSKLLS | 203 |
| | NAMELIST/NL404/ PW, FMW, NPWTX, SPW, NSUEP, SWTIM, RISTIM,
+ RALTIM, TBLART, PCODE, WTX, IODUMP, SIMFO, VPEAK, CHIRP, FSTRT | 205 |
| | NAMELIST/NL411/ PW, FMW, NPWTX, SPW, NSUEP, SWTIM, RISTIM,
+ RALTIM, TBLART, PCODE, WTX, IODUMP, SIMFO, VPEAK, CHIRP, FSTRT | 207 |
| | NAMELIST/NL422/ NTAPS, DEC, HUDEC, ITAF | |
| | NAMELIST/NL433/ NTAPS, DEC, HUDEC, ITAF | |
| | NAMELIST/NL452/ DX, THETAS, NRCKS, NEPSG, IRPSG,
+ IRPSK, IRCKS, IODUMP, NPWTX, FMW, WTX, RISTIM, RALTIM,
+ TBLART, TIMESO | |
| | NAMELIST/NL460/ NTSAR,DX,THETAS,NRCKS,NEPSG,IRPSK,IRPSK,TLLINE,
+ ARLLS,TSKLLS,IODUMP,PCODE,TBLART,MOUTSK,HUDEC,TLLMON | |
| | NAMELIST/NL467/ NTSAR,DX,THETAS,NRCKS,NEPSK,IRPSK,TLLINE,
+ ARLLS,VILLUM,RELLL,THETAF,MOUTSF,HUDEC,TLLMON | |
| | NAMELIST/NL474/ FFC,FF1,FB1,FB2,IFFON,IFFOU,IFFIN,IFFIO,IFBIN,
+ IFFI,IFFI2,IFFI2D,NEITDF,MODEDF | 217 |
| | NAMELIST/NL481/ FFC,FF1,FB1,FB2,IFFON,IFFOU,IFFIN,IFFIO,IFBIN,
+ IFFI,IFFI2,IFFI2D,NEITDF,MODEDF | 219 |
| | NAMELIST/NL491/ FFC,FF1,FB1,FB2,IFFON,IFFOU,IFFIN,IFFIO,IFBIN,
+ IFFI,IFFI2,IFFI2D,NEITDF,MODEDF | 221 |
| | NAMELIST/NL493/ FFC,FF1,FB1,FB2,IFFON,IFFOU,IFFIN,IFFIO,IFBIN,
+ IFFI,IFFI2,IFFI2D,NEITDF,MODEDF | 223 |
| | NAMELIST/NL494/ FFC | |
| | NAMELIST/NL495/ FFC | |

261 NAMELIST/NL437/FLCK
262 NAMELIST/NL440/ NCELL
263 NAMELIST/NL441/ NCELL
264 NAMELIST/NL451/ FBCK,RECDEL,RECIFT,THETAK,LX,NFLWS
265 NAMELIST/NL452/ FBCK,RECDEL,RECIFT,THETAK,LX,NFLWS
266 NAMELIST/NL453/ LX,THETAS,NFLWS,NFSCG,IPFSCG,
267 * NPULS,NUPLES,TGNUM,NFWTX,FMOW,WIX,KISTIM,FALTIN,TIMLSB
268 NAMELIST/NL454/ SIMFO,SPW,NSUBF,BFR
269 NAMELIST/NL455/ LX,THETAS,NFLWS,TGNUM,SPW
270 NAMELIST/NL456/ GAIN
271 NAMELIST/NL457/ GAIN
272 NAMELIST/NL458/ GAIN
273 NAMELIST/NL459/ TAVI
274 NAMELIST/NL460/ TAVG
275 NAMELIST/NL461/ NSFC,SF,RECDEF,RECDEF
276 NAMELIST/NL462/ NSEL,SF,RECDEF,RECDEF
277 NAMELIST/NL463/ RADIUS,NSAM,NDLZ,PSAM
278 NAMELIST/NL464/ IDUMP,HTGT,HTLT,ANGTG,TOKINT,KSIM,NLCAT,
279 * TSCAT,TGTVEL
280 NAMELIST/NL465/ IDUMP,HTGT,HTLT,ANGTG,TOKINT,KSIM,NLCAT,
281 * TSCAT,TGTVEL
282 NAMELIST/NL466/ NTSAF,LX,FFU,THETAS,NFLWS,NFSCG,NBPSK, 235
283 * IPFSK,INCFM,IDDUMP,NPHLS,TSKLS
284 NAMELIST/NL467/ IDUMP,NTSAF,LX,THETAS,NFLWS,IPFSK,IPFSF,TULINE, 237
285 * AUTN,AUTP,ANLIT,TSKLS,RECDEF,THETAK,MU,TSK,RECIFT,FBCK,
286 * TLMEN
287 NAMELIST/NL468/ NSR,MODEFH,IPY,INCLUDE,CHIRP,ESTAB,SPW,NSUBP,SWTIM,
288 * TLTART,SIMFO,VPEAK,FISTIM,FALTIN
289 NAMELIST/NL469/ NSF,MODEPH,IPY,INCLUDE,CHIRP,ESTAB,SPW,NSUBF,SWTIM,

CONTINUATION	ROUTINE CALLING	AUTOFLOW CHART SET - FWD/SCC RADSIM
		2-16 ****
1000	*****	CONTENTS
1001	< JNAME,LSIM,VEAR,MISTIM,FALTIM	
1002	NAME,LIST/REGDIZ,FODEC,TAPSPL,INPTF	
1003	NAME,LIST/REGDIZ,FODEC,TAFSEC,INPTF	
1004	NAME,LIST/REGDIZ,CHFC,XWLEN	
1005	NAME,LIST/REGDIZ,SCUNS	
1006	NAME,LIST/REGDIZ,JENG,JFSIM,JMAZ,JHUT,JEFF,DEMOW,JPWS	
1007	* JPC,JOVIL,JELFON,RADLUS,NSAM,NDLZ,FSAM	
1008	NAME,NO0001,NO0041,NO0141,NO0453,NO0500/1,NO141,NO500/	234
1009	NO0142,NO0013,NO0021,NO0149/12,NO21,NO47	
1010	C	
1011	C	
1012	CALL,FANL1,(A1,500)	
1013	EXEC=1	
1014	EXEC(500)=1	
1015	EXECUR=1	
1016	AUXC=1	
1017	DTL<-1+C	
1018	XY(j)=1	
1019	C	
1020	CONF100	
1021	CONF101	
1022	CONF102	
1023	CONF103	
1024	CONF104	
1025	CONF105	
1026	CONF106	
1027	C	
1028	TELLER,SCS1,WITE(0111) EXEC	
1029	C	
1030	TELLER,SCS1,WITE(0111) EXEC	

314 1614 11,MP(1) = 0 1-17
320 JSTEP=0
321 ISIM=1
322 IFLAGG = 1
323 IFCFLG=0
324 VPLAK=1.0
325 L
326 2000 CONTINUE
327 IFI IFLAGG .EQ. 0 GO TO 2003
328 IFLAGG = 0
329 WRITE(6,2001) ISIM,ICFG
330 2001 FORMAT(1H1,'SIMULATION PASS',14,1'DATA LOAD FOR CONFIGURATION NUMBER 273
331 *H',14,1' IS BEGINNING')
332 2003 CONTINUE
333 FSHIFT=0.0
334 IFL=0
335 1000UMP=0
336 INPTF=0
337 READ(5,6) ICARD,III,MODULE
338 6 FORMAT(A6 , 3X, 13, 3X, 13)
339 WRITE(6,16) ICARD,III,MODULE
340 16 FORMAT(///,1H ,A0 , 10X,1A,10X,13)
341 L
342 IFI ICARD .EQ. NCLDEX 1 GO TO 1600
343 IFI ICARD .EQ. EXEC 1 GO TO 1605
344 IFI ICARD .EQ. LDEEXEC 1 GO TO 1610
345 IFI ICARD .EQ. ENDPAS 1 GO TO 1500
346 IFI ICARD .EQ. ENDJOB 1 GO TO 1600
347 IFI ICARD .EQ. ENDCFG 1 GO TO 1700

Card 1

Index Card 1

AUTOFLOW CHART SET - FNU/SCC RAUSIM

Card 2

CONTENTS

2-18

290 INT ICARD GEN. MODIFY F GO TO 1710
295 INT ICARD GEN. SKEP F GO TO 1710
300 DATAFORMAT
304
308 INT ICARD GEN. STOREX F GO TO 1610
312 INT ICARD GEN. STEREX F GO TO 1620
316 INT ICARD GEN. LIGERA F GO TO 1625
320 INT ICARD GEN. STPER F GO TO 1630
324 INT ICARD GEN. LOADX F GO TO 1635
328 INT ICARD GEN. LEALY F GO TO 1640
332 INT ICARD GEN. LEADA F GO TO 1645
336 INT ICARD GEN. LEAPP F GO TO 1650
340 INT ICARD GEN. FLWIND F GO TO 1655
344 INT ICARD GEN. LUTIX F GO TO 1660
348 INT ICARD GEN. LUTTY F GO TO 1665
352 INT ICARD GEN. LUTTA F GO TO 1670
356 INT ICARD GEN. QUITF F GO TO 1675
360 INT ICARD GEN. INITX F GO TO 1680
364 INT ICARD GEN. INITUY F GO TO 1685
368 INT ICARD GEN. INITUA F GO TO 1690
372 INT ICARD GEN. INPUTI F GO TO 1695
376 INT ICARD GEN. INPUTU F GO TO 1700
380 INT ICARD GEN. CLEARX F GO TO 1710
384 INT ICARD GEN. CLEARY F GO TO 1715
388 INT ICARD GEN. CLEARA F GO TO 1740
392 INT ICARD GEN. CLEARR F GO TO 1745
396 DATAFORMAT
400 WHILE (true)
404
408 INT ICARD GEN. INCREFCT ALPHA INHIB. CARD IGNORED. FZ)

316

END OF LOG

2-19

377 C
378 31 CLNTINUE
379 IF(INDEX.EQ.+1).OR.INDEX.EQ.426.EK.INDEX.EQ.504) GU TD 32
380 IF(INDEX.EQ.505) GU TD 32
381 GU TD 34
382 32 GU 33 J=1,100
383 33 TSKLCS(J)=1.0
384 34 CLNTINUL
385 IF(INDEX.LT.300.OR.INDEX.GT.320) GU TU 35
386 GU 36 J=1+16
387 ITEMPI(200+J)=BLANK
388 ITEMPI(300+J)=BLANK
389 ITEMPI(400+J)=BLANK
390 36 CLNTINUE
391 37 CLNTINUE
392 C
393 IF(INDEX.LE.100.OR.INDEX.GE.600) GU TD 2040
394 IF(INDEX.GT.100.AND.INDEX.LT.200) GL TD 100
395 IF(INDEX.GT.200.AND.INDEX.LT.300) GU TD 200
396 IF(INDEX.GT.300.AND.INDEX.LT.400) GL TD 300
397 IF(INDEX.GT.400.AND.INDEX.LT.500) GU TD 400
398 IF(INDEX.GT.500.AND.INDEX.LT.600) GL TD 500
399 C
400 C
401 100 INDEX=INDEX-100
402 CL TL(101,102,103,104,105,106,107,108,109,110,111,112,113,114, 330
403 * 115,116,117,118,119,120).INDEX
404 200 INDEX=INDEX-200
405 GU TU(201,202,203,204,205,206,207,208,209,210,211,212,213,214, 333

000012.00 10001 CONTINUE AUTOFLOW CHART SET - FWU/SCL RADSIM
 **** CONTENTS **** 2-20
 00001 *****
 00002 * 115,210,217,218,219,220,221,222,223,224,225,226,227,228,229, 334
 00003 * 200,231,232,233,234,235,236,237,238,239,240,241,242,243), INDEX 335
 00004 300 INDEX=INDEX-300
 00005 GL TL 1001,1002,103,304,305,306,307,308,309,310,311,312,313), INDEX 337
 00006 * 100 INDEX=INDEX-400
 00007 GL TL 401,402,403,404,405,406,407,408,409,410,411,412,413,414, 339
 00008 * 415,416,417,418,419,420,421,422,423,424,425,426,427,428,429, 340
 00009 * 420,431,432,434,435,436,437,438,439,440,441,442,443,444, 341
 00010 * 445,446,447,448,449,450,451,452,453,454,455,456,457,458,459,
 00011 * 460,461,462,463,464,465,466,467,468,469,470), INDEX
 00012 GL INDEX=INDEX-500
 00013 GL TL 501,502,503,504,505,506,507,508,509,510,511,512,513,
 00014 * 514,515), INDEX
 00015 C
 00016 * 11 FLOW(S,NL101)
 00017 IF(JADUL,LL,LL,ANU,JADU1,GE,1) GL TL 1101
 00018 JADU1=1
 00019 NL101 CONTINUE
 00020 CALL SLEUKX(N00001,N00013,N00124,XRNDM)
 00021 NL101 CONTINUE
 00022 SLEUKX=-1.0*SIGMA*SIGMA
 00023 UL=UMEAN-0.5*ULEXT
 00024 XLEXT=UL*1.3+4.54736*E10
 00025 IF(JKNU,LL,LL,JKNU1,JENU1)
 00026 CALL SLEUKX(N00021,N00001,N00012,ITEMP,XRNDM)
 00027 WRITE(0,NL101)
 00028 GL TU 1000
 00029 C
 00030 * 11 FLOW(S,NL101)

- 1) $\boxed{a = b} \quad \overline{Fa}$ produces $\boxed{a = b} \quad \boxed{Fa} \quad \boxed{Fb}$
- 2) $\boxed{Fa} \quad (a = b)$ produces $\boxed{Fa} \quad \boxed{a = b} \quad \boxed{Fb}$

Though reduction is defined as a post processing operation, it is, in reality, more of a resolution operation and, therefore, should be executed within the resolution procedure or prior to other post processing operations.

(6) Ordering

Literals to the right of the right-most framed literal are free to be reordered. Reordering may not occur across framed literals without special care.

2.4 FACT DETERMINATION

OL-deduction, as has been stated, is a refutation procedure. A questionable assertion, that is, a query, is presented in negated form to the OL-deduction mechanism. Deductions are then generated and are sought to be refuted. A refutable deduction implies the existence of a collection of rules and facts (possibly a null collection) that refutes the negated query, and consequently, satisfies the assertion of the query. It is the collection of facts that is the answer to the positive query and that is provided by the inference system.

A resolved deduction is a clause consisting of only resolution literals; that is, it is a deduction clause that has been fully resolved.

Each resolution (framed) literal in a resolved deduction clause is a literal about which the information system can supply facts or is an acceptable inferred literal. An inferred literal will often be a simple binary proposition, signifying a yes or no; true or false; 0 or 1 value. In the more general case, where the framed literal is a complex predicate, the literal will tend to be a fact literal for which the information system will supply all facts. For example, given $\boxed{L(X,5)}$ where $L(X,5)$ means "X" is a worker in factory "5", then the information system will search out all workers in factory number 5 and supply these as facts satisfying the literal. We call this procedure "fact determination". When fact determination is applied to all of the fact literals of a completely resolved deduction, we then determine a largest subset of these facts that can satisfy the deduction as an entirety.

06/21/75

INPUT LISTING

AUTOFLOW CHART SET ~ FWL/SCL RADSIM

CARD NO.

CONTENTS

2-22 ****

404 READ(5,NL208)
405 WRITE(6,NL208)
406 GL TU 1206
407 204 READ(5,NL204)
408 WRITE(6,NL204)
409 1206 IF(NHIST .LE. 6000) GO TO 1000
410 WRITE(6,1210)
411 1210 FORMAT(* THE SPECIFIED NUMBER OF POINTS IN HISTOGRAM EXCEEDS
* 8000 NHIST SET TO 8000 *)
412 NHIST = 8000
413 GL TU 1000
414 C
415 C
416 210 CONTINUE
417 READ(5,NL210)
418 WRITE(6,NL210)
419 GL TU 1000
420 211 READ(5,NL211)
421 WRITE(6,NL211)
422 GL TU 1000
423 212 CONTINUE
424 READ(5,NL212)
425 WRITE(6,NL212)
426 GL TU 1000
427 213 READ(5,NL213)
428 WRITE(6,NL213)
429 GL TU 1000
430 C
431 214 READ(5,NL214)

670 WRITE(UNIT=14)
674 DD 1D 1000
678 READ(BUF1)
680 WRITE(UNIT=14)
684 DD 1D 1000
688 READ(BUF1)
690 WRITE(UNIT=14)
694 DD 1D 1000
700 READ(BUF1)
704 WRITE(UNIT=14)
708 DD 1D 1000
712 READ(BUF1)
716 WRITE(6,NL217)
720 IF(AUCFS.EQ.0.0) GOTO 5217
724 N=1FIX(FS/AUCFS+0.49)
728 KRSF=AUCFS-(FS/FLOAT(N))/FS
732 IF(KRSF.LT.-0.04) GOTO 1000
736 AUCFS=FS/FLOAT(N)
740 WRITE(6,NL217) AUCFS
744 READ(FMT1) THE SPECIFIED VALUE OF (FS/AUCFS + NUT),
748 * AN INTEGER ...AUCFS SET EQUAL TO 1, ELSE
752 GOTO 1000
756 AUCFS=FS
760 DD 1D 1000
764 READ(BUF1)
768 WRITE(UNIT=14)
772 DD 1D 1000
776 READ(BUF1)
780 WRITE(6,NL214)
784 DD 1D 1000
788 READ(5,NL220)

2-23

06/11/76

INPUT LISTING

AUTOFLOW CHART SET - FWD/SOL RADSIM

2-24

CARD NO.

CONTENTS

200 WRITE(6,NL220)
201 CC TO 1000
202 L22 READ(5,NL221)
203 WRITE(6,NL222)
204 CC TO 1000
205 L22 READ(5,NL223)
206 WRITE(6,NL224)
207 CC TO 1000
208 L23 READ(5,NL225)
209 WRITE(6,NL226)
210 CC TO 1000
211 L24 READ(5,NL227)
212 WRITE(6,NL228)
213 CC TO 1000
214 L25 READ(5,NL229)
215 WRITE(6,NL230)
216 CC TO 1000
217 L26 READ(5,NL231)
218 WRITE(6,NL232)
219 CC TO 1000
220 L27 READ(5,NL233)
221 WRITE(6,NL234)
222 CC TO 1000
223 L28 READ(5,NL235)
224 WRITE(6,NL236)
225 CC TO 1000
226 L29 READ(5,NL237)
227 WRITE(6,NL238)
228 CC TO 1000
229 L30 READ(5,NL239)
230 WRITE(6,NL240)
231 CC TO 1000

```

551      READ(5,NL231)
552      WRITE(6,NL231)
553      GO TO 1000
554      READ(5,NL232)
555      WRITE(6,NL232)
556      GO TO 1000
557      READ(5,NL233)
558      WRITE(6,NL233)
559      GO TO 1000
560      READ(5,NL234)
561      WRITE(6,NL234)
562      GO TO 1000
563      READ(5,NL235)
564      WRITE(6,NL235)
565      GO TO 1000
566      READ(5,NL236)
567      WRITE(6,NL236)
568      GO TO 1000
569      READ(5,NL237)
570      WRITE(6,NL237)
571      GO TO 1000
572      GO
573      SET CONTINUE
574      IF(UK=1
575      IFINV=1
576      READ(5,NL238)
577      IF(FS>0.0) T1=1.0/FS
578      IF(T1>0.0 AND FS>0.0) FS=1.0/T1
579      IF(KFFU>0.0) LAMBDA= 0.2997438/KFFU

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2-25

08/22/76

INPUT LISTING

AUTOCORR CHART SET - FWL/SCL - RADSIM

CARD NO.

CONTENTS

2-26

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500      IF(F1.LL=0.0) F1=FS/FLLAT(24*NZ)
501      IF(SIMBWF.LL=0.0) SIMBW.GT.FST SIMBWF=0
502      L001  IF(KNOL.LL=0.0 AND SIMBW.NF.LL=0.0) KNOLLE=1.0/SIMBW
503      IF(NBULL.LL=1.0) KNOLLE=1.0
504      AZANG=ANTAZ0+WSCAN*TIME
505      CLANG=ANGLE
506      IF(F1.LL=0.0) GO TO 2701
507      NF=IFIX(S*MBW/F1)
508      IF(NF+LL<142) GO TO 2301
509      WRITE(6+3501)
510      0011 FORMAT(* THE REQUIRED NUMBER OF FREE-DEMAIN SAMPLES EXCEEDS*
511      * 142.....THIS JOB WILL BE TERMINATED*)
512      GO TO 1797
513      2201 WRITE(6+NLOC0)
514      GLTU 1000
515      5501 WRITE(6+11) NREPET
516      IFC=FLD(6,6,1*XEC(1))
517      READ(11*IFC) ITEMP
518      6001 ILEFT=ILEFT+1
519      IF(ILEFT.GT.NREPET) GOTO 1501
520      ILLUCK=1+LUCK+1
521      IFC=10LUCK
522      IPRIPT=IPRIPT+1
523      IF(IPRIPT.GT.NPRI) IPRIPT=1
524      TIME=TIME+PR1(IFPIPT)
525      AZANG=ANTAZ0+WSCAN*TIME
526      WRITE(11*IFC) ITEMP
527      FLU(6,6,1*XEC(1))=IFC
528      GOTO 1500

```

009 II FORMAT(* THIS CONFIGURATION WILL BE REPLATED*,13,
010 * *TIMES*)
011 D02 READ(5,NL302)
012 IF(KNUCEL.LT.11) KNGCEL=11
013 CALL CLINT(\$1302)
014 WHITE(6,NL302)
015 OC TO 1000
016 D03 READ(5,NL303)
017 WHITE(6,NL303)
018 OC TO 1000
019 D04 READ(5,NL304)
020 WHITE(6,NL304)
021 OC TO 1000
022 D05 READ(5,NL305)
023 WHITE(6,NL305)
024 OC TO 1000
025 D06 READ(5,NL306)
026 WHITE(6,NL306)
027 OC TO 2000
028 D07 READ(5,NL307)
029 WHITE(6,NL307)
030 OC TO 1000
031 D08 READ(5,NL308)
032 WHITE(6,NL308)
033 OC TO 1000
034 D09 READ(5,NL309)
035 WHITE(6,NL309)
036 OC TO 1000
037 OC READE(5,NL310)

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INPUT LISTING

AUTOFLOW CHART SET - FWL/SCC RAUSTM

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CONTENTS

CARD NO.

638 WRITE(6,NL310)
639 GO TO 1000
640 C
641 READ(5,NL401)
642 WRITE(6,NL401)
643 GO TO 1000
644 READ(5,NL402)
645 WRITE(6,NL402)
646 GO TO 1000
647 C
648 READ(5,NL403)
649 WRITE(6,NL403)
650 GO TO 1000
651 READ(5,NL404)
652 WRITE(6,NL404)
653 GO TO 1000
654 READ(5,NL405)
655 WRITE(6,NL405)
656 GO TO 1000
657 READ(5,NL406)
658 WRITE(6,NL406)
659 GO TO 1000
660 C
661 READ(5,NL407)
662 WRITE(6,NL407)
663 GO TO 1000
664 READ(5,NL408)
665 WRITE(6,NL408)
666 GO TO 1000

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667 409 READ(5,NL409)
668 WRITE(6,NL409)
669 GO TO 1000
670 410 READ(5,NL410)
671 WRITE(6,NL410)
672 GO TO 1000
673 413 READ(5,NL413)
674 WRITE(6,NL413)
675 GO TO 1000
676 C
677 420 READ(5,NL420)
678 WRITE(6,NL420)
679 IF(K1STIM.LT.71) K1STIM=71
680 IF(FALTIM.LT.71) FALTIM=71
681 IF(SWTIM.LT.71) SWTIM=71
682 GO TO 1000
683 421 READ(5,NL421)
684 WRITE(6,NL421)
685 GO TO 1420
686 C
687 422 READ(5,NL422)
688 WRITE(6,NL422)
689 GO TO 1000
690 423 READ(5,NL423)
691 WRITE(6,NL423)
692 GO TO 1000
693 C
694 425 READ(5,NL425)
695 WRITE(6,NL425)

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ABOUT EDITING

AUTOFLOW CHART SET - FWL/SCL RADSIM

LITERATURE

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725 GO TO 1000
726 434 READ(5,NL434)
727 WRITE(6,NL434)
728 GO TO 1000
729 435 READ(5,NL435)
730 WRITE(6,NL435)
731 GO TO 1000
732 436 READ(5,NL436)
733 WRITE(6,NL436)
734 GO TO 1000
735 437 READ(5,NL437)
736 WRITE(6,NL437)
737 GO TO 1000
738 440 READ(5,NL440)
739 WRITE(6,NL440)
740 GO TO 1000
741 441 READ(5,NL441)
742 WRITE(6,NL441)
743 GO TO 1000
744 442 READ(5,NL442)
745 WRITE(6,NL442)
746 GO TO 1000
747 443 READ(5,NL443)
748 WRITE(6,NL443)
749 GO TO 1000
750 444 READ(5,NL444)

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Export and Import

ANNUAL CHART SET - FWL/SCC RADSIM

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CONTENTS

160 WRITE(6,NL460)

165 OCTO 1000

170 C

175 SUB READ(5,NL501)

180 WRITE(6,NL501)

185 GO TO 1000

190 SUB READ(5,NL502)

195 WRITE(6,NL502)

200 GO TO 1000

205 SUB CONTINUE

210 READ(5,NL504)

215 WRITE(6,NL504)

220 GO TO 1000

225 SUB READ(5,NL505)

230 WRITE(6,NL505)

235 IF(NF.GT.4000) GOTO 2426

240 GO TO 1000

245 C

250 SUB READ(5,NL506)

255 WRITE(6,NL506)

260 CALL PHENC(\$1500)

265 MODULE=420

270 OCTO 1420

275 SUB READ(5,NL507)

280 WRITE(6,NL507)

285 CALL PHENC(\$1500)

290 MODULE=421

295 OCTO 1420

300 SUB FODEC=\$IMFO

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INVESTIGATION

AUTOFLOW CHART SET - FNU/SCL RADSIM

CONTINUOUS

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201 204 CONTINUE
202 205 CONTINUE
203 206 CONTINUE
204 207 CONTINUE
205 220 CONTINUE
206 232 CONTINUE
207 0
208 312 CONTINUE
209 313 CONTINUE
210 0
301 414 CONTINUE
302 415 CONTINUE
303 416 CONTINUE
304 417 CONTINUE
305 418 CONTINUE
306 419 CONTINUE
307 430 CONTINUE
308 439 CONTINUE
309 442 CONTINUE
310 443 CONTINUE
311 445 CONTINUE
312 446 CONTINUE
313 447 CONTINUE
314 448 CONTINUE
315 449 CONTINUE
316 450 CONTINUE
317 451 CONTINUE
318 0
319 502 CONTINUE
320 0

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FOLIOLATE PHYLLOPS

ENTITLED CHART 1 - PHYSICAL RADSIM

LAWRENCE

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CONTENTS

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444 D49 CUNTINUE 2-37
 460 S14 CUNTINUE
 461 S15 CUNTINUE
 462 2040 WRITE(6,51) JSTEP,MODULE
 463 S1 FORMAT(* THE MODULE NUMBER FOR THE *,15,0TH STEP IS INVALID...THE 644
 * MODULE NUMBER IS *,I4)
 465 JSTEP=JSTEP-1 7042
 466 IBLUCK=IBLUCK-1 7043
 467 GO TO 2000
 468 L ** LOAD DATA BLOCK AND EXEC WORD **
 469 1000 WRITE(11*IFC) ITEMP
 470 1001 ITEXEC= MODULE
 471 ITEXEL= IPACK(12,ICW,ITEXEC)
 472 ITEXEL= IPACK(24,IFC,ITEXEC)
 473 ITEXEL(JSTEP)= IPACK(30,ICFG,ITEXEL)
 474 GO TO 2000
 475 L ** ENDPAS **
 476 1500 IBLUCK=IBLUCK+1
 477 ITEXEL(500)=IBLUCK
 478 WRITE(11*IEXEC) IEXEC
 479 WRITE(6,61) ITEXEL,IBLUCK
 480 61 FORMAT(* ITEXEL = *,110,* IBLUCK = *,110)
 481 ITEXEL=IBLUCK
 482 ISIM=ISIM+1 730
 483 IF(IKPT.EQ.0) GOTO 1501
 484 IF(IKPT.EQ.1) GOTO 5301
 485 GOTO 0501
 486 1501 IFLAGG=1
 487 LL TO 2000

DATE/1975	INPUT LISTING	AUTOFLOW CHART SET - FWU/SCL RADSIM
CARD NO.	****	CONTENTS
420	1550 WRITE(6,1550)	
421	1550 FORMAT * MORE THAN 250 JBL STEPS PER SIMULATION PASS ATTEMPTED...734	
422	* THE SIMULATION ACTIVITY IS DELETED*	
423	GO TO 1530	
424	L	
425	1505 INDEX = MODULE	
426	1506 IOW=1	
427	1507 IFLLOCK	
428	IF(IFCFLG.EQ.1) IFC=IFEXEC-1	
429	JSTEP = JSTEP+1	
430	IF(JSTEP.GT.250) GO TO 1530	
431	GO TO 1506	
432	L	
433	1506 IOW=1	
434	GO TO 1511	
435	1510 IOW=2	
436	IFCFLG=1	
437	IFLOCK = IFLOCK+1	
438	IF(IFLOCK.GT.400) GO TO 1544	
439	1512 INDEX = MODULE	
440	JSTEP=JSTEP+1	
441	IF(JSTEP.GT.250) GO TO 1530	
442	IFC=IFLOCK	
443	WRITE(6,2022) INDEX	752
444	1512 FORMAT(1H0) * THE NEXT CLOCK OF DATA TO BE LEADED IS FLR MODULE NUM754	
445	IFCFLG.EQ.14 // 1	755
446	GO TO 31	756
447	L	
448	1507 IFLLOCK	758

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457 $ICW=4$
458 $GD\ TD\ 1001$
459 $1620\ CONTINUE$
460 $ICW=5$
461 $GD\ TC\ 1001$
462 $1625\ CONTINUE$
463 $ICW=6$
464 $GD\ TC\ 1001$
465 $1630\ CONTINUE$
466 $ICW=7$
467 $GD\ TC\ 1001$
468 $1635\ CONTINUE$
469 $ICW=8$
470 $GD\ TD\ 1001$
471 $1640\ CONTINUE$
472 $ICW=9$
473 $GD\ TC\ 1001$
474 $1645\ CONTINUE$
475 $ICW=10$
476 $GD\ TD\ 1001$
477 $1650\ CONTINUE$
478 $ICW=11$
479 $GD\ TC\ 1001$
480 $1655\ CONTINUE$
481 $ICW=12$
482 $GD\ TD\ 1001$
483 $1660\ CONTINUE$
484 $ICW=13$
485 $GD\ TC\ 1001$

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INPUT LISTING

AUTOFLOW CHART SET - FNU/SCL RAUSIM

DATA NO.	*****	CONTENTS	2-40 *****
900	1005 CONTINUE		
907	ICW=13		
908	UL TL 1001		
909	1070 CONTINUE		
940	ICW=14		
941	UL TL 1001		
942	1075 CONTINUE		
943	ICW=15		
944	UL TL 1001		
950	1006 CONTINUE		
946	ICW=16		
947	UL TL 1001		
948	1045 CONTINUE		
949	ICW=17		
1000	UL TL 1001		
1001	1076 CONTINUE		
1002	ICW=18		
1003	UL TL 1001		
1004	1045 CONTINUE		
1005	ICW=19		
1006	UL TL 1001		
1007	1070 CONTINUE		
1008	ICW=20		
1009	UL TL 1001		
1010	1075 CONTINUE		
1011	ICW=21		
1012	UL TL 1001		
1013	1070 CONTINUE		
1014	ICW=22		

1040 GO TO 1001
 1041 1740 CONTINUE
 1042 ICHW=25
 1043 GO TO 1001
 1044 C ** ENDCFG **
 1045 1700 CONTINUE 822
 1046 ISIM=ISIM-1 823
 1047 WRITE(6,1701) ICFG,ISIM 824
 1048 1701 FORMAT(1H0,'THE DATA LOAD FOR CONFIGURATION NUMBER',I3,', HAS BEEN 827
 1049 *COMPLETED.....',I3,', SIMULATION PASSES WERE LEAGEND') 828
 1050 ICFG=ICFG+1
 1051 GO TO 5 830
 1052 C ** MODIFY **
 1053 1710 CONTINUE 832
 1054 JSTEP = 111 833
 1055 INDEX=MODULE 834
 1056 ICHW=FLD((12,14),JEXEC(JSTEP))
 1057 IFC=FLD((c,c),JEXEC(JSTEP))
 1058 IF(LICARD,EQ,SKIP) WRITE(6,1751) JSTEP
 1059 1751 FORMAT(' STEP NUMBER',I3,', WILL BE BYPASSED FOR REMAINDER',
 1060 * * OF THIS CONFIGURATION')
 1061 IF(LICARD,EQ,MODIFY) WRITE(6,1712) ICHM,IFC ,JSTEP,MODULE
 1062 1712 FORMAT(1H , 'MOD FOR PASS NUMBER',I3,', DATA BLOCK',I3,', FOR J
 1063 *LB STEP',I4,', CALLING MODULE',I4,', IS TO BE MODIFIED') 838
 1064 C 839
 1065 IF(JFL .NE. 0) GO TO 1720 840
 1066 WRITE(6,1714) 841
 1067 1714 FORMAT(1H , 'BLOCK = 0 MODIFICATION NOT PERFORMED.') 842
 1068 GO TO 2000

CARD NUMBER	DATA LISTING	AUTOFLOW CHART SET - FNU/SCL KADSIM
CARD NO.	*****	CONTENTS
1044	1720 READ (11*IFC) ITEMP	
1045	IBLOCK=IBLOCK+1	
1046	IFC=IBLOCK	
1047	IF (ICARD.EQ.MODIFY) GOTO 35	
1048	MODULE=0	
1049	GOTO 1001	
1050	C	851
1052	1502 WRITE(6,2502) ICFG	852
1052	1502 FORMAT(* NON-STANDARD RETURN FROM CLINT.....THE CONFIGURATIONS PRE	853
1053	*CEEDING*,15,* WILL BE EXECUTED*)	854
1054	GO TO 1757	855
1055	1506 WRITE(6,2506)	856
1056	2506 FORMAT(* NON-STANDARD RETURN FROM PHEN...PRECEEDING	8520
1057	* CONFIGURATIONS WILL BE EXECUTED*)	8521
1058	GO TO 1757	
1059	1749 WRITE(6,1749) ICFG	854
1060	1792 FORMAT * THE NUMBER OF DATA BLOCKS TO BE LOADED EXCEEDS STORAGE A860	860
1061	*AVAILABLE....THE CONFIGURATIONS PRECEEDING*,15,* WILL BE EXECUTED*661	
1062	*)	662
1063	1749 CONTINUE	
1064	1500 CONTINUE	
1065	IFC=IFC-1	
1066	WHITE(6,1661) ICFG	866
1067	1601 ELEMENT(*,THE DATA LOAD FOR*,15,* CONFIGURATIONS HAS BEEN COMPLE	867
1068	*TED.....SIMULATION ACTIVITY FOLLOWS*)	868
1069	1510 EXEC(1)-0	
1070	WHITE (11*IbLEXEC) EXEC	
1071	C	673
1072	CALL EXIT	674
1073	C	875
1074	STOP	876
1075	END	

S E C T I O N 3

S I M U L A T I O N C O N T R O L L E R (M A I N - 2)

The simulation controller serves as the switchboard which connects the simulation modules together in the manner prescribed by the control cards read by the simulation data loader. Figure 3-1 is a block diagram of the Simulation Load Module. The control word blocks and System/Module Parameter Tables are stored in DSRN #11 which was initialized during the simulation data loader activity. The clutter scatterer parameters are stored in DSRN #2 which was initialized during the simulation data loader activity. In addition, provisions are available for reading and writing data on user defined disc and magnetic tape data sets.

There are two storage arrays allocated for storing simulated signal data. These arrays are designated as XT and YT. In addition, two auxiliary arrays are allocated for storing either signal data, processed data such as probability distributions, or other miscellaneous data. These arrays are designated as XA and XB. All four arrays are composed of 8192 elements.

The following is a description of the sequence of events that occur in performing a step of the simulation.

1. The operation to be performed in the Jth step is defined by the control word stored in location J of the control word block. This word is compared with the control word dictionary to determine (1) the operation to be performed, (2) the reference number of the module to be executed, and (3) the Data Set Reference Number.
2. If the operation to be performed is the execution of a module with no input data requirements, then control is transferred to the designated module. If the operation to be performed is execution of a module requiring input data, then the System/Module Parameter table is loaded from DSRN #11 and control is transferred to the designated module. For operations involving data transfers the contents of the designated array are either loaded from or transferred to the DSRN which was specified.

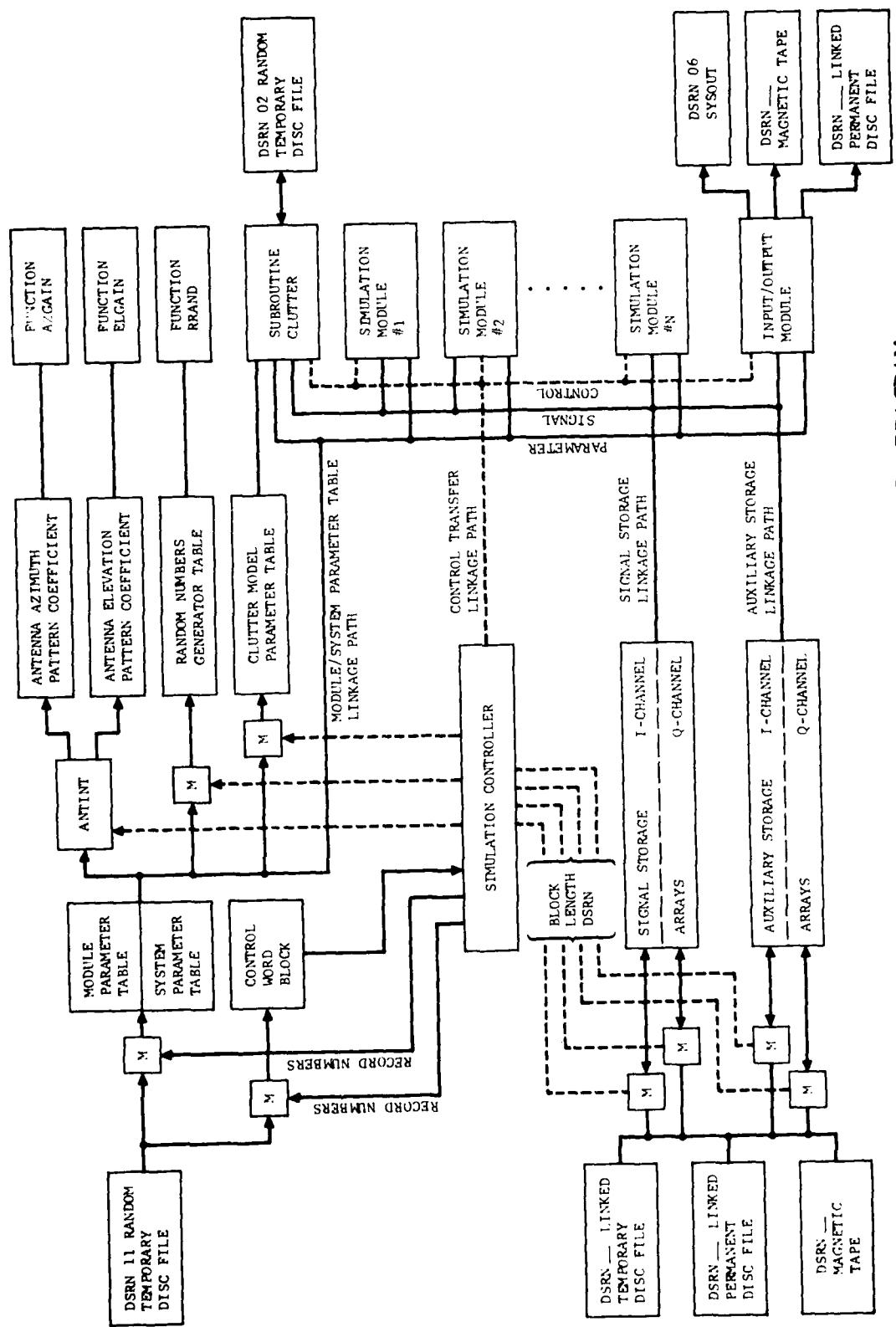


Figure 3-1 SIMULATION LOAD MODULE FUNCTIONAL BLOCK DIAGRAM

3. Once the operation for the Jth step is completed the job step counter is incremented by 1 and the process is repeated.

When a blank (all zeros) control word is encountered, the simulation pass is ended. The job step counter is reset to 1 and a new pass through the simulation is begun with a different set of parameters. A block of data containing all zeros is used to designate the end of a simulation configuration. When this is encountered the simulation controller will move the next block of data into the control word buffer. This new block of control words defines a new simulation configuration. When a new control word block containing all zeros is encountered, the simulation job is terminated.

Flow Chart: Page 9-34

Cross Reference Table: Page 9-210

1076 C * MAIN 2 *
 3-4
 1077 COMMON IT,TOKIG,DELT,TDUM,XT(8193),ITY,TOKIGY,DELTG,TDUMY,
 * YI(8193),IXA,XA(R16,XADEL,XADUM,XA(8193),IEXEC(500)
 1078 COMMON/BLK1/I DATA(500)
 1079 COMMON/BLK330/ICLCUN(30)
 1080 COMMON/AZPAT/ CLEFAZ(304)
 1081 COMMON/ELPAT/ CLEFEL(304)
 1082 COMMON/ELUUU/ IXB,XEGRIG,XDEL,XBDUM,XB(8193)
 1083 COMMON/BLKEND/ RNDAT(141) 80
 1084 COMMON/SYS/ MODULE,ICW,INC
 1085 C
 1086 DIMENSION XTT(516),YTT(516),XAT(516),XBT(516) 100
 1087 C
 1088 DIMENSION XD1(-610),X02(4010),Xc1(4010),Xc2(4010)
 1089 DIMENSION IXI(6192),IYT(8192)
 1090 DIMENSION ANTAE(150),ANTEL(150)
 1091 DIMENSION XTM(4010),YTM(4010)
 1092 C
 1093 DATA AXI/* XI */, AYI/* YT */, AXA/* XA */, AXB/* XB */ 180
 1094 DATA N193, N194, N195, N196/-3,-2,-1,0/
 1095 C
 1096 CHARACTER LARE*10
 1097 EQUIVALENCE (IBEXLG, IEXEC(500))
 1098 EQUIVALENCE (I DATA(516)*LARE)
 1099 EQUIVALENCE (XT(1),IXI(1)),(YT(1),IYT(1))
 1100 EQUIVALENCE (XTT(1), IT), (YTT(1), ITY)

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INPUT LISTING

AUTOFLOW CHART SET - FWD/SCL RADSIM

LARD NO.	*****	CONTENTS	3-5 888
1102	*	(XAT(1), IXA), (XBT(1), IBD)	
1103		EQUIVALENCE (XD1(1),XA(1)), (XD2(1),XA(4011))	
1104		EQUIVALENCE (XB1(1),XB(1)), (XB2(1),XB(4011))	
1105		EQUIVALENCE (XT1(1),XT(4011)), (YT1(1),YT(4011))	
1106		EQUIVALENCE (IDATA(150), ALBST), (IDATA(151), NHTAZ),	
1107	*	(IDATA(152), ELEST), (IDATA(153), NHTEL),	
1108	*	(IDATA(201), ANTAZ(1)), (IDATA(351), ANTEL(1))	
1109		EQUIVALENCE (IDATA(160), MOLDF)	
1110		EQUIVALENCE (IDATA(1), N2), (IDATA(2), FS)	
1111	*	(IDATA(3), KFFU), (IDATA(4), SIMEW)	
1112	*	(IDATA(5), ISDUMP), (IDATA(6), ICINV)	
1113	*	(IDATA(7), ICFLR), (IDATA(8), SIMFU)	
1114	*	(IDATA(9), NCRMFT), (IDATA(10), WSCAN)	
1115	*	(IDATA(11), F1), (IDATA(12), TI)	
1116	*	(IDATA(13), LAMEUA), (IDATA(14), KNGLL)	
1117	*	(IDATA(15), PRF), (IDATA(16), TIME)	
1118	*	(IDATA(17), ALANG), (IDATA(18), ANTAZ),	
1119	*	(IDATA(19), ELANG), (IDATA(20), ANTEL)	
1120	C		
1121		DATA NU0000,NU0001,NU0012,NU0021,NU0013,NU0124,NU0201	
1122		* /0,1,12,2,1,13,129,201*	
1123	C		
1124		CALL RADSLZ(11,500)	
1125		IF EXEC=1	
1126		ICLUN(20)=0	
1127		CALL FAFFF(00,101,0)	480
1128		ISDUMP=1	
1129	C00	SCAL(11)*10EXEC IF EXEC	
1130		WRITE(0,240) 10EXEC	

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INPUT LISTING

AUTOFLOW CHART SET - FWD/SCL RADSIM

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CARD NO.	INPUT	CONTENTS

1161	LL TL (551,452,453,454,455,456,457,458,459,460,461,462,463,464, * 465,466,467,468,469,470,471,472,473),ICW	
1162	551 CONTINUE	
1163	464 TIME=TIME	
1164	AZANG=AZANG	
1165	CLANG=ELANG	
1166	READ(11*IFC) IDATA	
1167	IF(MODULE=LU,501) GOTO 986	
1168	TIME=TIME0	
1169	ALANG=AZANG	
1170	ELANG=ELANG	
1171	566 CONTINUE	
1172	WRITE(6,2041)	
1173	2042 FORMAT(1H1)	
1174	WRITE(6,2042) MODULE,ICW,IFC,ICFG	
1175	2042 FORMAT(* MODULE=*,I10,* ICW=*,I10,* IFC=*,I10,* ICFG=*,I10)	
1176	IF(JSDUMP,LT,2) WRITE(6,2040) (J,IDA(J), J=1,500)	
1177	2040 FORMAT(1H ,5(2X, *IDATA(*, I3, *)= *,012))	900
1178	WRITE(6,10) ITMP	
1179	10 FFORMAT* THE NEXT SCHEDULED OPERATION HAS AN EXEC NUMBER OF *,I4)	
1180	L	
1181	IF(ITEMP.LT.303.OR.ITEMP.GT.310) GOTO 998	
1182	INCLUDE(LABL,37) 2PASS,ICFG	
1183	57 FFORMAT* PASS=*,I2,* CFG=*,I2)	
1184	566 CONTINUE	
1185	IF(ITEMP .LE. 100 .OR. ITEMPI .GE. 600) GO TO 2100	
1186	IF(ITEMP.GT.100.AND.ITEMP.LT.200) GO TO 100	
1187	IF(ITEMP.GT.200.AND.ITEMP.LT.300) GO TO 200	
1188	IF(ITEMP.GT.300.AND.ITEMP.LT.400) GO TO 300	

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1149      IF(ITEMP.GT.+000.AND.ITEMP.LT.+500) GL TU 400
1150      IF(ITEMP.GT.+500.AND.ITEMP.LT.+600) GU TL 500
1151      C
1152      C
1153      100 ITTEMP=ITEMP-100
1154          GU TU(101,102,103,104,105,106,107,108,109,110,111,112,113,114,
1155          * 115,116,117,118,119,120),ITEMP
1156      200 ITTEMP=ITEMP-200
1157          GU TU(201,202,203,204,205,206,207,208,209,210,211,212,213,214,
1158          * 215,216,217,218,219,220,221,222,223,224,225,226,227,228,229,
1159          * 230,231,232,233,234,235,236,237,238,239,240,241,242,243),ITEMP
1160      300 ITTEMP=ITEMP-300
1161          GU TU(301,302,303,304,305,306,307,308,309,310,311,312,313),ITEMP
1162      400 ITTEMP=ITEMP-400
1163          GL TL (401,402,403,404,405,406,407,408,409,410,411,412,413,414,
1164          * 415,416,417,418,419,420,421,422,423,424,425,426,427,428,429,
1165          * 430,431,432,433,434,435,436,437,438,439,440,441,442,443,444,
1166          * 445,446,447,448,449,450,451,452,453,454,455,456,457,458,459,
1167          * 460,461,462,463,464,465,466,467,468,469,470),ITEMP
1168      500 ITTEMP=ITEMP-500
1169          GU TU(501,502,503,504,505,506,507,508,509,510,511,512),ITEMP
1170      C
1171      C
1172      101 CONTINUE
1173          CALL SUBLKX(N00201,N00013,N00129,1DATA,RNDDAT)           1240
1174          102 CALL SUBLKX(N00021,N00001,N00012,1DATA,RNDDAT)           1250
1175          WRITE(6,1101) (J,RNDDAT(J), J=1,141)
1176          1101 FORMAT(1H , 41 2X, 'RNDDAT(*,I3, *) = ', 0I2))
1177          GU TU 1000

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INPUT LISTING

AUTOFLOW CHART SLT - FMC/SCL RADSIM

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CARL RUE

CONTENTS

1216 103 CALL KTUPUB(XT,YT,XA,XB)
 GO TO 1000
 1219 104 CALL XYTLDE(XT,YT,XA)
 GO TO 1000
 1220 105 CALL XYTUM(XT,YT,XA)
 GO TO 1000
 1221 106 CALL XYTLM2(XT,YT,XA)
 GO TO 1000
 1222 107 CALL XYTLLB(XT,YT,XT)
 GO TO 1000
 1223 110 CALL KTUPMIXT,YT,XA,XB)
 GO TO 1000
 1224 111 CALL KTUPM2(XT,YT,XA,XF)
 GO TO 1000
 1225 113 CALL PLTHMT(XT,YT,XA,\$1070)
 GO TO 1000
 1226 L
 1227 114 CALL LBKRXIN193,8147,XT,XA)
 CALL DBRXX(N193,8147,YT,XB)
 GO TO 1000
 1228 L
 1229 115 CALL LBKRX(N193,8147,XA,XT)
 CALL DBRXX(N193,8147,XB,YT)
 GO TO 1000
 1230 L
 1231 116 CALL ERGYNK(EXT)
 GO TO 1000
 1232 117 CALL ERGYRK(YT)
 GO TO 1000

1450

1247 118 CALL ERGULP(XT,YT)
1248 GO TO 1000
1249 C
1250 201 CALL DFT(XT,YT)
1251 GO TO 1000
1252 202 CONTINUE
1253 CALL ZFFT(XT,YT)
1254 GO TO 1000
1255 203 CONTINUE
1256 CALL ZIFFT(XT,YT)
1257 GO TO 2000
1258 204 CALL CONVXT(XT,YT,XA,XB,\$1130)
1259 GO TO 1000
1260 205 CALL CONVMP(XT,YT,XA,XB,\$1130)
1261 GO TO 1000
1262 206 CALL DIVA(XT,YT,XA,XB,\$1130)
1263 GO TO 1000
1264 207 CALL ADDA(XT,XA,\$1130)
1265 GO TO 1000
1266 208 CALL CUMDIS(XT,XA)
1267 GO TO 1000
1268 209 CALL CUMDIS(YT,XA)
1269 GO TO 1000
1270 210 CALL LUTCUM(XB,XA)
1271 GO TO 1000
1272 211 CALL OUTCUM(XA,XA)
1273 GO TO 1000
1274 212 CALL PDF(XB,XA)
1275 GO TO 1000

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INPUT LISTING

AUTOFLOW CHART SET - FWD/SCL RADSIM

CARD NO.

CONTENTS

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1276 213 CALL PDE(XA,XA)
1277 GO TO 1000
1278 214 CALL RNDARY(EXT)
1279 GO TO 1000
1280 215 CALL RNDARY(YT)
1281 GO TO 1000
1282 216 CALL ATOD(EXT,XT)
1283 GO TO 1000
1284 217 CALL ADD(YT,YT)
1285 GO TO 1000
1286 218 CALL DILAT(IXT,XT)
1287 GO TO 1000
1288 219 CALL DILAT(IYT,YT)
1289 GO TO 1000
1290 220 CALL DTUA(IYT,XA)
1291 GO TO 1000
1292 221 CALL WEITFE(XI,YT,\$1010)
1293 GO TO 1000
1294 222 CALL WEITCP(EXT,YT,\$1010)
1295 GO TO 1000
1296 223 CALL WEITMP(EXT,YT,\$1010)
1297 GO TO 1000
1298 224 CALL SHIFT(EXT,YT,XT,YT)
1299 GO TO 1000
1300 225 CALL SHIFT(EXT,YT,XA,XB)
1301 GO TO 1000
1302 226 CALL SHIFTS(EXT,YT,XA,XB)
1303 GO TO 1000
1304 227 CONTINUE

1305 GO TO 972
1306 1227 CONTINUE
1307 GO TO 973
1308 2227 CALL SHIFT5(XT,YT,XA,XB)
1309 GO TO 1000
1310 228 CALL DTDA(IXT,XA)
1311 GO TO 1000
1312 229 CALL RSHIFT(XT,YT,XT,YT)
1313 GO TO 1000
1314 230 CALL RSHIFT(XT,YT,XA,XB)
1315 GO TO 1000
1316 231 CALL RSHIFT5(XT,YT,XA,XB)
1317 GO TO 1000
1318 232 CONTINUE
1319 GO TO 974
1320 1232 GO TO 973
1321 2232 CALL RSHIFT5(XT,YT,XA,XB)
1322 GO TO 1000
1323 233 CALL DFTRF(XT,YT)
1324 GO TO 1000
1325 234 CALL DFTFU(XT,YT)
1326 GO TO 1000
1327 235 CALL ALURNU(XT)
1328 GO TO 1000
1329 236 CALL ADRNU(YT)
1330 GO TO 1000
1331 237 CALL AURNU(XT,YT)
1332 GO TO 1000
1333 238 CALL CONV(XT,YT,XL1,XL2,\$1130)

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INPUT LISTING

AUTOFLOW CHART SET - FNU/SCL RADSIM

CARD NO.

CONTENTS

3-13

1354 GOTO 1000
 1355 239 CALL ADDA(YT,XB,\$1130)
 1356 GOTO 1000
 1357 C
 1358 301 CONTINUE
 1359 IF(1CFG.GT.1.AND.NPTAZ.EQ.0) GO TO 1302
 1360 CALL ANTINT(NPTAZ,AZEST+ANTAZ,CDEFAL)
 1361 1302 IF(1CFG.GT.1.AND.NPTLL.EQ.0) GO TO 1000
 1362 CALL ANTINT(NPTEL,ELBST+ANTEL,CDEFEL)
 1363 GO TO 1000
 1364 302 CALL SDBLKX(140,1,13,1DATA,ICLCNT)
 1365 CALL SDBLKX(120,14,9,1DATA,ICLCNT)
 1366 GO TO 1000
 1367 303 CALL PTLIST(XT)
 1368 GO TO 1000
 1369 304 CALL PTLIST(YT)
 1370 GO TO 1000
 1371 305 CALL PTLIST(XA)
 1372 GO TO 1000
 1373 306 CALL PTLIST(XB)
 1374 GO TO 1000
 1375 307 CALL PLUTTK(XT)
 1376 GO TO 1000
 1377 308 CALL PLUTTK(YT)
 1378 GO TO 1000
 1379 309 CALL PLUTTK(XA)
 1380 GO TO 1000
 1381 310 CALL PLUTTK(XB)
 1382 GO TO 1000

1500	512 CALL SPCLAVG(XA,\$1050)	25003-14
1504	512 TO 1000	
1505	512 CALL SCANNK(XA)	2520
1506	512 TO 1000	
1507	C	
1508	C	
1509	502 CALL NOLIN(XT,\$1050)	
1510	502 TO 1000	
1511	402 CALL NOLIN(YT,\$1050)	
1512	402 TO 1000	
1513	402 CALL C1FLP(XI,YT)	
1514	402 TO 1000	
1515	402 CALL C2FLP(XT,YT)	
1516	402 TO 1000	
1517	402 CALL R1FLP(XT,YT)	
1518	402 TO 1000	
1519	402 CALL R2FLP(XI,YT)	
1520	402 TO 1000	
1521	502 CALL FILT(XI,YT)	
1522	502 TO 1000	
1523	502 CALL FILT(XA,XE)	
1524	502 TO 1000	
1525	402 CALL INFLC(XA,XT)	
1526	402 TO 1000	
1527	402 CALL INFLC(YT,YT)	
1528	402 TO 1000	
1529	512 CALL ANTAN(XT,YT,\$1050)	2700
1530	512 TO 1000	
1531	512 CALL ENDFL(XI,YT)	

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INPUT LISTING

AUTOFLOW CHART SET - FWD/SCL KADSIM

CARD NO.

CONTENTS

3-15

1342	66 TU 1000	
1343	415 CALL FWDET(YT,YT)	
1344	66 TU 1000	
1345	416 CALL FWDET(XT,XT)	
1346	66 TL 1000	
1347	417 CALL FWDET(YT,YT)	
1348	66 TU 1000	
1349	418 CALL SLDET(XT,XT)	
1400	66 TL 1000	
1401	419 CALL SLDET(YT,YT)	
1402	66 TL 1000	
1403	420 CALL FGENXY(XT,YT,\$1030)	
1404	66 TL 1000	
1405	421 CALL FGENMPAT,YT,\$1030	28e0
1410	66 TL 1000	
1411	422 CALL DIGTFL(IXT,IXT)	
1406	66 TU 1000	
1407	423 CALL DIGTFL(IYT,IYT)	
1410	66 TL 1000	
1411	425 CALL CGEN(XT,YT,XD1,XD2,\$1040)	
1412	66 TU 1000	
1413	426 CALL TSARY(IXT,YT,XD1,XD2,\$1020)	
1414	66 TL 1000	
1415	427 CALL TSARY(IXT,YT,XD1,XD2,\$1020)	
1416	66 TL 1000	
1417	430 66 TL(1430,2430),M00LUF	
1418	1430 CALL MTFLT(XT,XT)	
1419	66 TL 1000	
1420	430 CALL MTFLT(IXT,IXT)	

1421 GU TL 1000
1422 431 GU TU(1431,2431),MODULEF
1423 1431 CALL MT1FL1(Y1,Y1)
1424 GU TL 1000
1425 2431 CALL MT1FL1(Y1,Y1)
1426 GU TU 1000
1427 432 GU TU(1432,2432),MODULEF
1428 1432 CALL MT1NLL(XT,XT)
1429 GU TU 1000
1430 2432 CALL MT1NLL(XT,XT)
1431 GU TU 1000
1432 433 GU TU(1433,2433),MODULEF
1433 1433 CALL MT1NLL(Y1,Y1)
1434 GU TU 1000
1435 2433 CALL MT1NLL(Y1,Y1)
1436 GU TU 1000
1437 434 CALL SWPINT(XT,XT)
1438 GU TU 1000
1439 435 CALL SWPINT(Y1,Y1)
1440 GU TL 1000
1441 436 CALL NSWP1(XT,XT)
1442 GU TL 1000
1443 437 CALL NSWP1(Y1,Y1)
1444 GU TU 1000
1445 438 CALL HLIM(XT,XT)
1446 GU TU 1000
1447 439 CALL HLIM(Y1,Y1)
1448 GU TU 1000
1449 440 CALL DCFAK1(XT,XA)

3-16

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INPUT LISTING

AUTOFLOW CHART SET - FWL/SCL KADSIM

CARD NO.

CONTENTS

3-17

1450 GL TD 1000
 1451 441 CALL UCFAPI(IXT,XB)
 1452 GL TL 1000
 1453 442 CALL IHLIM(IYT,IXT)
 1454 GL TD 1000
 1455 443 CALL IHLIM(IYT,IYT)
 1456 GL TL 1000
 1457 445 CALL IHADLT(IXT,IXT)
 1458 GL TD 1000
 1459 446 CALL IHADLT(IYT,IYT)
 1460 GL TL 1000
 1461 447 CALL IFNDET(IXT,IXT)
 1462 GL TL 1000
 1463 448 CALL IFNDET(IYT,IYT)
 1464 GL TL 2000
 1465 449 CALL ISGDET(IXT,IXT)
 1466 GL TL 1000
 1467 450 CALL ISGDET(IYT,IYT)
 1468 GL TL 2000
 1469 451 CALL RCLF(IXT,YT,XA,XE)
 1470 GL TD 1000
 1471 452 CALL RCLFT(IXT,YT)
 1472 GL TD 1000
 1473 453 CALL CBLNSP(IXT,YT)
 1474 GL TL 1000
 1475 454 CALL FAFRM(IXT,YT)
 1476 GL TD 1000
 1477 455 CALL LLCHN(IXT,YT)
 1478 GL TL 1000

1474	450	CALL LAMPRE(XT,XT)
1480		GOTO 1000
1481	457	CALL LAMPRE(YT,YT)
1482		GOTO 1000
1483	458	CALL LAMPLP(XT,YT,XT,YT)
1484		GLTC 1000
1485	459	CALL LFAK(XT,XA)
1486		GLTC 1000
1487	460	CALL CFAK(YT,XB)
1488		GLTC 1000
1489	461	CALL DIGF2L(XT,YT)
1490		GLTC 1000
1491	462	CALL DIGFNL(XT,YT)
1492		GLTC 1000
1493	463	CALL DIGFS(XT,YT)
1494		GLTC 1000
1495	L	
1496	SUB CALL TARGET(XT,YT)	
1497		GU TU 1000
1498	SUB CALL TG1NLL(XT,YT)	
1499		UL TL 1000
1500	SUS IF(1000LN(20)+EQ.0) GO TO 1121	
1501		CALL CLUTIA(XT,YT,XR1,XR2,\$1120)
1502		GU TU 1000
1503	SUB CALL ANTIPAT(XT,YT,\$1060)	3540
1504		UL TL 1000
1505	SUB CALL TSKPAT(XT,YT,XD1,XD2,XTM,YTM,\$1162)	
1506		UL TU 1000
1507	SU CALL PHULLC(XT,YT)	

3-18

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INPUT LISTING

AUTOFLOW CHART SET - FWD/SEL RADSIM

3-19
3000

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CONTENTS

1500 GOTO 1000
 1509 509 CALL PHULL(XA,XB)
 1510 GOTO 1000
 1511 510 CALL WVGUJU(XT,YT)
 1512 GOTO 1000
 1513 511 CALL IUNUS(XT,YT)
 1514 GOTO 1000
 1515 512 CALL ECH(XT,YT)
 1516 GOTO 1000
 1517 L
 1518 107 CONTINUE
 1519 109 CONTINUE
 1520 111 CONTINUE
 1521 114 CONTINUE
 1522 120 CONTINUE
 1523 L
 1524 240 CONTINUE
 1525 241 CONTINUE
 1526 242 CONTINUE
 1527 243 CONTINUE
 1528 L
 1529 311 CONTINUE
 1530 L
 1531 421 CONTINUE
 1532 424 CONTINUE
 1533 426 CONTINUE
 1534 428 CONTINUE
 1535 429 CONTINUE
 1536 430 CONTINUE

3-20

08/11/75 INPUT LISTING AUTOFLOW CHART SET - FWD/SCL RADSIM
 CARO NO **** CONTENTS 3-21
 1566 455 CONTINUE
 1567 WRITE(IFC) YT
 1568 IF(ITY.GT.512) WRITE(IFC) (YT(J),J=513,ITY) 4210
 1569 WRITE(6,1954) AYT,IFC
 1570 GO TO 1000
 1571 C
 1572 456 CONTINUE
 1573 WRITE(IFC) XAT
 1574 IF(IXA.GT.512) WRITE(IFC) (XA(J),J=513,IXA) 4270
 1575 WRITE(6,1954) AXA,IFC
 1576 GO TO 1000
 1577 C
 1578 457 CONTINUE
 1579 WRITE(IFC) XBT
 1580 IF(IXB.GT.512) WRITE(IFC) (XB(J),J=513,IXB) 4330
 1581 WRITE(6,1954) AXB,IFC
 1582 GO TO 1000
 1583 C
 1584 458 CONTINUE
 1585 READ(IFC) XTT
 1586 IF(IT.GT.512) READ(IFC) (XT(J),J=513,IT) 4390
 1587 WRITE(6,1954) AXT,IFC
 1588 1950 FORMAT(' THE ARRAY',A6,'HAS BEEN LOADED FROM DATA SET NO.',IS)
 1589 GO TO 1000
 1590 C
 1591 459 CONTINUE
 1592 READ(IFC) YTT
 1593 IF(ITY.GT.512) READ(IFC) (YT(J),J=513,ITY) 4460
 1594 WRITE(6,1954) AYT,IFC

3-22

```

1240      GL TL 1000
1240      C
1247      460 CONTINUE
1248      READ(IFC) XAT
1249      IF(IXA.GT.512) READ(IFC) (XA(J),J=513,IXA) 4520
1250      WRITE(6,1458) AXA,IFC
1251      GL TL 1000
1252      C
1253      461 CONTINUE
1254      READ(IFC) XBT
1255      IF(IXB.GT.512) READ(IFC) (XB(J),J=513,IXB) 4580
1256      WRITE(6,1458) AXB,IFC
1257      GL TL 1000
1258      462 CONTINUE
1259      GL TL 1000
1260      463 CONTINUE
1261      GL TL 1000
1262      464 CONTINUE
1263      GL TL 1000
1264      465 CONTINUE
1265      GL TL 1000
1266      466 CONTINUE
1267      GL TL 1000
1268      467 CONTINUE
1269      GL TL 1000
1270      468 CONTINUE
1271      GL TL 1000
1272      469 CONTINUE
1273      GL TL 1000

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INPUT LISTING

AUTOFLOW CHART SET - FWD/SCL RADSIM

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CARD NL	*****	CONTENTS	*****
1624	C		
1625	970 CONTINUE		
1626	DO 1970 K=1,8147		
1627	1970 XTT(K)=0.0		
1628	IT=2**N2		
1629	DELT=T1		
1630	WRITE(6,2970) AXT		
1631	2970 FORMAT(' THE ARRAY ',A6,', HAS BEEN SET TO 0.0 ')		4850
1632	DL TL 1000		
1633	971 CONTINUE		
1634	DL 1971 K=1,8147		
1635	1971 YTT(K)=0.0		
1636	ITY=2**N2		
1637	DELTY=T1		
1638	WRITE(6,2970) AYT		
1639	DL TL 1000		
1640	972 CONTINUE		
1641	DL 1972 K=1,8147		
1642	1972 XAT(K)=0.0		
1643	WRITE(6,2970) AXA		
1644	IF(MODULE.EQ.227) DL TL 1227		
1645	IF(MODULE.EQ.232) GO TO 1232		
1646	IXA=2**N2		
1647	XADEL=T1		
1648	DL TL 1000		
1649	973 CONTINUE		
1650	DO 1973 K=1,8147		
1651	1973 XET(K)=0.0		
1652	WRITE(6,2970) AXE		

1671 IF (INCLUDE .LE. 27) GO TO 2227 3-24
1674 IF (INCLUDE .GE. 232) GO TO 2232
1675 IXH=2**NZ
1676 XNDL=11
1677 GO TO 1000
1678 C
1679 1020 WRITE(0,1015)
1680 FORMAT(* NON-STANDARD RETURN FROM SUBROUTINE WEIT*)
1681 GO TO 2020
1682 C
1683 1021 WRITE(0,1025) 5111
1684 FORMAT(* NON-STANDARD RETURN FROM SUBROUTINE TSARY*) 5112
1685 GO TO 2020 5113
1686 C 5114
1687 1030 WRITE(0,1035) 5141
1688 FORMAT(* NON-STANDARD RETURN FROM SUBROUTINE FGENXY*)
1689 GO TO 2020
1690 1040 WRITE(0,1045)
1691 FORMAT(* NON-STANDARD RETURN FROM SUBROUTINE CGEN*)
1692 GO TO 2020
1693 C
1694 1050 WRITE(0,1055)
1695 FORMAT(1H , * NONLINEAR TRANSFORM IMPROPERLY DEFINED *)
1696 GO TO 2020
1697 C
1698 1060 WRITE(0,1065)
1699 FORMAT(* NON-STANDARD RETURN FROM SUBROUTINE ANTARY*)
1700 GO TO 2020
1701 C

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AUTOFLOW CHART SET - PWL/SCL RADSIM

3-25

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CONTENTS

1602 WRITE(6,1602)
1603 FORMAT(* NON-STANDARD RETURN FROM SUBROUTINE PLTEM1*)
1604 GO TO 2020
1605 C
1606 WRITE(6,1606)
1607 FORMAT(* NON-STANDARD RETURN FROM SUBROUTINE SPCAVG *)
1608 GO TO 1000
1609 C
1610 WRITE(6,1610)
1611 FORMAT(* NON-STANDARD RETURN FROM SUBROUTINE CLUTTER*)
1612 GO TO 1000
1613 C
1614 WRITE(6,1614)
1615 FORMAT(* THE CLUTTER MODEL HAS NOT BEEN PROPERLY INITIALIZED BY *
* CLINT1*. *CLUTTER* WILL NOT BE EXECUTED*)
1616 GO TO 2020
1617 C
1618 WRITE(6,1618)
1619 FORMAT(* NON-STANDARD RETURN FROM SUBROUTINE CONV*)
1620 GO TO 1000
1621 C
1622 WRITE(6,1622)
1623 FORMAT(* SUBROUTINE TSRPAT NOT EXECUTED *)
1624 GO TO 2020
1625 C
1626 WRITE(6,1626) JSTEP, MODULE, ITEMP
1627 FORMAT(* STEP *, I3, * WITH MODULE = *, I4, * HAS SCHEDULED AN OP
* ERATION WITH EXEC NUMBER *, I3, * WHICH IS OUT OF RANGE*)
1628 GO TO 1000

1611 C
1612 2000 WRITE(6,2005)
1613 END FORMAT(*,0A) CONDITION EXISTS WHICH WILL CAUSE THE REMAINDER OF THE
1614 *S CONFIGURATION TO BE BYPASSED.*)
1615 GO TO 290
1616 C
1617 2000 WRITE(6,2055)
1618 2055 FORMAT(* THIS JOB COMPLETE *)
1619 CALL EXIT
1620 2000 WRITE(6,2005)
1621 2005 FORMAT(* THIS JOB ABORTED BECAUSE OF IMPROPER INPUT DATA*,
1622 * ****SEE PRINT OUT FROM ACTIVITY 1*)
1623 CALL EXIT
1624 STOP
1625 END

3-26

CALL DTOA (IX,X)

Where: IX contains the Input Waveform
 X contains the Output Waveform

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. If the computed digital output is greater than the largest number which can be specified by NBITS, it will be set to the maximum number.
- b. Flow Chart: Page 9-98
- c. Cross Reference Table: 9-220.

6. THEORY OF OPERATION

The analog-to-digital conversion is performed by dividing the floating point input signal by the value of the least significant digital bit. If round off is to be performed, 0.5 is then added to the value. The value thus obtained is converted to an integer number and its absolute value is tested against the maximum allowable number, $2^{**}(NBITS-1)$. If the magnitude of the signal is greater than the maximum allowable, it is set equal to the maximum. The basic mechanization equation for the ATOD module is:

$$IX (J) = IFIX(X(J)/XLSB + 0.5 * IROFF)$$

The digital-to-analog conversion is made by changing the input to a floating point number and multiplying it times the value of the least significant bit. The basic mechanization equation for the DTOA module is:

$$X(J) = FLOAT (IX(J)) * ZLSB$$

where: ZLSB = BOOL (IX(N196))

2544 SUBROUTINE ATOD(X,IX) 4-4
2600 C
2601 C**** THIS SUBROUTINE PERFORMS AN ANALOG TO DIGITAL (REAL TO INTEGER)
2602 C CONVERSION WITH SPECIFIED DIGITAL PRECISION AND SATURATION
2603 C LEVEL, OR A DIGITAL TO ANALOG (INTEGER TO REAL) CONVERSION
2604 C ON THE INPUT DATA ARRAY. *****
2605 C
2606 COMMON/BLK1/BK1(500)
2607 DIMENSION X(1),IX(1)
2608 EQUIVALENCE (BK1(103), XLSB) ,
2609 * (BK1(104), NBITS) , (BK1(105), IKUFF)

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INPUT LISTING

AUTOFLOW CHART SET - FWD/SCL RADSIM

4-4a

CARD NO.	*****	CONTENTS	*****
2610	*	(DH1(144), ADCFS)	
2611		DATA N193,N194,N195,N196/-3,-2,-1,0/	
2612		WHILE (6, 120)	
2613		TIMADC=1.0/ABS(ADCF5)	
2614		T1=X(N195)	
2615		TIMADC=X(N194)	
2616		TIME=TIMADC+T1*0.5	
2617		N=IDULL(X(N193))	
2618		K=1	
2619		IF (NBITS .LT. 31) GO TO 20	
2620		NBITS = 31	
2621		WHILE (6, 110) NBITS	
2622		10 CONTINUE	
2623		MAX = 2**(NBITS-1)	
2624		RCH = 0.5*FLCATT(FLCFF)	
2625		UXLSB = 1.0 / XLSB	
2626	C		
2627		***** ANALOG TO DIGITAL CONVERSION *****	
2628	C		
2629		DC = 40 J = 19 19	
2630		IF (TIME.LT.TIMADC) GO TO 20	
2631		IY(K)=FIX(X(J)*UXLSB+FCH)	
2632	C		
2633		***** DCF CALCULATION *****	
2634	C		
2635		IF (FLCATT(IY(K)).GT.Max) IY(K)=FLCATT(MAX,IY(K))	
2636		FLCATT=FLCATT+FLATE	
2637	C		
2638		IF (K.NE.1)	
		DO 10 J=2,K	

2639 20 IF(AUDCF) 31,02,02
2640 31 IX(N)=IX(N-1)
2641 N=N+1
2642 32 TIM₁=TIME+TA
2643 40 CONTINUE
2644 C
2645 IX(N193)=N-1
2646 IX(N194)=ISQUL(X(N194))
2647 IX(N195)=ISQUL(TIADC)
2648 IF(AUDCF.LT.0.0) IX(N195)=BQUL(TI)
2649 IX(N196)=ISQUL(XLSB)
2650 RETURN
2651 ENTRY DTLA(IX,X)
2652 WRITE(6, 150)
2653 X(N193)=BQUL(IX(N193))
2654 X(N194)=BQUL(IX(N194))
2655 X(N195)=BQUL(IX(N195))
2656 N=IX(N193)
2657 ELSE=BQUL(IX(N196))
2658 C
2659 ***** DIGITAL TO ANALOG CONVERSION *****
2660 C
2661 DO 30 J= 1, N
2662 X(J)=FQAT(IX(J))+ZLSF
2663 GO CONTINU
2664 RETURN
2665 IIC FORMAT OF NBITS IS EXCESSIVE. THE VALUE OF NBITS HAS BEEN SET TO
2666 *8,1*)
2667 I2D FORMAT(//24X,* * * * * A TO D CONVERTER * * * */ /)
2668 I3D FORMAT(//24X,* * * * * D TO A CONVERTER * * * */ /)
2669 END

SUBROUTINE CDIGFL

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
CDIGFL	LTI-4	403
CDFNCL	LTI-4	404

2. PURPOSE:

This subroutine is used to simulate a cross-coupled digital filter and synthesize a filter transfer function having one complex pole and/or one complex zero.

3. INPUT PARAMETERS:

Name	O/R	T	Description
FFR	0	F	Feed - Forward coefficient - R
FFI	0	F	Feed - Forward coefficient - I
FBR	0	F	Feedback coefficient - R
FBI	0	F	Feedback coefficient - I

4. CALLING SEQUENCES:

CALL CDIGFL (X,Y)

Where: X contains the Input Waveform - R
 Y contains the Input Waveform - I
 X contains the Output Waveform - R
 Y contains the Output Waveform - I

The storage registers (TX1 and TY1) are cleared before execution begins.

CALL CDFNCL (X,Y)

Where: X contains the Input Waveform - R
 Y contains the Input Waveform - I
 X contains the Output Waveform - R
 Y contains the Output Waveform - I

The storage registers, TX1 and TY1, are not cleared before execution begins.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

a. Flow Chart: Page 9-96

b. Cross Reference Table: 9-220

6. THEORY OF OPERATION

The block diagram of the complex digital filter simulated by this module is shown in Figure CDIGFL-1. The Z-plane transfer function is given by the following expression:

$$T(Z) = \frac{Z - (FFR + jFFI)}{Z - (FBR + jFBI)}$$

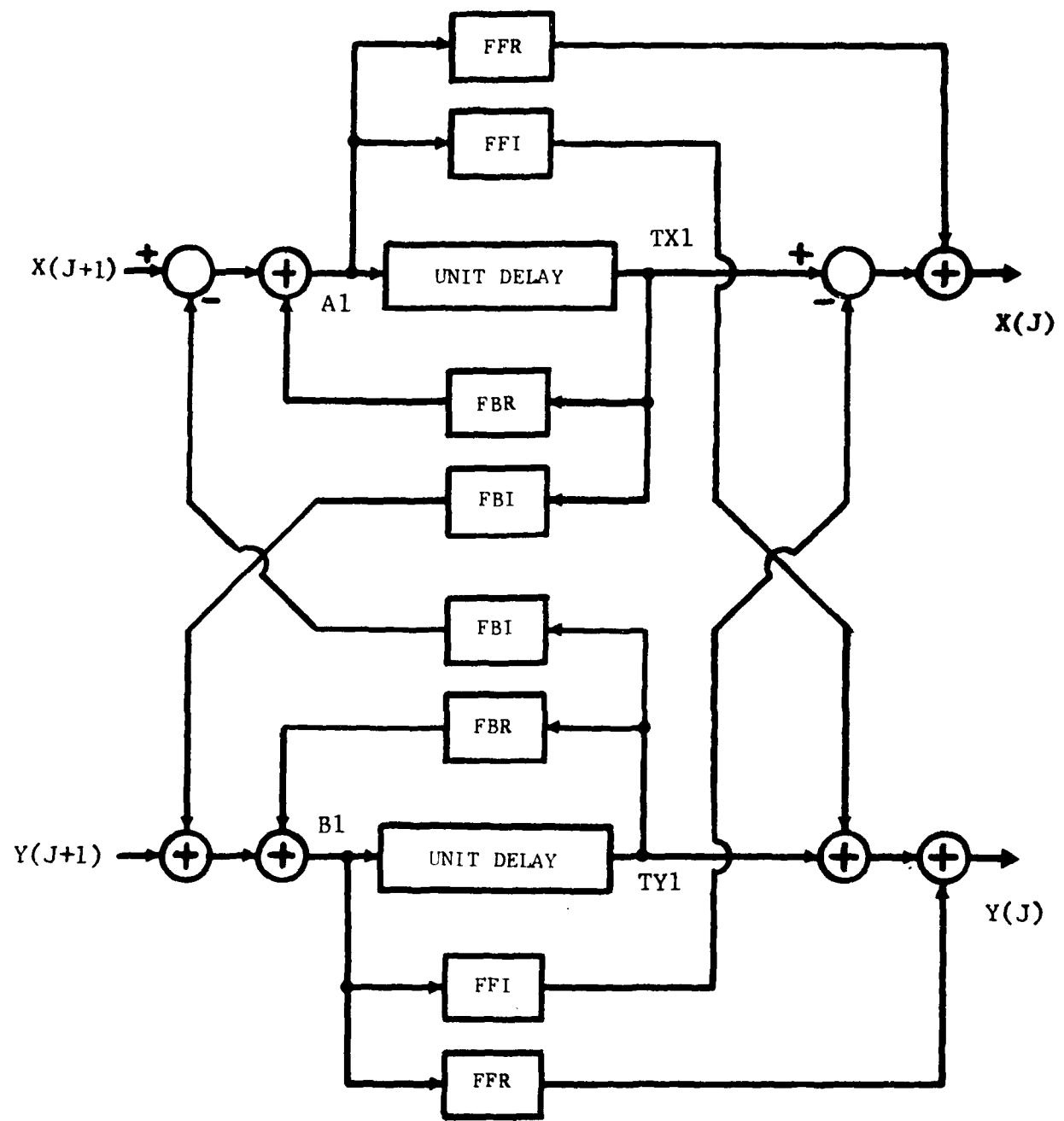


Figure CDIGFL-1 BLOCK DIAGRAM OF CDIGFL/CDFNCL

2501	SUBROUTINE CDFNCL(X,Y)	4-9
2504	COMMON/ZLK1/ZLK1(500)	
2505	BK1VALLEN(LBK1(62), FFX),LBK1(65), FFXY),	470
2506	* (BK1(70), FFX), (BK1(71), FFXY)	480
2507	DATA K143/-5/	490
2508	DIMENSION X(3),Y(1)	
2509	TX1=0.0	510
2510	TY1=0.0	520
2509	ENTRY CDFNCL(X,Y)	
2510	N=LLI(X(1),S1)	
2511	L1=10,J=1,I1	570
2512	A1=X(J)+TX1*FFX-TY1*FFXY	
2513	U1=Y(J)+TY1*FFX+TX1*FFXY	
2514	X(J)=A1*FFX-U1*FFXY+TX1	
2515	Y(J)=U1*FFX+A1*FFXY+TY1	
2516	TX1=F1	620
2517	TY1=S1	621
2518	I0=CONTINU	622
2519	RETURN	623
2520	END	624

SUBROUTINE CFAR

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
CFAR	NL-2	459,460

2. PURPOSE:

This subroutine is used to simulate a constant false alarm rate (CFAR) video processor.

3. INPUT PARAMETERS:

Name	O/R	T	Description
TAVG	R	F	Width of averaging window used in determining video gain (TAVG \geq 2*TI)

4. CALLING SEQUENCES:

CALL CFAR(VIN,VOUT)

Where: VIN contains the Input Waveform
 VOUT contains the Output Waveform

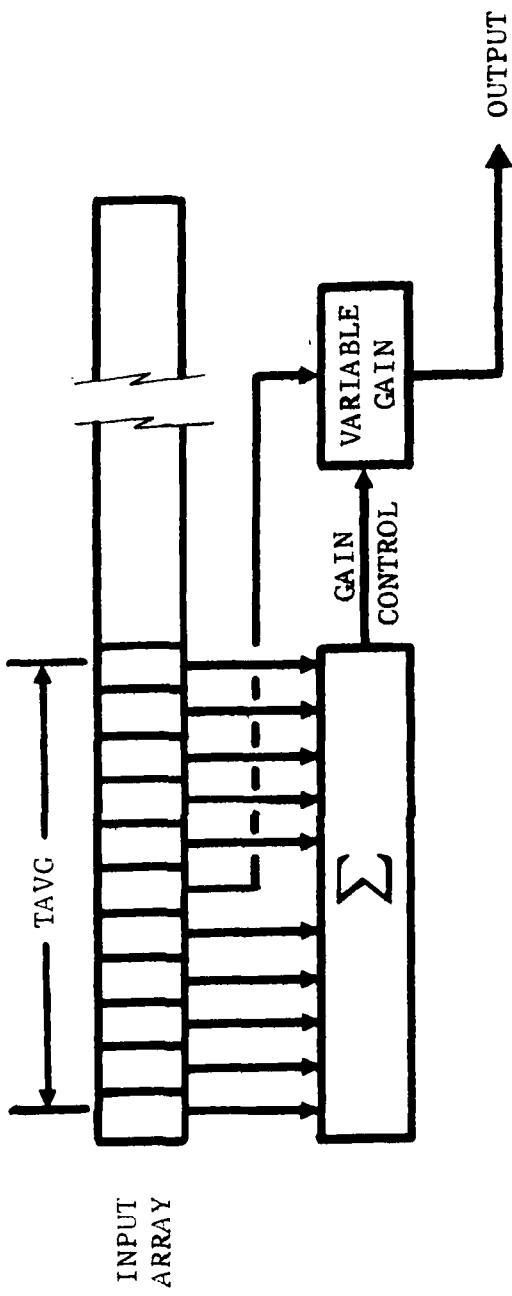
5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- The input and output arrays cannot be equivalenced.
- Flow Chart: Page 9-66
- Cross Reference Table: Page 9-216

6. THEORY OF OPERATION

The block diagram of the CFAR processor simulated by this module is shown in Figure CFAR-1. Each sample of the input waveform is passed through a variable gain amplifier which is controlled by the average value

Figure CFAR-1 BLOCK DIAGRAM OF CFAR



of this waveform surrounding the sample being processed.
The gain applied to the Jth sample is given by the
following expression:

$$G(J) = \frac{2 * NCELL2}{\sum_{K=J+NCELL2}^{K=J-NCELL2} (|V_{IN}(K)| - |V_{IN}(J)|)}$$

where: $NCELL2 < J \leq NPTS - NCELL2$

$NCELL2 = \text{IFIX}(TAVG * 0.5 / TI)$

$TI = \text{independent variable increment between samples}$

$NPTS = \text{number of samples in the input array}$

```
2000      SUBROUTINE CFAR(VIN,VOUT)
2001      COMMON/BLK1/ BK1(200)
2002      DIMENSION VIN(1),VOUT(1)
2003      EQUIVALENCE (BK1(146), TAVG )
2004      DATA N143,N144,N145/-3,-2,-1/
2005      NCELL2=IFIX(TAVG*0.5/VIN(N145))
2006      XCELL=2*NCELL2
2007      NPTS=BLDL(VIN(N143))
2008      NSTLP=NPTS-NCELL2
2009      NCELL1=NCELL2+1
2010      AV=0.0
2011      DO 100 J=1,NCELL2
2012      AV=AV+ADS(VIN(J))
2013      100  CONTINUE
2014      GF=1.0
2015      DO 200 J=1,NPTS
2016      IF(J.LE.NSTLP) AV=AV+ABS(VIN(J+NCELL2))
2017      IF(J.GT.NCELL1) AV=AV-ABS(VIN(J-NCELL1))
2018      DVSR=AV-AES(VIN(J))
2019      IF(DVSR.GT.1.0E-20) GF=XCELL/DVSR
2020      VOUT(J)=VIN(J)*GF
2021      200  CONTINUE
2022      VLUT(N143)=VIN(N143)
2023      VLUT(N144)=VIN(N144)
2024      VLUT(N145)=VIN(N145)
2025      RETURN
2026      END
```

SUBROUTINE CLUTTR

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
CLUTTR	LTI-3 or LTV-3	503

2. PURPOSE:

This subroutine generates the transfer function of a clutter volume. A pictorial diagram of the clutter volume is shown in Figure CLUTTR-1.

3. INPUT PARAMETERS:

All required input data is entered via the clutter model initialization subroutine (CLINT).

4. CALLING SEQUENCES:

CALL CLUTTR(XT,YT,GAZ,GEL)

WHERE: XT contains the Output Impulse response - R

YT contains the Output Impulse response - I

GAZ-Temporary storage for antenna azimuth gain values (MM=number of storage cells required)

GEL-Temporary storage for antenna elevation gain values (NN - number of storage cells required)

5. RESTRICTIONS, REQUIREMENTS, AND MISCELLANEOUS DATA

- a. The subroutines CLINT must have been successfully executed prior to calling CLUTTR. See p 6-4 for restrictions on CLINT.
- b. The functions AZGAIN and ELGAIN are used to compute the antenna gain associated with each scatterer.

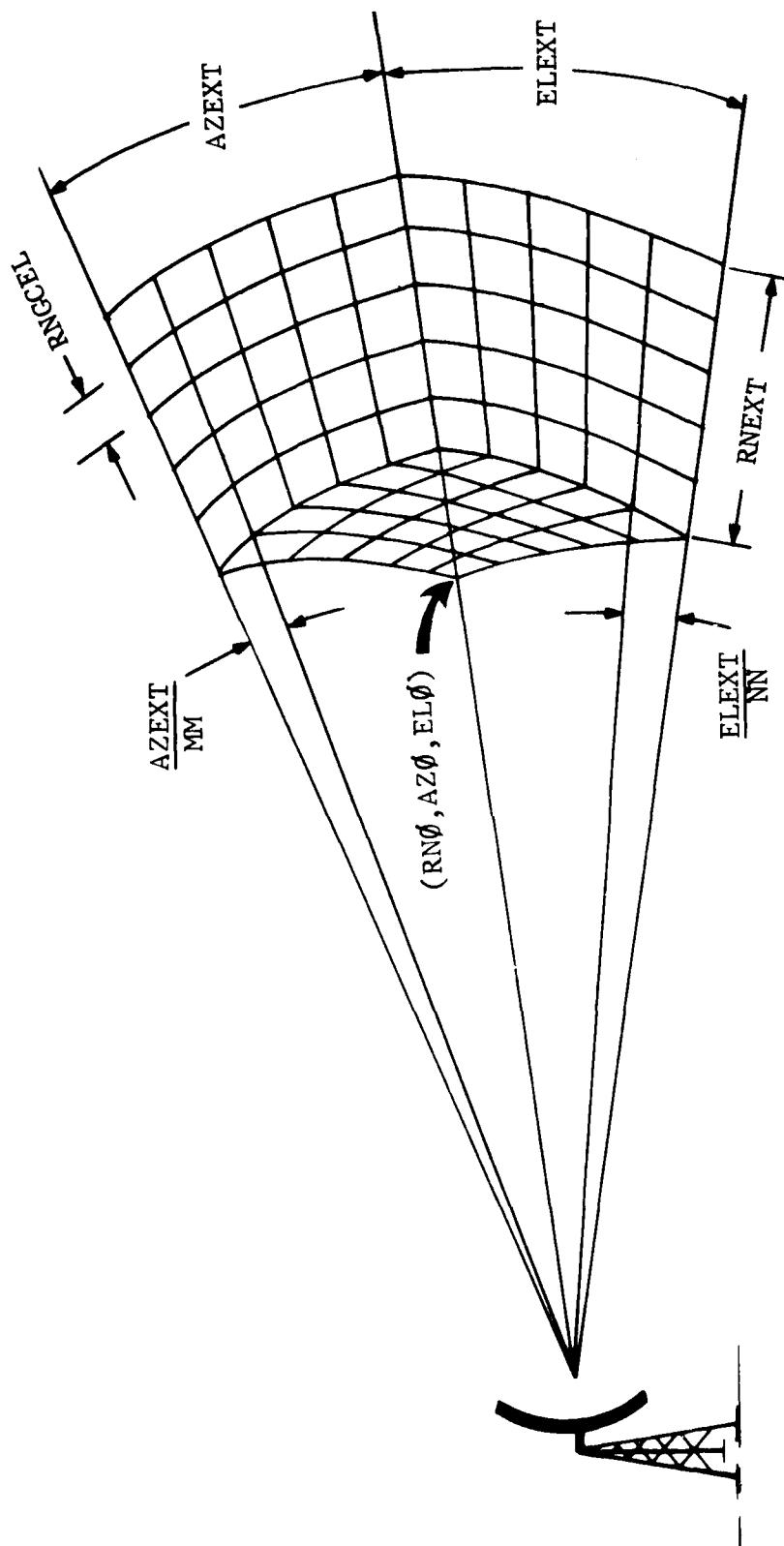


Figure CLUTTR-1 CLUTTER MODEL GEOMETRY

c. Flow Chart: Page 9-112

d. Cross Reference Table: Page 9-222

6. THEORY OF OPERATION

The clutter model is based on the premise that a volume of clutter can be represented by an ensemble of discrete scatterers. The RCS of these scatterers is derived from a theoretical probability density function, but can be easily modified to allow the use of a density function derived from measurements data. The phase behavior of the scatterer is determined from motion of the scatterer due to wind and from any inherent frequency spread derived from measurements data. The basic mechanization equation for the clutter model is given by the following expressions:

a. MODE = 1 (stationary clutter):

$$XT(K) + jYT(K) = \sum_{N=1}^{NN} GEL(N) \sum_{M=1}^{MM} GAZ(M) [CLUX(IPNT) + jCLUY(IPNT)]$$

where: GEL(N) - Normalized antenna gain corresponding to an elevation angle of $EL\theta\theta\theta + DELEL * (N-1)$

GAZ(M) - Antenna gain corresponding to an azimuth angle of $AZ\theta\theta\theta + DELAZ * (M-1)$

IPNT - Scatterer element pointer which is determined as follows:

$$IPNT = (K*(N-1)(M-1)+(N-1)*MM+M) \text{ MODULO } 250$$

CLUX() - Array containing real part of clutter scatterer specification

CLUY() - Array containing imaginary part of clutter scatterer specification

b. MODE = 2 (Time varying clutter):

$$XT(K) + jYT(K) = \sum_{N=1}^{NN} GEL(N) \sum_{M=1}^{MM} GAZ(M) [CLUX(PDNT) + jCLUY(IDNT)] * e^{\underline{\text{PHDEL}}}$$

"New" CLUX(IDNT) + jCLUY(PDNT)

Where: PHDEL = is the phase term to be applied to each scatter

$$= 57.29578 * \text{DELTIM} * \text{DOPFRQ} * \cos \left[\text{XVLANG} - \text{DELAZ} * (M-1) \right] / 57.29567 + \text{PHRW}$$

DELTIM = Radar interpulse period

PHRW = The random walk phase. This variable is generated by a random number generator from a uniform distribution.

$$-\frac{\text{RWPH}}{2.0} < \text{PHRW} < \frac{\text{RWPH}}{2.0}$$

The pulse phase shift due to doppler is computed via a recursive loop which is more efficient than a direct evaluation of the cosine function.

$$\begin{aligned} C(N+1) &= C(N) * \text{DELCS} - S(N) * \text{DELSN} \\ S(N+1) &= C(N) * \text{DELSN} + S(N) * \text{DELCS} \end{aligned}$$

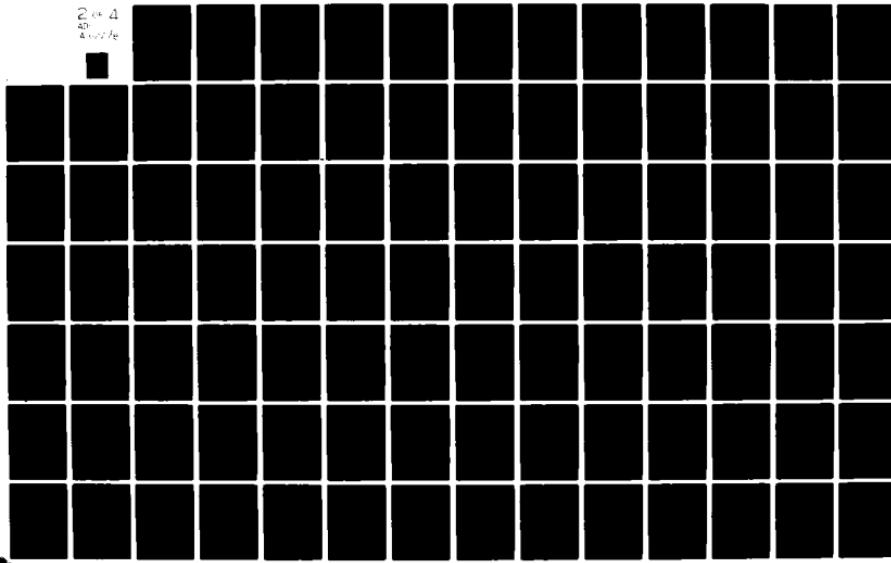
where C = Phase shift due to doppler

$$\begin{aligned} C(1) &= \text{DOPFRQ} * \text{DELTIM} * 2\pi * \cos(\text{XVLANG}) \\ S(1) &= \text{DOPFRQ} * \text{DELTIM} * 2\pi * \sin(\text{XVLANG}) \end{aligned}$$

The clutter scatterer parameters (CLUX and CLUY) are updated by PHDEL for each execution of the clutter model and the new values are stored in the random disc file.

AD-A102 278 GENERAL DYNAMICS FORT WORTH TEX CONVAIR AEROSPACE DIV F/6 17/9
ENDO ATMOSPHERIC-EXO ATMOSPHERIC RADAR MODELING, VOLUME II. PAR--ETC(U)
JUN 76 R J HANCOCK, F H CLEVELAND F30602-73-C-0380
UNCLASSIFIED RADC-TR-76-186-VOL-2-PT-1 NL

2 of 4
40
40-178



```

2452      SUBROUTINE CLUTTR(XT,YT,GAZ,GEL,*)
2456      COMMON/LKL1/ BK1(200)
2457      COMMON/BLK330/BK4(30)
2458      DIMENSION GAZ(1),GEL(1),CLUX(250),CLUY(250)
2459      COMMON/LBLRND/ IIII(12),NRAND(129)
2460      DIMENSION XT(1),YT(1),CSCAT(500),IRAND(128)
2461      EQUIVALENCE (CLUX(1),CSCAT(1)), (IRAND(1),NKAUD(2))
2462      EQUIVALENCE (CLUY(1),CSCAT(251))
2463      EQUIVALENCE (BK1( 14), TCELL)      1,(BK1( 21), TOMP)    1,
2464      *      (BK1( 12), TI)           1,(BK1( 23), PS)    1,
2465      *      (BK4( 3), RWPH)        1,
2466      *      (BK4( 6), RNEXT)       1,
2467      *      (BK4( 7), RN000)       1,(BK4( 4), AZ000)    1,
2468      *      (BK4( 10), MM)         1,(BK4( 12), EL000)    1,
2469      *      (BK4( 13), NN)         1,(BK4( 14), KK)    1,
2470      *      (BK4( 16), MDE)        1,(BK4( 17), DELAZ)   1,
2471      *      (BK4( 18), DELET)       1,(BK4( 19), XVLANG) 1,
2472      *      (BK4( 20), ICFLG)       1,(BK4( 21), DUFFFLG) 1
2473      *      (BK4( 22), KCELL)       1
2474      EQUIVALENCE (BK1( 16), TIME)      1
2475      DATA N143,N144,N145,N146/-3,-2,-1,0/
2476      DATA UTIML,IMULT,F12/0.0,1220763125,6.2631055/
2477      CALL RAND12(L2,500)
2478      L
2479      WRITE(6,101) (BK4(J),J=1,30)
2480      101 FORMAT(1H + 012+8X,(12+8X,(12+8X,012+8X,012))
2481      KWPFLC= KWPFL*F12/1.360.0*(2.0**35)
2482      DELAZK=ELLAZ/57.29572
2483      DELTIME= TIME-UTIML
2484      UTIML=TIME
2485      U= KWPFLC*DELTIME+F12
2486      U=U*UCL*(AVLANG-DELAZK)

```

4-18

2897 314-0114(ZVALANG+DELAZK)
 2898 300-0114(ZVALANG+DELAZK)
 2899 311-0114(ZVALANG+DELAZK)
 2900 300-0114(ZVALANG+DELAZK)
 2901 30-100-J=1,MM
 2902 300-0114(ZVALANG+DELAZK)
 2903 300-0114(ZVALANG+DELAZK)
 2904 300-0114(ZVALANG+DELAZK)
 2905 300-0114(ZVALANG+DELAZK)
 2906 300-0114(ZVALANG+DELAZK)
 2907 300-0114(ZVALANG+DELAZK)
 2908 300-0114(ZVALANG+DELAZK)
 2909 300-0114(ZVALANG+DELAZK)
 2910 300-0114(ZVALANG+DELAZK)
 2911 300-0114(ZVALANG+DELAZK)
 2912 300-0114(ZVALANG+DELAZK)
 2913 300-0114(ZVALANG+DELAZK)
 2914 300-0114(ZVALANG+DELAZK)
 2915 300-0114(ZVALANG+DELAZK)

4-18 a

02/11/72

INPUT LISTING

AUTOFLOW CHART SET - FWD/SCL RADSIM

4-19

CARD NO.

CONTENTS

3016 C=FLS
 3017 C=SN
 3018 GO TO M41+MM
 3019 IF (FNT.LL+50) GO TO 750
 3020 GO TO (725+730)+M0DE
 3021 750 = WF11*(2*FREQ)*OSCAT
 3022 725 = FFLC=FLC+1
 3023 FFLC = FFLC*OSCAT
 3024 FFLC+1
 3025 FFLC = FFLC*(M)*QFLC(N)
 3026 GO TO (720+770)+M0DE
 3027 GO TO APAL+FLUX(IPNT)*0
 3028 E+CFLC*(IPNT)*0
 3029 GO TO 700
 3030 770 CONTINUE
 3031 IF (KWH+FLU,0,0) GO TO 780
 3032 IF KWH>FLA(N)(MAD)
 3033 IF KWH>JEND+JEND*IMULT
 3034 IF KWH>FLU(15,7,IRNE)
 3035 JEND=JEND
 3036 IF AND(MAD)=JEND
 3037 MAI=FLU(15,7,JEND)
 3038 FHW=FLLAT(JEND)*FWPHC
 3039 700 CONTINUE
 3040 IF L+EP,0,0) GO TO 790
 3041 TIME=L
 3042 C=FLLLS-S*DLSN
 3043 S=TIME*DLSN+S*DLC5
 3044 790 CONTINUE

```

3046      FNULL=FFNN+L
3047      VCCS=COS(FNULL)
3048      VSIN=SIN(FNULL)
3049      TIMP=CLUX(1PNT)
3050      CLUX(1PNT)=TIMP*VCCS+CLUY(1PNT)*VSIN
3051      CLUY(1PNT)=TIMP*VSIN+CLUX(1PNT)*VCCS
3052      A=A+CLUX(1PNT)
3053      B=B+CLUY(1PNT)
3054      END CONTINUE
3055      IPNT=IPNT+1
3056      END CONTINUE
3057      END CONTINUE
3058      ELL=IFIX(KTIME*EST)
3059      X(EELL)=A
3060      Y(EELL)=B
3061      KTIME=KTIME+KCELL
3062      END CONTINUE
3063      C
3064      IF(IDME<=N/2) WRITE(7,FREC) CSCAT
3065      XT(N193)=DDBL(FCELL)
3066      XT(N194)=EN000
3067      XT(N195)=T1
3068      YT(N193)=XT(N193)
3069      YT(N194)=XT(N194)
3070      YT(N195)=XT(N195)
3071      1001 FORMAT(1H ,6L0,5F)
3072      IF(IDME>N/2) WRITE(6,1001) (XT(J), YT(J), J=1,KCELL )
3073      RETURN
3074      END

```

4-19a

SUBROUTINE DCFAR

1. MODULE IDENTIFICATION:

<u>Name</u>	<u>Classification Code</u>	<u>Reference Number</u>
DCFAR	NL-2	440,441

2. PURPOSE:

This subroutine is used to simulate a digital constant false alarm rate (CFAR) video processor.

3. INPUT PARAMETERS:

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
NCELL	R	I	Number of cells to be averaged in computing the video gain.

4. CALLING SEQUENCES:

CALL DCFAR (IN, IOUT)

Where: IN contains the Input Waveform
IOUT contains the Output Waveform

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. The input and output arrays cannot be equivalenced.
- b. All calculations are in integer format.
- c. Flow Chart: Page 9-93
- d. Cross Reference Table: Page 9-220

6. THEORY OF OPERATION

The block diagram of the digital CFAR processor simulated by this module is shown in Figure DCFAR-1. Each sample of the input waveform is passed through a variable gain amplifier which is controlled by the average value of the waveform surrounding the sample being processed. The gain applied to the Jth sample is given by the following expression:

$$IG = \frac{NCELL}{\sum_{K=J-NCELL2}^{K=J+NCELL2} |IN(K)| - |IN(J)|}$$

where: $NCELL \leq J \leq NPTS - NCELL$

$$NCELL = NCELL/2$$

$NPTS$ = Number of input samples in the input array

The value of the J th output sample is computed as follows:

$$IOUT(J) = IN(J) * IG$$

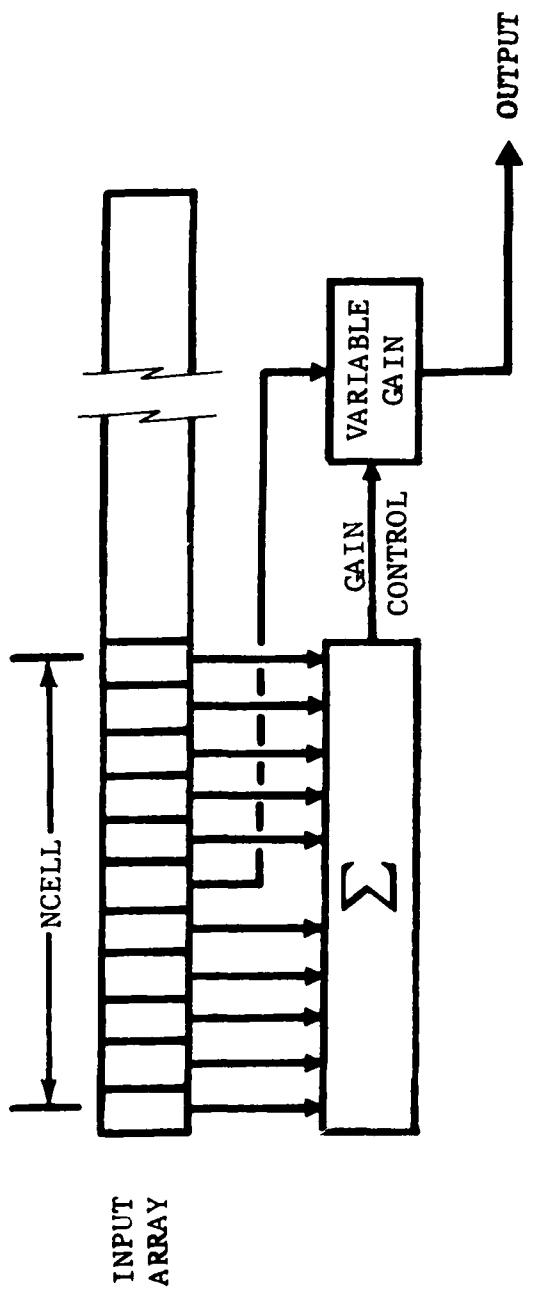


Figure DCFAR-1 BLOCK DIAGRAM OF DCFAR

```

2515      SUBROUTINE OCFAK(IN,IOUT)
2516      COMMON/CLK1/ ICK(200)
2517      DIMENSION IN(1),IOUT(1)
2518      CALL VALLEN(ICK(170), NCELL)
2519      DATA N193,N194,N195,N196/-3,-2,-1,0/
2520      NCELLZ=NCELL/2
2521      NCELLX=NCELL*
2522      NCELLY=N193
2523      NCELLZ=NCELLZ
2524      IAV=0
2525      DO 100 J=1,NCELLZ
2526      IAV=IAV+IN(J)
2527      100 CONTINUE
2528      NCELLZ=NCELLZ+1
2529      DO 200 J=1,NPTS
2530      IF(J.LE.NSTOP) IAV=IAV+IAVS(IN(J+NCELLZ))
2531      IF(J.GT.NCELLZ) IAV=IAV-IAVS(IN(J-NCELLZ))
2532      IUF=IAV-IAVS(IN(J))
2533      IF (IUF.EQ.0) ICF=1
2534      IF (IUF.GT.0) ICF=1
2535      200 CONTINUE
2536      IOUT(N193)=IN(N193)
2537      IOUT(N194)=IN(N194)
2538      IOUT(N195)=IN(N195)
2539      IOUT(N196)=IN(N196)
2540      RETURN
2541      END

```

SUBROUTINE DFT

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
DFT	LTI-2	201
DFTFØ	LTI-2	234
DFTRF	LTI-2	233
DFTNCL	LTI-2S	None

2. PURPOSE:

This subroutine computes the finite discrete Fourier transform of a sequence of δ -functions.

3. INPUT PARAMETERS:

Name	O/R	T	Description
SIMFØ	O	F	Center frequency of discrete output spectrum (DFTFØ only)
FI	R	F	Frequency increment between samples of the output spectrum
FEXT	R	F	Width of output spectrum
NIMP	R	I	Number of δ -functions to be transformed
IDMP	R	I	Diagnostic data dump parameter = 0; no diagnostic data = 1; dump internal parameters: PS, DELPS, NPTS, NIMP, DIN = 2; dump output spectrum: PS, DELPS, NPTS, NIMP, DIN
FØ	O	F	Center frequency of discrete output spectrum (DFTRF only)
INORM	R	I	Normalization Flag = 0; $f_N = TI$ = 1; $f_N = 1.0/NIMP$ = 2; $f_N = TI$ = 3; $f_N = 1.0/NIMP$ = 4; $f_N = 1.0$

Name	O/R	T	Description
TI	O	F	Time increment between simulated waveform samples. Used in this subroutine for normalization only (required only if INORM = 0 or 2)
DIN	R	F	Array containing the parameters of the δ -functions. The specification for the Jth δ -function is the following: DIN(1,J) = phase angle DIN(2,J) = time of occurrence DIN(3,J) = amplitude

4. CALLING SEQUENCES:

Video spectrum

CALL DFT (X,Y)

Where: X contains the Output Waveform - R

Y contains the Output Waveform - I

The range of the independent variable, f, used in computing the spectrum is:

$$-\frac{FEXT}{2} \leq f < \frac{FEXT}{2}$$

IF spectrum

CALL DFTFØ (X,Y)

Where: X contains the Output Waveform - R

Y contains the Output Waveform - I

The range of the independent variable, f, used in computing the spectrum is:

$$SIMFØ - \frac{FEXT}{2} \leq f < SIMFØ + \frac{FEXT}{2}$$

RF spectrum

CALL DFTRF (X,Y)

where: X contains the Output Waveform - R

Y contains the Output Waveform - I

The range of the independent variable, f, used in computing the spectrum is:

$$F\emptyset - \frac{FEXT}{2} \leq f < F\emptyset + \frac{FEXT}{2}$$

Transform additional sample

CALL DFTNCL (X,Y)

Where: X contains the Input Waveform - R

Y contains the Input Waveform - I

X contains the Output Waveform - R

Y contains the Output Waveform - I

The computed spectrum is added to the spectrum contained in arrays X and Y. The range of the independent variable is determined by the previous execution of DFT, DFTF \emptyset , or DFTRF.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. This subroutine is quite time consuming and therefore should be used only when necessary. For most applications the AFFT subroutine which uses the Fast Fourier Transform algorithm should be used. The execution time for this subroutine can be estimated using the following expression

$$\frac{FEXT}{FI} \times NIMP \times 50 \mu S$$

- b. This subroutine is used normally in conjunction with other subroutines such as PHDEC and CGEN.
- c. The output spectrum has a center frequency of zero, i.e. it is the low pass equivalent.
- d. Flow Chart: Page 9-142
- e. Cross Reference Table: Page 9-226
- f. DFT lets user generate 100 delays to be considered.

6. THEORY OF OPERATION

The Fourier transform of a sequence of samples represented by S-functions is given by the following expression:

$$S(f) = F_N \int_{-\infty}^{\infty} \left[\sum_{m=1}^{NIMP} a(m) e^{j\phi(m)} \delta(t-t(m)) \right] e^{-j2\pi ft} dt$$

where: F_N is the normalization factor determined by the flag INORM.

Interchanging the order of integration and summation the following result is obtained:

$$S(f) = F_N \sum_{m=1}^{NIMP} a(m) e^{j\phi(m)} e^{-j2\pi ft(m)}$$

If only K equally spaced samples of $S(f)$ are computed, the following expression results:

$$S_k = S_*(f) \Big|_{f=kFI+f_0} = F_N \sum_{m=1}^{NIMP} a(m) e^{j\phi(m)} e^{-j2\pi kFI t(m)}$$

where: $K = \frac{FEXT}{FI}$ and f_0 is defined in the following manner for each module name:

$$\text{DFT: } f_0 = -\frac{FEXT}{2}$$

$$\text{DFTF}\phi: f_0 = \text{SIMF}\phi - \frac{FEXT}{2}$$

$$\text{DFTRF: } f_0 = F\phi - \frac{FEXT}{2}$$

4-28

```
5697      SUBROUTINE DFT(X,Y)          1650
5698      COMMON/EK1/ EK1(200),BIN(3,100)
5699      EQUIVALENCE (S1MFO,BK1(6)), (F1,BK1(11)), (FFXT,BK1(4)),
5700      *           (NIMP,BK1(200)), (IDMP,BK1(21)), (FU,BK1(5))
5701      *           ,(INCM ,EK1(9)), ( TI ,EK1(12))
5702      DIMENSION X(1) + Y(1)
5703      DATA N193,N194,N195,PI2,D1/-3,-2,-1,6.2831853+2.777777E-03/
5704      FCENT=0.0
5705      GE=10 10
5706      C
5707      ENTRY DFTU(X,Y)
5708      FCNT=S1MFO
5709      GE=10 10
5710      C
5711      ENTRY DFTK(X,Y)
```

06/11/75

INPUT LISTING

AUTOFLOW CHART SET - FNU/SCC KADSIM

CARD NO.

CONTENTS

4-28a

```

3712      FCNT=FO
3713      C
3714      10 CONTINUE
3715      NPTS = 1EIX(FEXT / FI )
3716      NPTS2= NPTS2
3717      NPTS= 2*NPTS2
3718      DO 50 J=1,NPTS
3719      X(J)=0.0
3720      Y(J)=0.0
3721      50 CONTINUE
3722      X(N193)=DOLIN(NPTS)
3723      X(N194)=-FI*FLUAT(NPTS2)
3724      X(N195)=FI
3725      Y(N193)=X(N193)
3726      Y(N194)=X(N194)
3727      Y(N195)=X(N195)
3728      C
3729      ENTRY DFLNCL(X,Y)
3730      IF(IUMP) 60,60,55
3731      60 CONTINUE
3732      WRITE(6,1007) ((DIN(K,J),K=1,3),J=1,NIMP)
3733      1007 FORMAT(1H ,6E15.5)
3734      60 CONTINUE
3735      XN=1
3736      IF(INURM,LW=1,UK=INORM,EW=3) XN=1.0/FLUAT(NIMP)
3737      IF(INURM,EW=4) XN=1.0
3738      DO 200 J=1,NIMP
3739      A=DIN(3,J)*XN
3740      T=DIN(2,J)

```

2050
4-29

2741 P=H001+L001,J1#01
2742 HLEH=21#1
2743 TRAS=1
2744 KNETU=1
2745 KLU=1
2746 C
2747 C CONTINUE
2748 FOF(PH=AH1(FH1)*F12
2749 CLFOF(LLFH=AINT(LEPH))*P12
2750 USE_CUSP1#A
2751 JN= SIN(P1#A
2752 ACBL=CUS(L1E1)
2753 ACBL=L1E1
2754 INT(MPSS) U TC 70
2755 WHITC,2163,2165,NPTS,NIM
2756 ADO FORMAT('I',T,IFL2,6,1) DLEPH,T,PH1,MPSS, NPTS+110,1 NIM
2757 +110)
2758 C CONTINUE
2759 U, 400, L-160,TSC
2760 X(N)=X(N)+CS
2761 Y(E)=Y(E)+DS
2762 LUMPED
2763 CLECPAUL=1+CLECPAUL
2764 CLECPAUL+TEMP*ASDE
2765 FST+DCL
2766 CNT=CONTINUE
2767 C
2768 INT(MPSS) U TC 200
2769 END

C/C/C/C/C	INPUT LISTING	AUTODELW CHART SET - ENCL/SOL RADSIM 4-29A
CARD NO.	*****	CONTENTS

5700	K=NPI5C	
5701	KDELZ=1	
5702	PHE=PHE+DELH	
5703	DELPHE=DELH	
5704	GO TO 71	
5705	ZOB CONTINUE	
5706	C	
5707	TELLME=21 CO,PB,CO	2430
5708	70 CONTINUE	
5709	WRITE(6,1000) (X(M),Y(M), M=1,NETS)	
5710	1000 FORMAT(1000, 0.0000)	
5711	50 CONTINUE	
5712	C	
5713	RETURN	
5714	END	

SUBROUTINE DIGFIL

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
DIGFIL	LTI-4	461
DIGFNC	LTI-4	462
ECMFL	LTI-4	None

2. PURPOSE:

This subroutine is used to simulate a multiple section digital filter.

3. INPUT PARAMETERS:

Name	O/R	T	Description
NP	R	I	Number of 2-delay sections
SF	R	F	Scale factor
FB	O	F	Array containing the feedback coefficients. The coefficients for the Kth section are the following: FB(1,K) = 1-delay feedback coef. FB(2,K) = 2-delay feedback coef.
FF	O	F	Array containing the feed-forward coefficients. The coefficients for the Kth section are the following: FF(1,K) = 0-delay feed-forward coef. FF(2,K) = 1-delay feed-forward coef.

4. CALLING SEQUENCES:

CALL DIGFIL (X,Y)

Where: X contains the Input Waveform - R
Y contains the Input Waveform - I
X contains the Output Waveform - R
Y contains the Output Waveform - I

The storage register arrays (XM and YM) are cleared before execution begins.

CALL DIGFNC (X,Y)

Where: X contains the Input Waveform - R
Y contains the Input Waveform - I
X contains the Output Waveform - R
Y contains the Output Waveform - I

The storage register arrays (XM and YM) are not cleared before execution begins.

CALL ECMFL (X,Y)

Where: X contains the Input Waveform sample - R
Y contains the Input Waveform sample - I
X contains the Output Waveform sample - R
Y contains the Output Waveform sample - I

One complex sample processed for each execution of the module.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. Flow Chart: Page 9-101
- b. Cross Reference Table: Page 9-221

6. THEORY OF OPERATION

The block diagram of one section of the digital filter simulated by this module is shown in Figure DIGFIL-1. The Z-plane transfer function for this section is given by the following expression:

$$T_K(z) = FF(1,K) \frac{z^2 + \frac{FF(2,K)}{FF(1,K)} z + \frac{1}{FF(1,K)}}{z^2 - FB(1,K) z - FB(2,K)}$$

The Z-plane transfer function for the complete filter is given by the following expression:

$$T(z) = SF \prod_{K=1}^{K=NP} T_K(z)$$

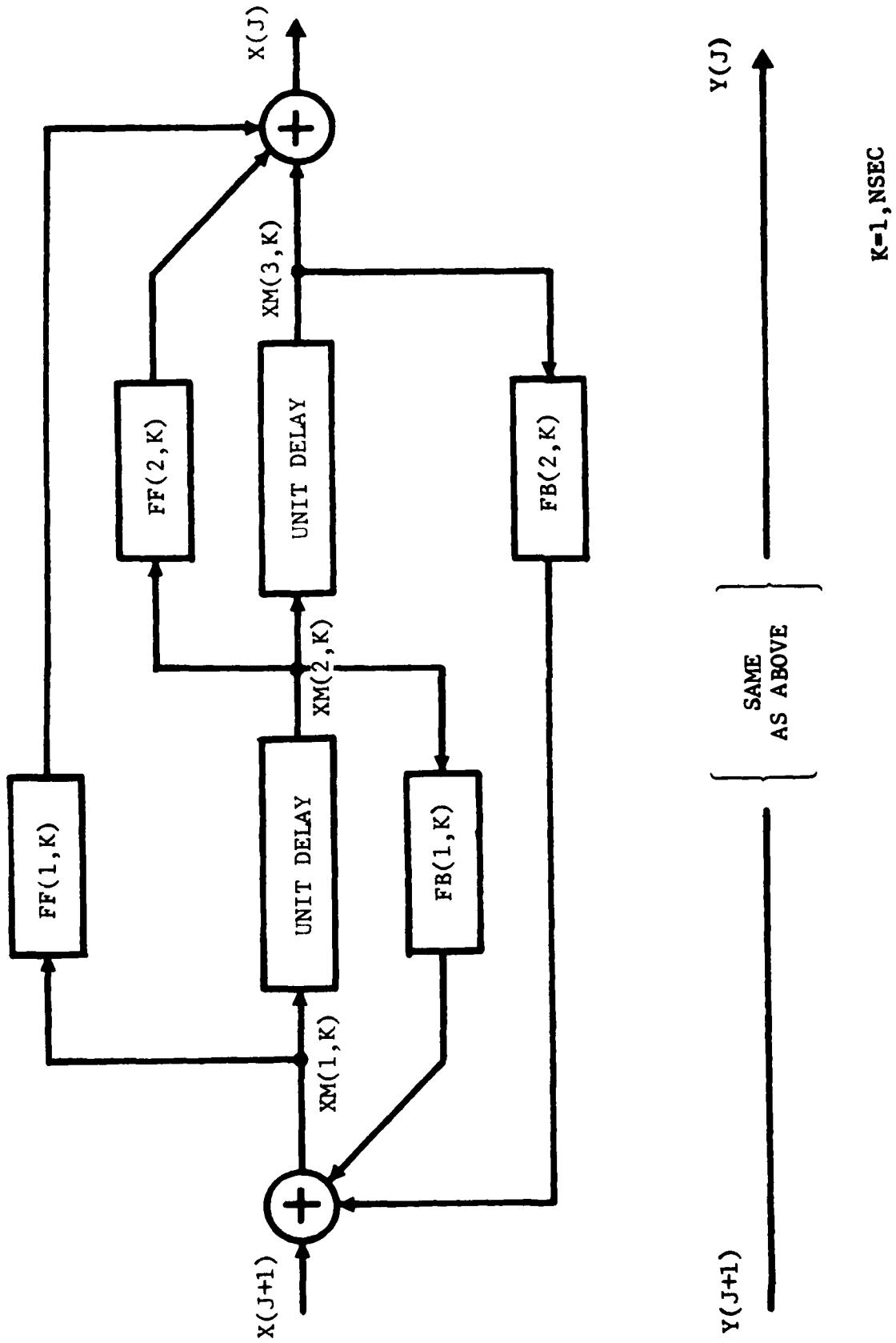


Figure DIGFIL-1 BLOCK DIAGRAM OF DIGFIL/DIGFNC

```

2644      SUBROUTINE DIGFILE(X,Y)
2645      COMMON/BLK1/ BK1(200),FB(2,25),FF(2,25)
2646      EQUIVALENCE (BK1(194), NP ), (BK1( 74), SF )
2647      DATA N193/-3/
2648      DIMENSION X(1),Y(1),XM(3,25),YM(3,25)
2649      DO 100 J=1,25
2700      DO 100 K=1,3
2701      XM(K,J)=0.0
2702      YM(K,J)=0.0
2703      100  CONTINUE
2704      ENTRY DIGFILE(X,Y)
2705      N=ALOLEX(N193))
2706      GOTO 150
2707      ENTRY LCMPL(X,Y)
2708      I=1
2709      150  DO 200 J=1,N
2710      XX=X(J)
2711      YY=Y(J)
2712      DO 300 K=1,NP
2713      XM(1,K)=XM(2,K)*FB(1,K)+XM(3,K)*FB(2,K)+XX
2714      YM(1,K)=YM(2,K)*FB(1,K)+YM(3,K)*FB(2,K)+YY
2715      XX=XM(1,K)*FF(1,K)+XM(2,K)*FF(2,K)+XM(3,K)
2716      YY=YM(1,K)*FF(1,K)+YM(2,K)*FF(2,K)+YM(3,K)
2717      XM(3,K)=XM(2,K)
2718      XM(2,K)=XM(1,K)
2719      YM(3,K)=YM(2,K)
2720      YM(2,K)=YM(1,K)
2721      300  CONTINUE
2722      X(J)=XX*SF
2723      Y(J)=YY*SF
2724      400  CONTINUE
2725      RETURN
2726      END

```

SUBROUTINE DIGFSF

1. MODULE IDENTIFICATION:

<u>Name</u>	<u>Classification Code</u>	<u>Reference Number</u>
DIGFSF	LTI-4	463
ECMFSU	LTI-4	None
ECMFSF	LTI-4	None

2. PURPOSE:

This subroutine is used to simulate a digital filter based on the frequency sampling design concept.

3. INPUT PARAMETERS:

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
RADIUS	R	F	Radius of circle in Z-plane which is locus of pole/zero locations
NSAM	R	I	Number of frequency samples used to specify the transfer function
NDFZ	R	I	Number of zeros synthesized
FSAM	R	F	Array containing the filter transfer function specification. The coefficients for the Kth sample are the following:

FSAM (1,K) = real coefficient
 FSAM (2,K) = imaginary coefficient

The frequency associated with the Kth sample is given by the following expression.

$$f_K = \frac{f_s}{NDFZ} (K-NDC) \quad K = 1, NSAM$$

where: NDC = IFIX (NSAM/2) + 1

f_s = Sampling rate of data to be processed

4. CALLING SEQUENCES:

Process a waveform

CALL DIGFSF (X,Y)

Where: X contains the Input Waveform - R
Y contains the Input Waveform - I
X contains the Output Waveform - R
Y contains the Output Waveform - I

The storage register arrays (S and PF) are cleared before execution begins.

Set up for use by ECM module

CALL ECMFSU (X,Y)

Where: X contains the Input Waveform sample - R
Y contains the Input Waveform sample - I
X contains the Output Waveform sample - R
Y contains the Output Waveform sample - I

The storage register arrays (S and PF) are cleared and coefficients are initialized.

Process 1 sample (called by ECM module)

CALL ECMFSF (X,Y)

Where: X contains the Input Waveform sample - R
Y contains the Input Waveform sample - I
X contains the Output Waveform sample - R
Y contains the Output Waveform sample - I

The storage register arrays (S and PF) are not cleared before execution begins.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. This subroutine is structured to simulate a low pass digital filter only.

b. References:

C. M. Rader and B. Gold: "Digital Filter Design Techniques in the Frequency Domain", Proc. IEEE, Vol. 55, pp 149-171, Feb. 1967.

L. R. Rabiner, B. Gold, and C. A. McGonegal: "An Approach to the Approximation Problem for Nonrecursive Digital Filters", IEEE Trans. Audio Electroacoust., Vol. AU-18, pp 83-106, June 1970.

L. R. Rabiner and B. Gold: Theory and Application of Digital Signal Processing, Prentice-Hall, Inc., Englewood Cliffs, N. J., 1975, pp 105-123.

c. Flow Chart: Page 9-107

d. Cross Reference Table: Page 9-222.

6. THEORY OF OPERATION

The basic concept of this filter design technique is as follows. A comb filter is used to synthesize N zeros around a circle of radius R in the Z-plane. The banks of parallel resonators are placed in cascade with the comb filter. The resonators are chosen such that once the desired passband region their poles exactly cancel the zeros. The weight applied to the resonators are samples of the desired frequency domain transfer function.

The block diagram of the digital filter simulated by the subroutine is shown in Figure DIGFSF-1. Since the phases at resonance of the consecutive resonators differ by π , a phase adjustment is inserted after each resonator. The location of the zeros synthesized by the comb filter are shown in Figure DIGFSF-2. The block diagram of a typical complex resonator is shown in Figure DIGFSF-3.

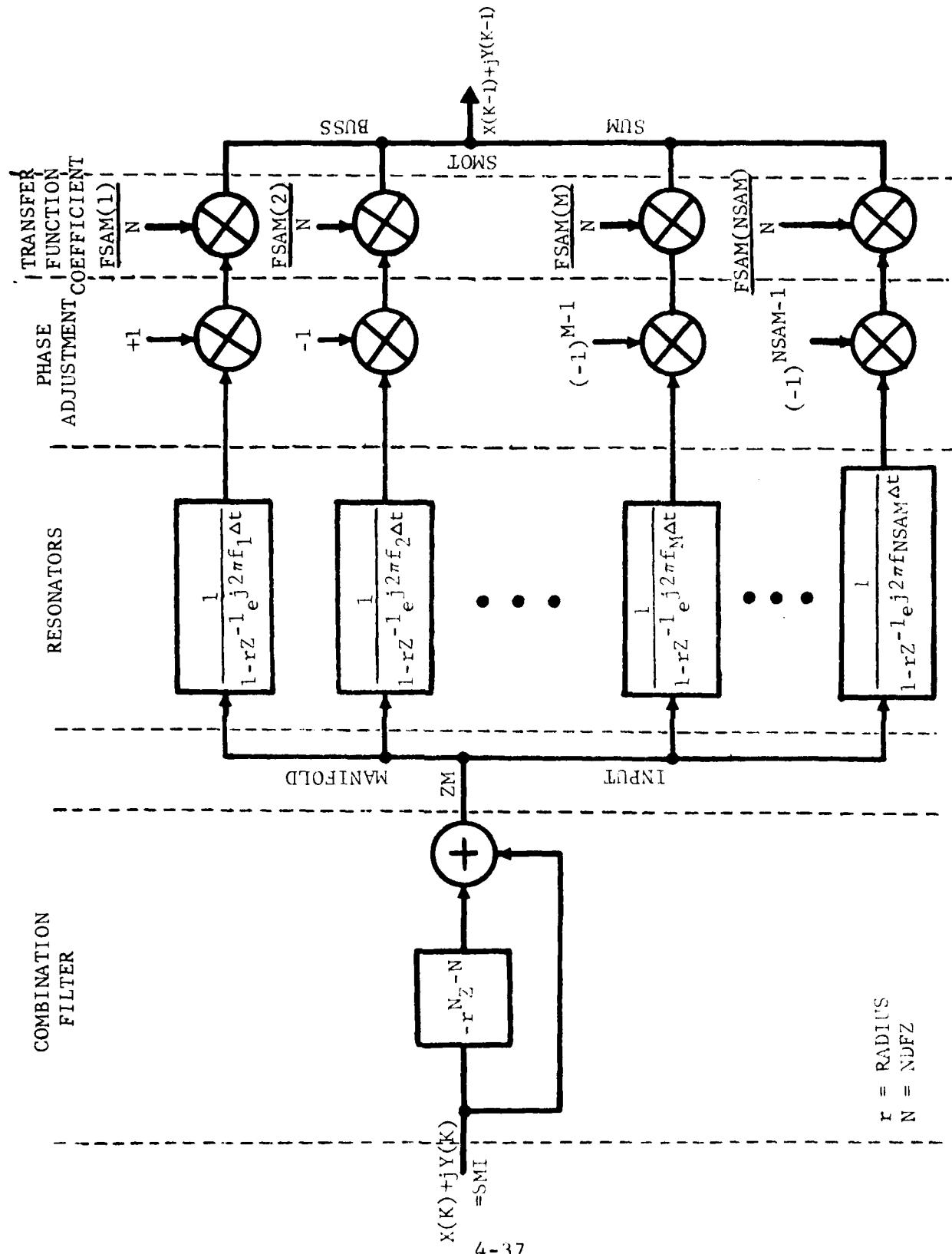


Figure DIGFSF-1 BLOCK DIAGRAM OF DIGFSF

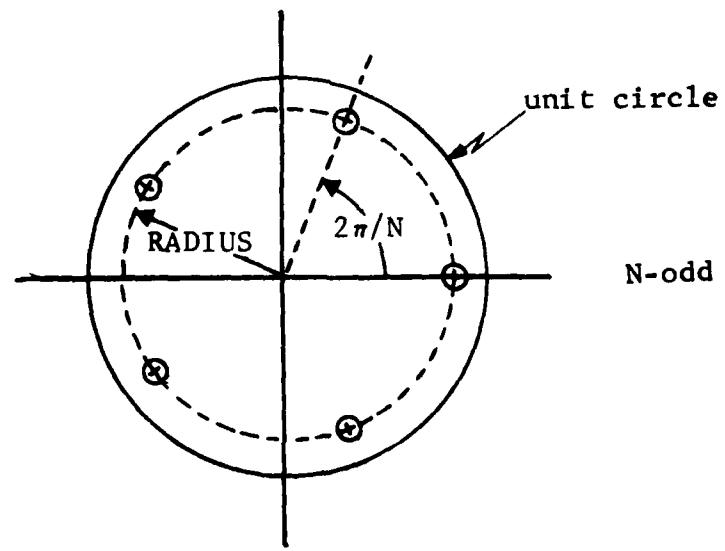
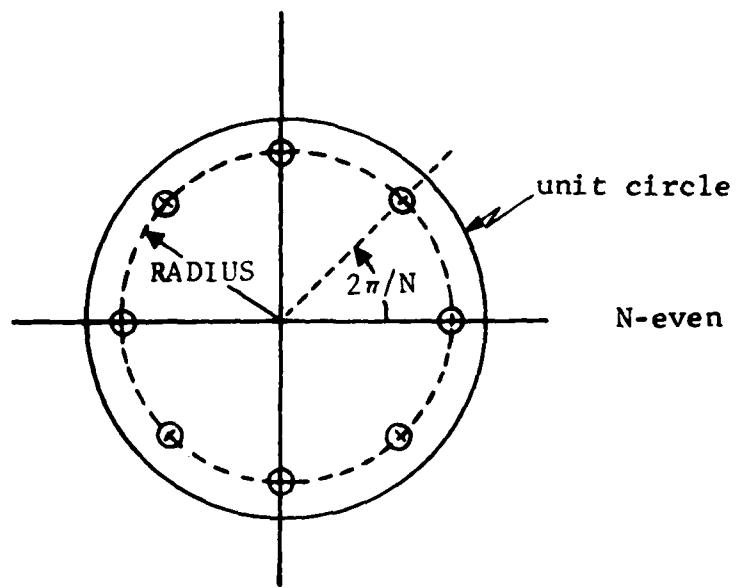
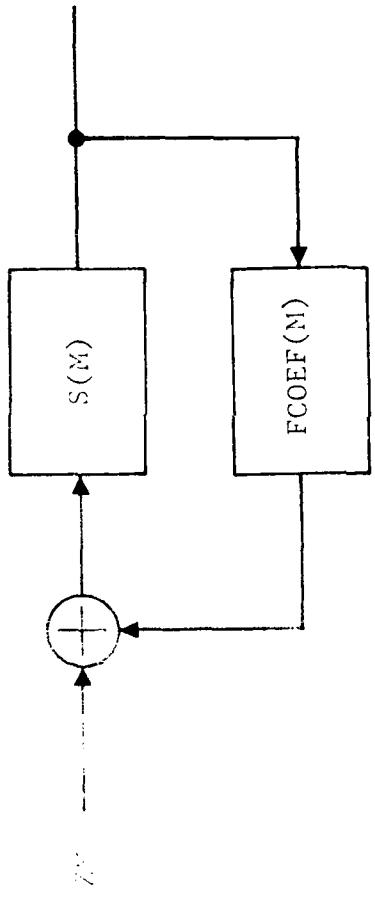


Figure DIGFSF-2 COMBINATION FILTER ZERO LOCATIONS IN THE Z-PLANE



where: $FCOEF(M) = e^{j2\pi f_M \Delta t}$

$$f_M = f_S (M - NDC) / NDFZ$$

Figure DIGFSF-3 BLOCK DIAGRAM OF A COMPLEX RESONATOR

4-40

SCALAR FIELD (X,Y)

4-40

COMPLEX FIELD (X,Y), SAME AS

COMPLEX FIELD (X,Y), FAIRLY EASY

(X,Y) = R₀ e^{iθ}

COMPLEX FIELD (X,Y), SAME AS

COMPLEX FIELD (X,Y), SAME AS

COMPLEX FIELD (X,Y)

DATA IS SAME AS

COMPLEX FIELD (X,Y)

DATA IS

68/11/75

INPUT LISTING

AUTOFLOW CHART SET - FWD/SCL RADSIM

4-40a

CARD NO.

CONTENTS

2842 $F_{CULF}(K) = CMPLX(COS(PH), SIN(PH)) * RADIUS$
 2843 $F_{SAM}(K) = FSAM(K) * DELSC$
 2844 $DELSC = -DELSC$
 2845 $S(K) = LZERD$
 2846 100 CONTINUE
 2847 NUC = NUFZ + 1
 2848 DU 105 K = 1 * NUC
 2849 FF(K) = CZERO
 2850 105 CONTINUE
 2851 DELSC = RADIUS ** NUFZ
 2852 IKP = 1
 2853 ISP = 1
 2854 ENTRY ECMFSF(X,Y)
 2855 DU Z(IU K = 1, NPTS
 2856 IKP = IKP + 1
 2857 SMI = CMPLX(X(K), Y(K))
 2858 FF(1SP) = SMI * DELSC
 2859 LM = SMI - FF(1KP)
 2860 ISP = IKP
 2861 IF (ISP = L) * NUC) IKP = 0
 2862 SMUT = CZERO
 2863 DU MLO M = 1, NSAM
 2864 SMUT = SMUT + S(M) * FSAM(M)
 2865 S(M) = S(M) * FCULF(M) + LM
 2866 100 CONTINUE
 2867 X(K) = REAL(SMUT) * XN1
 2868 Y(K) = AIMAG(SMUT) * XN1
 2869 100 CONTINUE
 2870 END

SUBROUTINE DIGTFL

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
DIGTFL	NL-2	422,423

2. PURPOSE:

This subroutine is used to simulate a digital transversal filter.

3. INPUT PARAMETERS:

Name	O/R	T	Description
NTAPS	R	I	Number of taps
ITAP	R	I	Array containing the tap specifications. The coefficient for the Kth tap are the following: ITAP(1,K) = numerator of tap gain ITAP(2,K) = denominator of tap gain ITAP(3,K) = delay in sampling increments

4. CALLING SEQUENCES:

CALL DIGTFL(IN,IOUT)

Where: IN contains the Input Waveform

IOUT contains the Output Waveform

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. This device is typically used as a digital phase decoder.
- b. Flow Chart: Page 9-95
- c. Cross Reference Table: Page 9-220

6. THEORY OF OPERATION

The block diagram of the digital transversal filter simulated by this module is shown in Figure DIGTFL-1. All calculations performed by this module are in integer format.

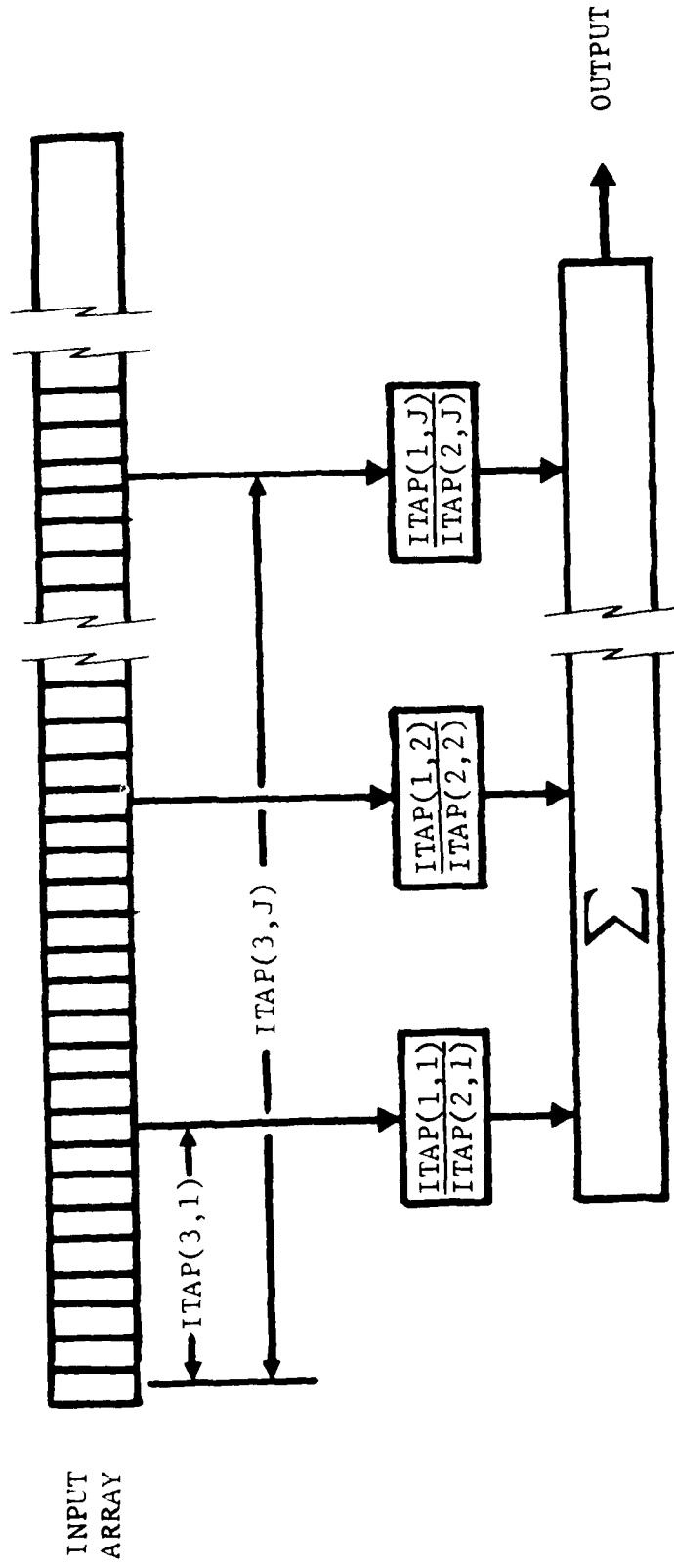


Figure DIGTFL-1 BLOCK DIAGRAM OF DIGTFL.

2542 SUBROUTINE DIGITFL(IN,IOUT) 4-44
 2543 COMMON/BLK1/BK1(200),ITAP(3,100)
 2544 DIMENSION IN(1),ICUT(1)
 2545 EQUIVALENCE (BK1(103),NTAPS)
 2546 DATA N193,N194,N195,N196/-3,-2,-1,0/
 2547 NSTUP=IN(N193)
 2548 NSTLP=NSTUP-ITAP(3,NTAPS)
 2549 DO 100 J=1,NSTUP
 2550 IA=0
 2551 DO 200 K=1,NTAPS

08/22/75 INPUT LISTING AUTOFLOW CHART SET - FWD/SCL RADSIM

CARTRIDGE NO.	*****	CONTENTS	*****
2552		IA=IA+ (ITAP(1,K)* IN(J+ITAP(3,K))) / ITAP(2,K)	
2553		100 CONTINUE	
2554		ICUT(J)=IA	
2555		100 CONTINUE	
2556		ICUT(N193)=NSTUP	
2557		ICUT(N194)=IN(N194)	
2558		ICUT(N195)=IN(N195)	
2559		RETURN	
2560		END	

SUBROUTINE ECM

1. MODULE IDENTIFICATION:

<u>Name</u>	<u>Classification Code</u>	<u>Reference Number</u>
ECM	SOU-1S	512

2. PURPOSE:

This subroutine simulates a noise modulation jammer.

3. INPUT PARAMETERS:

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
TIME	R	F	Elapsed time since beginning of simulation
JRNGØ	0	F	True jammer range corresponding to TIME = 0.0
JRSIM	R	F	Jammer range to be used in computing the starting time of the jammer.
JMAZ	R	F	Jammer azimuth angle
JHGT	0	F	Jammer height above ground
JERP	R	F	Jammer effective radiated power
JFMBW	0	F	Jammer swept bandwidth
JPW	0	F	Jammer on time for pulsed jammers
JFØ	0	F	Jammer center frequency offset from radar center frequency
JVEL	0	F	Jammer radial velocity with respect to the radar site
JPERØD	0	F	Jammer pulse repetition interval for pulsed jammer

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
N2	R	I	2^{**N2} = total number of signal storage array elements available
NDFZ	R	I	Number of zeros to be synthesized by the frequency sampling digital filter (DIGFSF).

In addition to the above parameters the characteristics of the jammer spectrum must be specified via the parameters of DIGFSF. These parameters are also members of NLS12.

4. CALLING SEQUENCES:

CALL ECM (X, Y)

Where:
 X contains the Input Waveform - R
 Y contains the Input Waveform - I
 X contains the Output Waveform - R
 Y contains the Output Waveform - I

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. The digital filter routine DIGFSF is used to specify the spectral characteristics of the jammer.
- b. Flow Chart: Page 9-104
- c. Cross Reference Table: Page 9-221

6. THEORY OF OPERATION

This module has four modes of operation:

- (1) Spot noise/Barrage noise

JPW = 0.0

- (2) Swept noise (single sweep)

JFMBW ≠ 0.0

JPW ≠ 0.0

JPEROD = 0.0

(3) Swept noise (repeating sweep)

JFMBW \neq 0.0
JPW \neq 0.0
JPEROD = JPW

(4) Pulsed noise

JPW \neq 0.0
JPEROD > JPW

Dependeing on the range and azimuth positioning of the jammer with respect to the target either a self screening or a standoff jammer can be simulated.

A block diagram of this module is shown in figure ECM-1. The output of the ECM simulation is summed with the data in arrays X and Y.

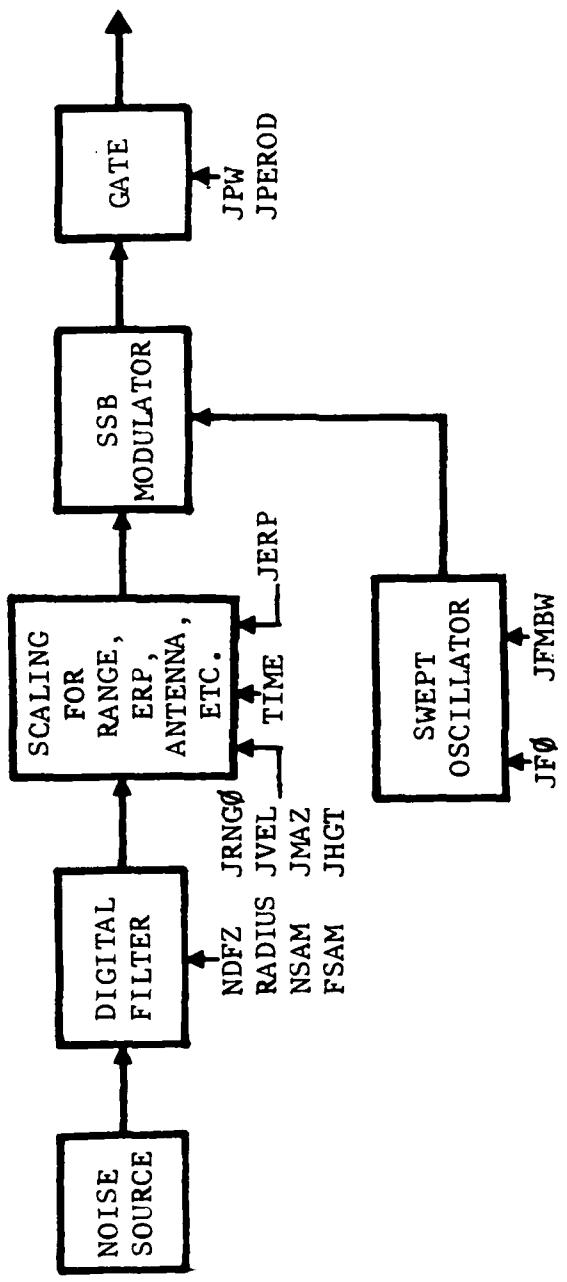


Figure ECM-1 BLOCK DIAGRAM OF ECM

This model is incomplete since the TWT does not produce saturated noise and the output of this model is not properly scaled for range effects. This will be accomplished in the near future.

ORIGINATOR	INPUT LISTING	AUTOFLOW CHART SET - FWC/SCL RADSIM 4-50 ****
CARD NO.	*****	CONTENTS
2704	200 JBG=IFIX(JSTART/DELT)	
2705	IF(JBG.LT.1) JBG=1	
2706	JST=IFIX(JPW/DELT)+JBG	
2707	IF(JST.GT.NTTL) JST=NTTL	
2708	FSTRT=JFO-JFMW*0.5	
2709	CHIRPZ=JFMW/JPW*0.5	
2710	IF(JPERED.EQ.0.0) GOTO 300	
2711	NHFT=2	
2712	IF(JPERED.GT.JPW) GOTO 240	
2713	JCTOFF= 1	
2714	IF TL = 200	
2715	JCTOFF=IFIX((JPERED-JFW)/DELT)+1	
2716	200 IF(NFTS.GE.NTTL) GOTO 310	
2717	HFMFT=1	
2718	DO 301 JAK,NNTTL	
2719	X(J)=0.0	
2720	Y(J)=0.0	
2721	201 CONTINUE	
2004	X(N142)=TLL(N142)	
2005	Y(N143)=X(N142)	
2006	10 T=0.0	
2007	10 DO J=1,JST	
2008	IF(J.EQ.1) JAK=NFTS	
2009	IF(J.EQ.1) JAK=NFTS	
2010	CALL COMED(XF*YR)	
2011	PRF=(XF*T)+(CHIRPZ*T)*T	
2012	RF=(AMPLI*PRF)+RF12	
2013	XF=COMED(RF)	
2014	YR=1.0	
2015	X(J)=XF*YR+X(J)	
2016	Y(J)=YR*(XF*YR+X(J))	
2017	T=T+DEL	
2018	200 CONTINUE	
2019	IF(NFTS.GE.NTTL) RETURN	
2020	DO=JAK+1,JAK+JFW-1	
2021	IF(JAK.GT.NTTL) JAK=NTTL	
2022	IF TL = 10	
2023	END	

SUBROUTINE FGENXY

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
FGENXY	SOU-1 or LTI-3	420
FGENMP	SOU-1 or LTI-3	421

2. PURPOSE:

This subroutine is used to simulate the radar waveform generator. In general, the waveform generator subsystem in a radar drives the power amplifier.

3. INPUT PARAMETERS

a. MODE #1; single pulse, internal modulation

Name	O/R	T	Description
FS	R	F	Simulation sampling rate
FØ	R	F	Center frequency of output waveform
INORM	R	I	Normalization flag
TI	R	F	Time increment between output waveform samples
NPWTX	R	I	Set = 0 for this mode
FMBW	O	F	Linear FM bandwidth
NSUBP	R	I	Set = 0 for this mode
RISTIM	O	F	Rise Time
FALTIM	O	F	Fall Time
TSTART	O	F	Start time of the output waveform
PW	R	F	Pulsewidth

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
VPEAK	R	F	Peak output voltage
N2	R	I	Simulation parameter used to specify maximum array length

Figure FGENXY-1(a) shows the relationship between some of the input parameters and the output waveform.

- b. MODE #2; single pulse, User modulation function

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
FS	R	F	Simulation sampling rate
F \emptyset	O	F	Center frequency of output waveform
INORM	R	I	Normalization flag
TI	R	F	Time increment between output waveform samples
NPWTX	R	I	Number of points in user specified modulation function
WT	R	F	Array containing the user specified modulation function. The specification for the Jth sample of the weighting function is the following: WT(1,J) = Gain WT(2,J) = Time WT(3,J) = Phase angle
NSUBP	R	I	Set = 0 for this mode
FSTART	O	F	Starting frequency at time = TSTART
CHIRP	O	F	Linear FM sweep rate
TSTART	O	F	Start time of the output waveform

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
VPEAK	R	F	Peak output voltage
N2	R	I	Simulation parameter used to specify maximum array length

NOTE: Either F0 or FSTART & FMBW must be specified.

Figure FGENXY-1(b) shows the relationship between some of the input parameters and the output waveform.

c. MODE #3; phase coded waveform

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
FS	R	F	Simulation sampling rate
FØ	O	F	Center frequency of output waveform
INORM	R	I	Normalization flag
TI	R	F	Time increment between output waveform samples
NPWTX	R	I	Set = 0 for this mode
NSUBP	R	I	Number of subpulses
SPW			Subpulse width
PCODE	R	F	Array containing the phase code
SWTIM	O	F	Switching time between subpulses
RISTIM	O	F	Rise time
FALTIM	O	F	Fall time
FSTART	O	F	Starting frequency at time = TSTART
CHIRP	O	F	Linear FM sweep rate
TSTART	O	F	Start time of the output waveform

<u>Time</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
VPEAK	R	F	Peak output waveform
N2	R	I	Simulation parameter used to specify maximum array length

NOTE: Either F0 or FSTART & FMBW must be specified.

Figure FGENXY-1(c) shows the relationship between some of the input parameters and the output waveform.

4. CALLING SEQUENCES:

CALL FGENXY (X,Y)

Where: X contains the Output Waveform - R
Y contains the Output Waveform - I

CALL FGENMP (X,Y)

Where: X contains the Output Waveform - M
Y contains the Output Waveform - P

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. The number of waveform samples to be generated must be less than $2^{**}N2$ where $N2 \leq 13$.
- b. The normalization flag, INORM, is used to indicate whether the output is to be interpreted as a matched filter impulse response or as a frequency generator output waveform.

If INORM = 0, 2 or 4 the output represents a frequency generator output.

If INORM = 1 or 3 the output represents the impulse response of an ideal matched filter and therefore TSTART is set equal to zero and no trailing zeros are added to the output. This procedure is required because the normalization procedure used in the Fourier transform routine is different for waveforms and impulse responses.

- c. For Mode #3 the sign of NSUBP indicates whether a polyphase or binary phase code is to be generated.

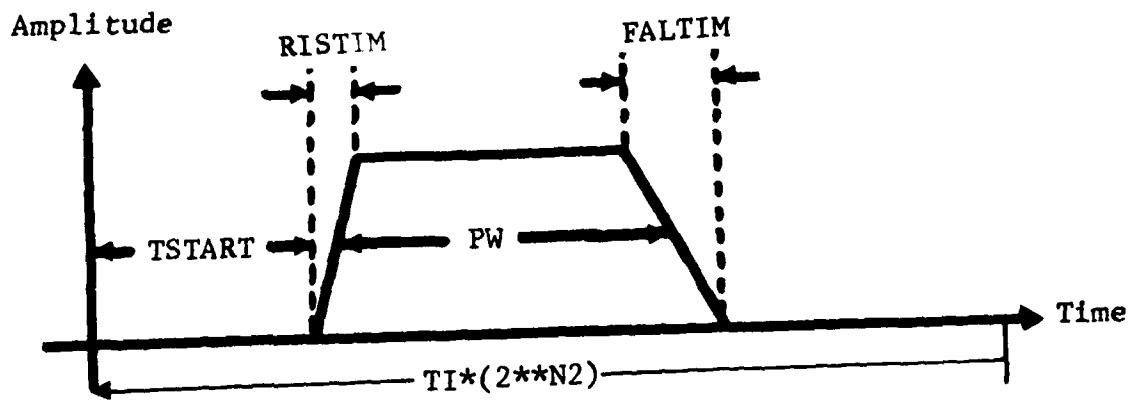


Figure FGENXY-1a OUTPUT WAVEFORM ENVELOPE - MODE 1

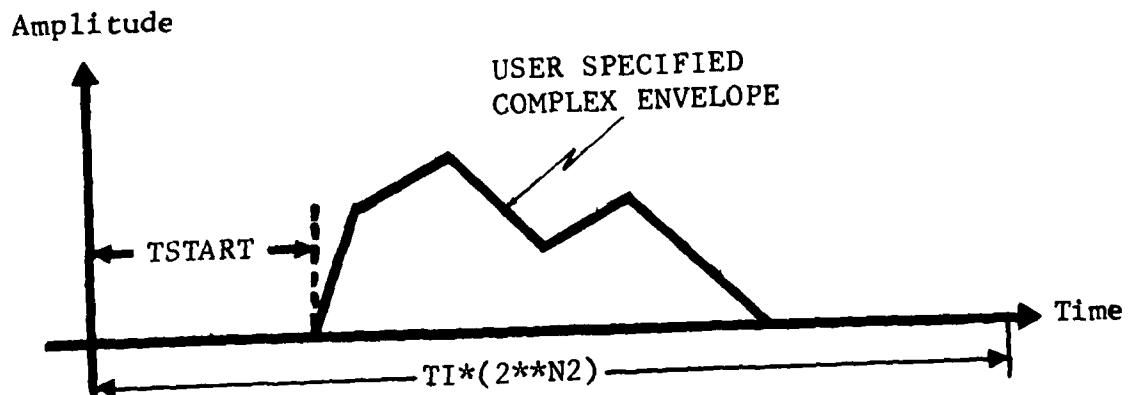


Figure FGENXY-1b OUTPUT WAVEFORM ENVELOPE - MODE 2

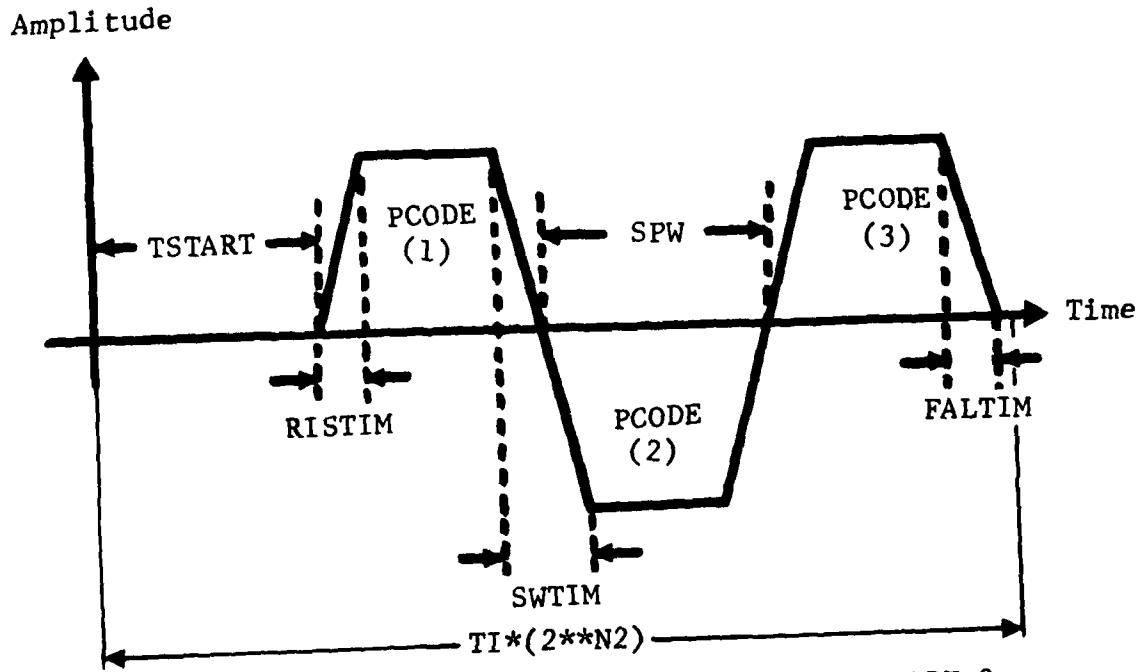


Figure FGENXY-1c OUTPUT WAVEFORM ENVELOPE - MODE 3
4-55

If NSUBP is positive the phase is either 0° or 180° with respect to the carrier. If NSUBP is negative the phase between subpulses is determined by linear interpolation.

- d. Operation of this module in Mode #3 causes the phase code array (PCODE) to be copies into the storage array XMITPC for later use by the phase decoder routine, PHDEC. In this way the phase decoder is automatically slaved to the phase code of the waveform generator.
- e. Abort error codes
 - 1, User attempted to specify both a phase code and a complex envelope
 - 2, User attempted to specify a complex envelope with less than 4 points
 - 3, The time span of the waveform to be generated is greater than the simulation time span, i.e. $TI*(2^{**N2})$.
 - 104, An error occurred during execution of the weighting function routine, WEITCP or WEITMP.
- f. Flow Chart: Page 9-72
- g. Cross Reference Table: Page 9-217.

6. THEORY OF OPERATION

This simulation is used to simulate the master frequency source of a radar system. The basic mechanization equation is given by the following expression:

$$S(t) = a(t) \exp[j(2\pi f_0 t + \theta(t))]$$

The envelope $a(t)$ and the phase modulation term $\theta(t)$ are determined either directly by the user (MODE #2) or indirectly through parameters (MODE #1 or #2).

This module can also handle a staggered PRF by specifying NPRIS and PRI(J) in the system module (301) namelist. NPRIS is the number of pulse repetitions and must be ≤ 11 . PRI(J) are the intervals in seconds of the pulses. For example, under \$NL301 might be included "..., NPRIS = 4, PRI = 1.0, 0.9, 1.1, 1.0\$."

2074 SUBROUTINE FGENXY(X,Y) 4-57
2075 COMMON/BLK1/ VAR(200), WT(3,100)
2076 COMMON/PHCLUE/ XMITFC(302)
2077 DIMENSION PCCLUE(300),X(1),Y(1)
2078 EQUIVALENCE (WT(1,1),PCCLUE(1))
2079 EQUIVALENCE (VAR(2),FS - 1), (VAR(3),FL - 1),
2080 * (VAR(4), INCRM - 1),
2081 * (VAR(12),TZ - 1), (VAR(37),NPWT - 1),
2082 * (VAR(38), ORIG - 1), (VAR(42), CHIFF - 1),
2083 * (VAR(43), FMRW - 1), (VAR(44),NPWTX - 1),
2084 * (VAR(45), SPW - 1), (VAR(46), NSUBP - 1),
2085 * (VAR(47), SWTIM - 1), (VAR(48), RISTIM),
2086 * (VAR(49), FALTIM), (VAR(100), TSTARTT),
2087 * (VAR(41), FSTARTT), (VAR(40), PW - 1),

02/11/70

INPUT LISTING

AUTOFLOW CHART SET - FWD/SCL RAUSIM

LARU NO.

CONTENTS

H-57a *****

2000 * (VAR124) + VPEAK) + (VAR1 1) , N2)
 2004 DATA N143,N144,N145,DTR/-3,-2,-1,1.7453292E-02/
 2008 DATA XLINK/2.7777E-03/,PI2/6.2831853/
 2012 JTYPE=2
 2016 GCTL 100
 2020 ENTRY PGEMMP(X,Y)
 2024 JTYPE=2
 2028 100 JPNM=0
 2032 IF(NSUBT,0,0) GOTO 210
 2036 NSUBP=-NSUBR
 2040 JPNM=1
 2044 210 IF(LCHINP,0,0,0) FSTART=FC
 2048 NTTL=2**N2
 2052 IF(NSUBT,0,0,0) GOTO 200
 2056 IF(NFRTX,0,0,0) CALL ABORT(1)
 2060 LUEPMP=PCULL(1)
 2064 XMJFL(1,0,1)=BELLNSUBP
 2068 XMJFL(3,0,1)=SPW
 2072 UC 300 J=1,NSLPK
 2076 XMJFL(J)=PCULL(J)
 2080 300 LCONTINUE
 2084 UC TL 000
 2100 70 LCONTINUE
 2111 IF(NPWTX,0,0,0) GOTO 300
 2115 IF(NPWTX,LT,4) CALL ABORT(2)
 2119 SPW=NT(2,NFRTX)
 2123 FSTIM=74
 2127 HALTIM=73
 2131 CLTL 400

```

2118      SPW=PW+(K1STIM+FALTIM)*0.5
2119      IF (CHIRP.EQ.0.0) CHIRP=FMFW/PW
2120      FSTART=FL-CHIRP*(PW+K1STIM)*0.5
2121      400  CONTINUE
2122      SUBPH=0.0
2123      NSUBPH=1
2124      SWT1M=K1STIM+FALTIM
2125      600  NSTKT=0
2126      IF (INUMR.EQ.1.0R.INUMR.EQ.3) GOTO 651
2127      NSTKT=1+IX(1$START*FS)
2128      TSTART=T1+FLAT(NSTRT)
2129      NSTKT=NSTKT+1
2130      DO 650 J=1,NSTKT
2131      X(J)=0.0
2132      Y(J)=0.0
2133      650  CONTINUE
2134      651  NS=1+IX( FLAT(NSUBPH)*SPW*FS )+NSTKT
2135      IF (NS.GT.NTIL) CALL ABORT(3)
2136      TIME=0.0
2137      K=1
2138      J=NSTRT
2139      *
2140      ***** LEAVING EDGE OF XMITTED WAVEFORM *****
2141      *
2142      IRLO=0
2143      ASLOPE=VPEAK/K1STIM
2144      IF (IPHM.EQ.0) ASLOPE=ASLOPE*CLS(SUBPH*UTK)
2145      PSLOPE=0.0

```

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06/11/75

INPUT LISTING

AUTOFLOW CHART SET - FNU/SCL RAUSIM

CARD NO.	*****	CONTENTS
2146		TOKIG=0.0
2147		PKIG=SULPH
2148		ALKIG=0.0
2149		:BREAK=K1STIM
2150	700	J=J+1
2151		TIME=TIME+TI
2152	800	IF (TIME.GE.BREAK) GOTO 400
2153		DTIM=TIME-TOKIG
2154		PH=(FSTART+CHIRP*0.5*TIME) * TIME
2155		IF (1PHM.EQ.1) PH=PH+(PKIG+PSLCF*DTIM)*XCFC
2156		AMPL=ALRIG + ASLLEP*DTIM
2157	800	IF (1YR.EQ.1) GOTO 870
2158		X(J)=AMPL
2159		Y(J)=PH*300.0
2160		GOTO 700
2161	700	PHAS=(PH-PI)/AT(1#IX(PH))*PIZ
2162		X(J)=AMPL*COS(PHAS)
2163		Y(J)=AMPL*SIN(PHAS)
2164		GOTO 700
2165	400	IF EG=1#E0+1
2166		TOKIG=BREAK
2167		IF (1EG.EQ.1) GOTO 410
2168		IF (1EG.EQ.4) GOTO 1000
2169		IF (1EG.EQ.3) GOTO 920
2170		1KLG=1#E0-2
2171	*	
2172	*****	TOP OF SUBPULSE *****
2173	*	
2174	410	BREAK=BREAK+SPW-SNTIM

4-580 *****

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2170 PULSE=0.0
2171 PULSE-SUEPH
2172 ASLOPE=0.0
2173 ALKIC=VPLAK
2174 IF(SUEPH<0.0) ALKIC=VPEAK*CLS(SUEPH+DTR)
2175 GOTO 200
2176 *
2177 ***** SWATCH KLTIN *****
2178 *
2179 V20 K=K+1
2180 IF(K>L) ENDIF GOTO 450
2181 EFLAK=EFLAK+SHTIM
2182 SUEPH=FCOUT(K)
2183 PSLEPF=(SUEPH - PUPIG)/SHTIM
2184 IF(SUEPH<0.0) ASLOPE=(VPEAK*CLS(SUEPH+DTR)-ALKIC)/SHTIM
2185 GOTO 200
2186 *
2187 ***** TRAILING EDGE OF XMITTED WAVEFORM *****
2188 *
2189 V50 EFLAK=FLAK+FALTIM
2190 ALLCFF=-ALF1G/FALTIM
2191 IFEGE=0
2192 GOTO 200
2193 IC00 IF(INCRM>0.1&LK>INRM>0.3) GOTO 1501
2194 DL 1500 K=J,NTL
2195 X(K)=0.0
2196 Y(K)=0.0
2197 1500 LCONTINUE
2198 GOTO 1504

COPIED BY:		INPUT LISTING	AUTOFLOW CHART SET - FWD/SCL RADSIM
			H-59a ****
CARD NO.	*****	CONTENTS	
2204	1501	NITLE=J-1	
2205	1504	X(N195)=S00L(NTITLE)	
2206		X(N194)=S00U	
2207		X(N195)=T1	
2208		Y(N186)=X(N195)	
2209		Y(N186)=X(N194)	
2210		Y(N195)=X(N195)	
2211		IF (NEWTA&NEWX) RETURN	
2212		CLEARDATA	
2213		NEWTA=NEWX	
2214		IF (TYPE=.1) GOTO 1899	
2215		DO 1600 J=1,NEWX	
2216		XM=WT(1,J)	
2217		WT(1,J)=XM*S00L(WT(3,J)*DTK)	
2218		WT(1,J)=AM*S00R(WT(3,J)*DTK)	
2219	1600	CONTINUE	
2220		CALL WRITE(X,Y,1200)	
2221		RETURN	
2222	1899	CALL REVERSE(X,Y,1200)	
2223		RETURN	
2224	1600	CALL WRITE(X,Y,1200)	
2225		RETURN	
2226		END	

SUBROUTINE FILT

1. MODULE IDENTIFICATION:

<u>Name</u>	<u>Classification Code</u>	<u>Reference Number</u>
FILT	LTI-1	407,408

2. PURPOSE:

This subroutine simulates a continuous filter which is defined by an S-domain polynomial transfer function.

3. INPUT PARAMETERS:

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
NZ	R	I	Number of zeros in the transfer function.
NP	R	I	Number of poles in the transfer function.
SF	R	F	Scale factor.
FZERO	O	F	Array containing the zero specifications. The s-plane location for the Kth zero is given by the following coefficients: FZERO(1,K) = real component FZERO(2,K) = imaginary component
FPOLE	O	F	Array containing the pole specifications. The s-plane location for the Kth pole is given by the following coefficients: FPOLE(1,K) = real component FPOLE(2,K) = imaginary component

4. CALLING SEQUENCES:

CALL FILT(X, Y)

Where: X contains the Input Waveform - R

Y contains the Input Waveform - I

X contains the Output Waveform - R

Y contains the Output Waveform - I

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. A purely imaginary pole may not be specified within the frequency extent of the input waveform. This would cause either zero or an extremely small number to occur in the denominator of the transfer function.
- b. Flow Chart: Page 9-55
- c. Cross Reference Table: Page 9-215

6. THEORY OF OPERATION

The S-domain transfer function for a general filter can be represented by the ratio of two polynomials as shown in the following expression

$$H(S) = \frac{(S-Z_1)(S-Z_2)(S-Z_3) \dots (S-Z_{NZ})}{(S-P_1)(S-P_2)(S-P_3) \dots (S-P_{NP})} \cdot SF$$

In general, H(S) is a complex function of the frequency variable s. The filter output signal $S_o(f)$ can be determined using the following expression

$$S_o(f) = H(f) S_i(F)$$

where $S_i(f)$ is the input signal representation in the frequency domain. The discrete representation of these equations used in the module are the following:

$$H(J) = SF \cdot \frac{\prod_{K=1}^{K=NZ} \{ jFREQ(J) - [FZERO(1,K) + jFZERO(2,K)] \}}{\prod_{K=1}^{K=NP} \{ jFREQ(J) - [FPOLE(1,K) + jFPOLE(2,K)] \}}$$
$$X(J) + j Y(J) = H(J) * [X(J) + j Y(J)]$$

where: FREQ(J) is the frequency associated with the Jth sample

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```
1720      SUBROUTINE FILT( X, Y)
1721      CLMMCN/ELK1/ BK1(200),FZERO(2,50),FFOLE(2,50)
1722      EQUIVALENCE ( NZ ,BK1(72)), ( NP ,BK1(73)), ( SF ,BK1(74))
1723      DIMENSION X(1), Y(1)
1724      DATA N143,N144,N145,N146/-3,-2,-1,0/
1725      FREW=X(N144)
1726      N = IBUGL(X(N143))
1727      DELF = X(N145)
1728      IF( SF .EQ. 0. ) SF = 1.0
1729      DO 100 J=1,N
1730      IF(NZ.EQ.0) GO TO 150
1731      DO 200 K=1,NZ
1732      WD = FREW - FZERO(2,K)
1733      A = X(J)
```

CODE/FORMAT	INPUT LISTING	AUTOFLOW CHART SET - FMC/SSL RADSIM
CARD NO.	*****	4-634 *****
		CONTENTS
1740	X(J) = -A * FZERD(I,K) - Y(J) * WD	
1741	Y(J) = A * WD - Y(J) * FZERU(I,K)	
1742	200 CONTINUE	
1743	100 IF(NP.EQ.0) GO TO 300	
1744	DO 250 K=1,NP	
1745	WD = FREQ - FPOLE(2,K)	
1746	A = X(J)	
1747	AA = FPOLE(1,K) * FPOLE(1,K) + WD * WD	
1748	X(J) = (-A * FPOLE(1,K) + Y(J) * WD) / AA	
1749	Y(J) = (-A * WD - Y(J) * FPOLE(1,K)) / AA	
1750	250 CONTINUE	
1751	300 X(J) = X(J) * SF	
1752	Y(J) = Y(J) * SF	
1753	FREQ = FREQ + DELF	
1754	100 CONTINUE	
1755	RETURN	
1756	END	

SUBROUTINE HET

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
HET	LTV-4	-

2. PURPOSE:

This subroutine simulates a single sideband modulator which is used to heterodyne waveforms.

3. INPUT PARAMETERS:

Name	O/R	T	Description
FSHIFT	R	F	Frequency shift to be applied to the input waveform.

4. CALLING SEQUENCE:

CALL HET(X,Y)

where: X contains the Input Waveform - R

Y contains the Input Waveform - I

X contains the Output Waveform - R

Y contains the Output Waveform - I

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA:

a. Flow Chart: Page 9-103

b. Cross Reference Table: Page 9-221

6. THEORY OF OPERATION:

The basic mechanization equation for this module is the following:

$$s'(t) = s(t) \times e^{j FSHIFT \cdot t}$$

or

$$X'(t) + jY'(t) = [X(t) + jY(t)] \cdot [\cos(FSHIFT \cdot t) + j \sin(FSHIFT \cdot t)]$$

The block diagram of a SSB modulator is shown in Figure HET-1.

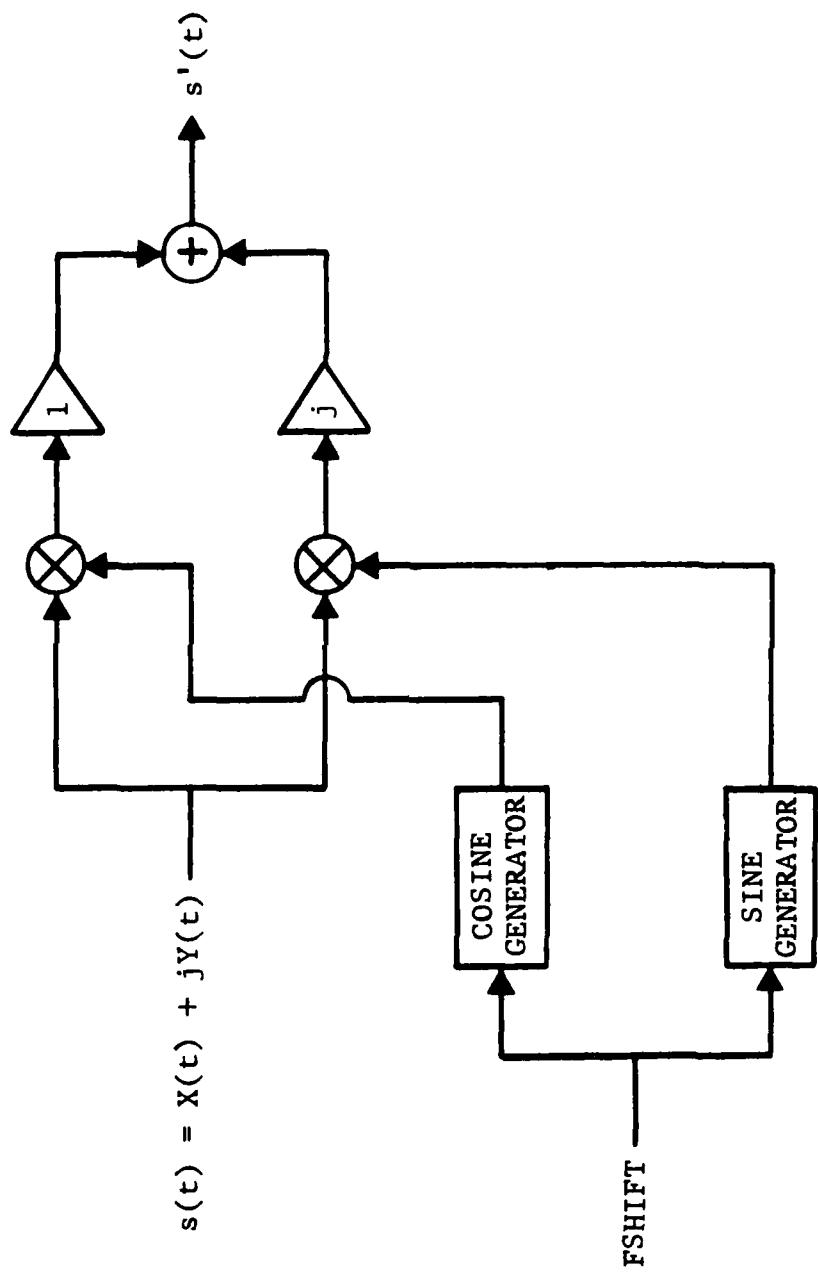


Figure HET-1 BLOCK DIAGRAM OF SSB MODULATOR

```

2707      SUBROUTINE HFT(X,Y)          4-64b
2708      DIMENSION X(1),Y(1)
2709      COMMON/ZHLK1Z/ VAR(500)
2710      EQUIVALENCE (VAR( 15), SHIFT )
2711      DATA N193,N194,N195,N196 /-3,-2,-1, 0/, P1276,.13485/
2712      NETS=VAL(X(N193))
2713      CK = X(N194)
2714      DEL=X(N195)
2715      D100=1.0/NETS
2716      THETA=CK*SHIFT
2717      THETA=(THETA-FLAT)*FIX(THETA))+FL
2718      C=COS(THETA)
2719      S=SIN(THETA)
2720      TMP=X(J)
2721      X(J)= X(J)*C - Y(J)*S
2722      Y(J)= TMP*S + Y(J)*C
2723      CK= CK + DEL
2724      100  CONTINUE
2725      RETURN
2726      END

```

SUBROUTINE HWDET

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
HWDET	NL-1	414,415
FWDET	NL-1	416,417
SQDET	NL-1	418,419
HLIM	NL-1	438,439
IHWDET	NL-1	445,446
IFWDET	NL-1	447,448
ISQDET	NL-1	449,450
IHLIM	NL-1	442,443

2. PURPOSE:

This subroutine simulates a signal detector. Depending on the entry point, a half-wave detector, a full-wave detector, a square-law detector, or a hard limiter is simulated.

3. INPUT PARAMETERS:

NONE

4. CALLING SEQUENCES AND THEORY OF OPERATION

a. Half-Wave Detector

CALL HWDET(XIN,XOUT)

Where: XIN contains the Input Waveform

XOUT contains the Output Waveform

XOUT(J) = XIN(J) ; if XIN(J) > 0.0

= 0.0 ; otherwise

b. Full-Wave Detector

CALL FWDET(XIN,XOUT)

Where: XIN contains the Input Waveform
XOUT contains the Output Waveform
 $XOUT(J) = |XIN(J)|$

c. Square-Law Detector

CALL SQDET(XIN,XOUT)

Where: XIN contains the Input Waveform
XOUT contains the Output Waveform
 $XOUT(J) = XIN(J)*XIN(J)$

d. Hard Limiter

CALL HLIM(XIN,XOUT)

Where: XIN contains the Input Waveform
XOUT contains the Output Waveform
 $XOUT(J) = 1.0 ; \text{ if } XIN(J) \geq 0.0$
 $= -1.0; \text{ if } XIN(J) < 0.0$

e. Digital Half-Wave Detector

CALL IHWDET(IN,IOUT)

Where: IN contains the Input Waveform
IOUT contains the Output Waveform
 $IOUT(J) = IOUT(J) ; \text{ if } IOUT(J) > 0$
 $= 0 ; \text{ otherwise}$

f. Digital Full-Wave Detector

CALL IFWDET(IN,IOUT)

Where: IN contains the Input Waveform
IOUT contains the Output Waveform
 $IOUT(J) = IABS(IN(J))$

g. Digital Square-Law Detector

CALL ISQDET(IN,IOUT)

Where: IN contains the Input Waveform
IOUT contains the Output Waveform
 $IOUT(J) = IN(J)*IN(J)$

h. Digital Hard Limiter

CALL IHLM(IN,IOUT)

Where: IN contains the Input Waveform
IOUT contains the Output Waveform
 $IOUT(J) = 1 ; IN(J) > 0$
 $= 0 ; IN(J) = 0$
 $= 1 ; IN(J) < 0$

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

a. Flow Chart: Page 9-137

b. Cross Reference Table: Page 9-225

```

2560      SUBROUTINE FDDETC(XIN, XOUT)
2561      DIMENSION XIN(1), XOUT(1), IN(1), IOUT(1)
2562      DATA N193, N194, N195, N196/-3, -2, -1, 0/
2563      NS = IBSOL(XIN(N193))
2564      DO 20 I=1,NS
2565      XOUT(I) = XIN(I)
2566      IF( XOUT(I) .LT. 0.0 ) XOUT(I) = 0.0
2567      GO TO 100
2568      C
2569      ENTRY FDDET(XIN, XOUT)
2570      NS = IBSOL(XIN(N193))
2571      DO 40 I=1,NS
2572      +0 XOUT(I) = ABS(XIN(I))
2573      CL 10 100
2574      C
2575      ENTRY SKDTC(XIN, XOUT)
2576      NS = IBSOL(XIN(N193))
2577      DO 60 I=1,NS
2578      00 XOUT(I) = XIN(I)*XIN(I)
2579      GO TO 100
2580      C
2581      ENTRY REIM(XIN, XOUT)
2582      NS = IBSOL(XIN(N193))
2583      DO 80 I=1,NS
2584      IF(XIN(I)) 01, 02, 02
2585      01 XOUT(I)=1.0
2586      02 1E-10
2587      00 XOUT(I)=1.0
2588      GO TO 100
2589      C
2590      00 XOUT(N193) = XIN(N193)
2591      XOUT(N194) = XIN(N194)
2592      XOUT(N195) = XIN(N195)
2593      RETURN
2594      C
2595      ENTRY FDWDT(XIN, XOUT)
2596

```

05/11/79

INPUT LISTING

AUTOFLOW CHART 5.1 - FNU/SOL - PAUSIM

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CAT# 100

CONTENTS

3590 NSE= 14(N193)
 3591 DC DU 1=1,ND
 3598 1F(IN(1)) 31+31+2
 3644 SI TOUT(1)=0
 3600 UL TL SC
 3601 32 TOUT(1)=IN(1) /
 3602 30 CONTINUE
 3603 UL TL 200
 3604 C
 3605 ENTRY TOUT(1)=IN(1)
 3606 N2= 14(N193)
 3607 DC DU 1=1,ND
 3608 32 TOUT(1)=TABS(IN(1))
 3609 UL TL 200
 3610 C
 3611 ENTRY TOUT(1)=IN(1)
 3612 N2= 14(N193)
 3613 DC DU 1=1,ND
 3614 32 TOUT(1)=IN(1)+IN(2)
 3615 UL TL 200
 3616 C
 3617 ENTRY TOUT(1)=IN(1)
 3618 N2= 14(N193)
 3619 DC DU 1=1,ND
 3620 32 TOUT(1)=IN(1)+IN(2)
 3621 SI TOUT(1)=1
 3622 UL TL 200
 3623 SI TOUT(1)=1
 3624 UL TL 200
 3625 SI TOUT(1)=1
 3626 UL TL 200
 3627 C
 3628 ENTRY TOUT(1)=IN(1)+IN(2)
 3629 N2= 14(N193)
 3630 DC DU 1=1,ND
 3631 32 TOUT(1)=IN(1)+IN(2)
 3632 SI TOUT(1)=1
 3633 UL TL 200

SUBROUTINE INGTOR

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
INGTOR	LTI-4	409, 410
INGNCL	LTI-4	None

2. PURPOSE:

This subroutine is used to simulate a digital integrator.

3. INPUT PARAMETERS:

Name	O/R	T	Description
FBCK	R	F	Feedback coefficient

4. CALLING SEQUENCES:

CALL INGTOR (DIN, DOUT)

Where: DIN contains the Input Waveform
DOUT contains the Output Waveform

The storage register (C1) is cleared before execution begins.

CALL INGNCL (DIN, DOUT)

Where: DIN contains the Input Waveform
DOUT contains the Output Waveform

The storage register (C1) is not cleared before execution begins.

5. RESTRICTIONS, REQUIREMENT, MISCELLANEOUS DATA

a. Flow Chart: Page 9-97

b. Cross Reference Table: Page 9-220

6. THEORY OF OPERATION

The block diagram of the digital integrator simulated by this module is shown in Figure INGTOR-1. The Z-plane transfer function is given by the following expression:

$$T(Z) = \frac{Z}{Z-FBCK}$$

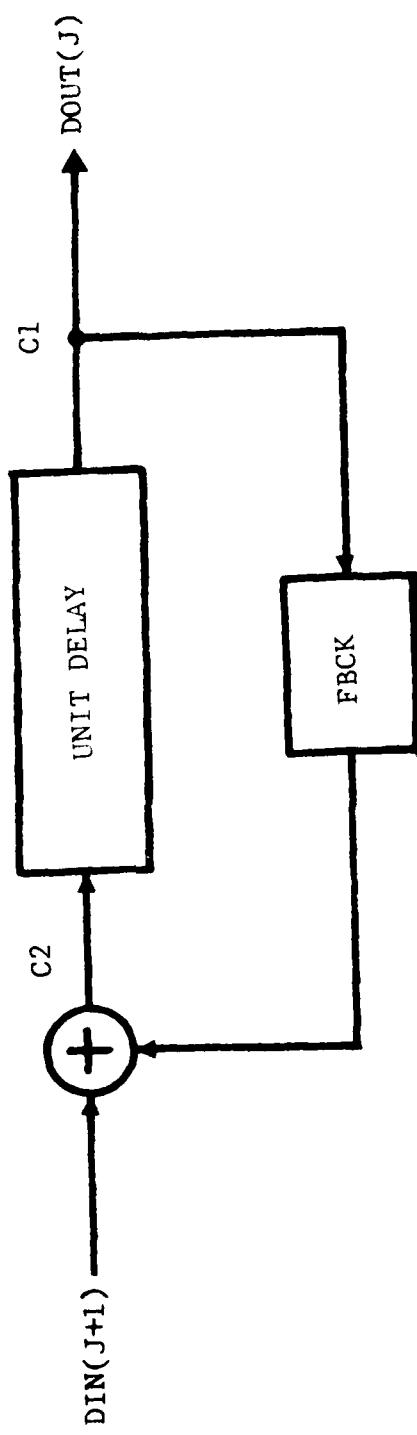


Figure INGTOR-1 BLOCK DIAGRAM OF INGTOR

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4-73

```
2581      SUBROUTINE JROTEN(DIN,DOUT)  
2582      COMMON/LK1/LK1(560)  
2583      DIMENSION DIN(1),DOUT(1)  
2584      EQUIVALENCE (LK1(21),IDMY      ), (LK1(75),FECK      )  
2585      DATA N193,N194,N195,N196/-3,-2,-1,0/  
2586      C1 = 0.0  
2587      ENTRY JNGC(DIN,DOUT)  
2588      N = ILOC(LK1(N193))  
2589      DOUT(N193) = DIN(N193)  
2590      DOUT(N194) = DIN(N194)  
2591      DOUT(N195) = DIN(N195)  
2592      DO 10 J=1,N  
2593      C2 = DIN(J)+C1*FECK  
2594      DOUT(J) = C1  
2595      C1 = C2  
2596      IF (CONTINUE)  
2597      RETURN  
2598      END
```

SUBROUTINE IONOS

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
IONOS	LTI-1	511

2. PURPOSE:

This subroutine is used to simulate the effect of the ionosphere on signals propagating through it.

3. INPUT PARAMETERS:

Name	O/R	T	Description
RFF0	R	F	Center frequency of the electro-magnetic wave traversing the ionosphere
SEDENS	R	F	The integrated electron density along the propagation path

4. CALLING SEQUENCES:

CALL IONOS (X, Y)

Where: X contains the Input Waveform - R
Y contains the Input Waveform - I
X contains the Output Waveform - R
Y contains the Output Waveform - I

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. The effect of the earth's magnetic field is not included in this model.

b. The effect of electron collisions with ions and neutral particles is not included in this model. The major effect resulting from electron collisions is a damping term which results in absorption of energy from the electromagnetic wave transversing the ionized medium. For frequencies above 100 MHz electron collisions have negligible effect on the phase behavior of the ionosphere as a function of frequency.

c. Reference:

Berkowitz, R. S., ed, Modern Radar Analysis, Evaluation, and System Design, John Wiley & Sons, Inc., New York, 1965, pp 349-354, 364-370.

d. Flow Chart: Page 9-117

e. Cross Reference Table: Page 9-223

6. THEORY OF OPERATION

The index of refraction of an ionized medium is given by the following expression:

$$n = \sqrt{1 - \frac{N_e e^2}{m\pi f^2}} \quad (1)$$

where: N_e is the electron density (electrons/cm^3)

e is the electron charge (4.8×10^{-10} esu)

f is the frequency of this incident electromagnetic energy

Collisions between electrons and ions or neutral particles are neglected.

The phase velocity of the propagating wave, v_p , is given by the following expression:

$$v_p = c/n \quad (2)$$

where: c is the speed of light in free space

Therefore, combining equations 1 and 2 the following expression is obtained:

$$v_p = \frac{c}{\sqrt{1 - N_e e^2 / m \pi f^2}} \quad (3)$$

The phase velocity will approach infinity as the denominator of equation 3 decreases to zero. When this condition arises, further wave propagation is impossible. The frequency for which this occurs is called the critical frequency and is given by the following expression:

$$f_c^2 = \frac{N_e e^2}{m \pi} = 8.0 \times 10^7 N_e (\text{Hz})^2 \quad (4)$$

Equation 3 now becomes the following:

$$v_p = \frac{c}{\sqrt{1 - f_c^2 / f^2}} \quad (5)$$

The differential phase shift $d\phi$ that a wave will encounter in traversing an element of path length ds is given by the following expression:

$$d\phi = -\frac{2\pi}{\lambda} ds \quad (6)$$

where: λ is the wavelength of the radiated electromagnetic energy

Since $\lambda = v_p/f$ the following expression is obtained by substitution of equation 5 into equation 6:

$$d\phi = \frac{2\pi f}{c} \sqrt{1 - f_c^2 / f^2} ds \quad (7)$$

This expression can be further simplified by adding the term $\frac{f_c^4}{4f^2}$ to the terms inside the square root

radical. For most radar applications $f_c \ll f$ so this will introduce a very small error. Equation 7 now becomes:

$$\begin{aligned} d\phi &= \frac{2\pi f}{c} \sqrt{\left(1 - \frac{f_c^2}{2f^2}\right)^2} ds \\ &= \frac{2\pi f}{c} \left(1 - \frac{f_c^2}{2f^2}\right) ds \end{aligned} \quad (8)$$

In order to determine the phase shift over a propagation path from s_1 to s_2 the following expression will be used

$$\begin{aligned} \phi &= \frac{2\pi f}{c} \int_{s_1}^{s_2} \left(1 - \frac{f_c^2}{2f^2}\right) ds \\ &= \frac{2\pi f}{c} \int_{s_1}^{s_2} ds - \frac{2\pi}{2cf} \int_{s_1}^{s_2} f_c^2 ds \end{aligned}$$

substituting for f_c^2 the following is obtained:

$$\phi = \frac{2\pi f}{c} \int_{s_1}^{s_2} ds - \frac{\pi}{cf} 8.0 \times 10^7 \int_{s_1}^{s_2} N_e ds \quad (9)$$

The first term of equation 9 is the linear phase shift due to propagation over a path of length $s_2 - s_1$ and will be omitted since it represents a time delay only

Therefore, the equation used to calculate the dispersive effect of the ionosphere is given by the following expression:

$$\phi(f) = -2\pi \frac{4.0 \times 10^7}{3.0 \times 10^{10}} \frac{1}{f} \quad \text{SEDENS}$$

where: SEDENS = $\int_{s_1}^{s_2} N_e ds$ = integrated electron density

$$f = RFF\phi + k \Delta F, \quad -\frac{FEXT}{2 \Delta F} < k < \frac{FEXT}{2 \Delta F}$$

FEXT = frequency extent of input waveform representations

F = independent variable spacing of input waveform representations.

3104 SUBROUTINE ZLIND(X,Y)
3105 LMMUN/LERK/ VAR(500)
3106 DIMENSION X(1),Y(1)
3107 EQUIVALENCE (VAR(148),SEDENS), (VAR(3), FFF0)
3108 * VARIABLE SEDENS IS INTEGRATED ELECTRON DENSITY ALONG
3109 * PROPAGATION PATH (ELECTRONS/CM*CM)
3110 DATA N193,N194,N195/-3,-2,-1/ CONS/ 1.3333E-03 /,PI2/6.2831853/
3111 NPTS=600L(X(N193))
3112 FREQ=(X(N194)+FFF0)*1.0E+09
3113 DELF=X(N195)*1.0E+09
3114 DO 200 J=1,NPTS
3115 THETA= CONS*SEDENS/FREQ
3116 THETA=(THETA- FLOAT(IFIX(THETA)))*PI2
3117 TMP=X(J)
3118 C=COS(THETA)
3119 S=SIN(THETA)
3120 X(J)=X(J)*C-Y(J)*S
3121 Y(J)=TMP*S+Y(J)*C
3122 FREQ=FREQ+DELF
3123 200 CONTINUE
3124 RETURN
3125 END

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SUBROUTINE LAMPCP

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
LAMPCP	LTI-1 or LTI-4	458
LAMPRE	LTI-1 or LTI-4	456, 457

2. PURPOSE:

This subroutine is used to simulate a linear amplifier.

3. INPUT PARAMETERS:

Name	O/R	T	Description
GAIN	R	F	Amplifier gain

4. CALLING SEQUENCES:

CALL LAMPCP (XIN, YIN, XOUT, YOUT)

Where: XIN contains the Input Waveform - R

YIN contains the Input Waveform - I

XOUT contains the Output Waveform - R

YOUT contains the Output Waveform - I

CALL LAMPRE (XIN, XOUT)

Where: XIN contains the Input Waveform

XOUT contains the Output Waveform

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

a. Flow Chart: Page 9-68

b. Cross Reference Table: Page 9-217

6. THEORY OF OPERATION

The relationship between the input and output is given by the following expressions:

XOUT(J) = GAIN * XIN(J) ; LAMPCP & LAMPRE
YOUT(J) = GAIN * YIN(J) ; LAMPCP

2027 SUBROUTINE LAMPCP(XIN,YIN,XOUT,YOUT) 482
2028 DIMENSION XIN(1),YIN(1),XCUT(1),YCUT(1)
2029 COMMON/BLK1/ R1200

08/13/73	INPUT LISTING	AUTOFLOW CHART SET - FHL/SCL FAUSIM
CARD NO.	*****	CONTENTS
2030		*****
2030	DATA N193,N194,N195/-3,-2,-1/	
2031	EQUIVALENCE (E1145) , GAIN)	
2032	MUL=1	
2033	GOUT 100	
2034	ENTRY LAMPRE(XIN,XCUT)	
2035	MUL=0	
2036	100 NPTS=EULL(XIN(N193))	
2037	DO 200 J=1,NPTS	
2038	XOUT(J)=XIN(J)*GAIN	
2039	200 CONTINUE	
2040	IF(MUL.EQ.0) GOTO 500	
2041	DO 300 J=2,NPTS	
2042	YOUT(J)=YIN(J)*GAIN	
2043	300 CONTINUE	
2044	YCUT(N193)=YIN(N193)	
2045	YCUT(N194)=YIN(N194)	
2046	YCUT(N195)=YIN(N195)	
2047	500 XCUT(N193)=XIN(N193)	
2048	XCUT(N194)=XIN(N194)	
2049	XCUT(N195)=XIN(N195)	
2050	RETURN	
2051	END	

SUBROUTINE MTIFLT

1. MODULE IDENTIFICATION:

<u>Name</u>	<u>Classification Code</u>	<u>Reference Number</u>
MTIFLT (MODEDF=1)	LTI-4	430,431
MTINCL (MODEDF=1)	LTI-4	432,433
MTIIFT (MODEDF=2)	NL-2	430,431
MTIINC (MODEDF=2)	NL-2	432,433

2. PURPOSE:

This subroutine is used to simulate a double delay MTI processor. Either floating point or integer arithmetic is selectable.

3. INPUT PARAMETERS

a. MODEDF = 1

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
FF0	0	F	Feed - forward coefficient - 0 delay (no delay)
FF1	0	F	Feed - forward coefficient - 1 delay (single delay)
FB1	0	F	Feedback coefficient - 1 delay
FB2	0	F	Feedback coefficient - 2 delay (double delay)

b. MODEDF=2

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
IFF0N	0	I	Numerator of Feed - forward coef - 0 delay
IFF0D	R	I	Denominator of feed - forward coef - 0 delay
IFF1N	0	I	Numerator of feed - forward coef - 1 delay

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
IFF1D	R	I	Denominator of feed - forward coef - 1 delay
IFB1N	O	I	Numerator of feedback coef - 1 delay
IFB1D	R	I	Denominator of feedback coef - 1 delay
IFB2N	O	I	Numerator of feedback coef - 2 delay
IFB2D	R	I	Denominator of feedback coef. - 2 delay
NBITS	R	I	Number of bits to be used in storing one range sample in the arrays (ISR1 and ISR2) which represents the digital delay lines (includes sign bit).

4. CALLING SEQUENCES:

Floating point arithmetic

CALL MTIFLT (DIN, DOUT)

Where: DIN contains the Input Waveform

DOUT contains the Output Waveform

The range bit storage arrays (SR1 and SR2) are cleared prior to execution.

The entry point is used only if MODEDF=1.

Floating point arithmetic

CALL MTINCL (DIN, DOUT)

Where: DIN contains the Input Waveform

DOUT contains the Output Waveform

The range bin storage arrays (SR1 and SR2) are not cleared prior to execution except for the first execution of this subroutine. This entry point is used only if MODEDF=1.

Integer arithmetic

CALL MTIIFT (IN, IOUT)

Where: IN contains the Input Waveform

IOUT contains the Output Waveform

The range bin arrays (ISR1 and ISR2) are cleared prior to execution.

This entry point is used only if MODEDF=2.

Integer Arithmetic

CALL MTIINC (IN, OUT)

Where: IN contains the Input Waveform

IOUT contains the Output Waveform

The range bin storage arrays (ISR1 and ISR2) are not cleared prior to execution except for the first execution of this subroutine.

This entry point is used only if MODEDF=2.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. The maximum number of range bins simulated is 2048. If more than 2048 range samples are contained in the input array, only the first 2048 are processed.
- b. The parameter MODEDF is used by the simulation controller to determine whether the floating point or the fixed point module entry points are to be used.
- c. The entry points which use integer arithmetic are considered nonlinear because of truncation in arithmetic and saturation in the delay line.
- d. Flow Chart: Page 9-201
- e. Cross Reference Table: 9-234

6. THEORY OF OPERATION

The block diagram of the two-delay MTI processor digital filters simulated by this module are shown in Figure MTIFLT-1 and MTIFLT-2. The Z-plane transfer function for each range bin (floating point arithmetic) is given by the following expression:

$$T(z) = \frac{z^2 + \frac{FF1}{FF0} z + \frac{1}{FF0}}{z^2 - FB1 z - FB2}$$

The Z-plane transfer function for each range bin (integer arithmetic) is approximated by the following expression:

$$T(z) = \frac{IFF0N}{IFF0D} \frac{z^2 + \frac{IFF1N \cdot IFF0D}{IFF0N \cdot IFF1D} z + \frac{IFF0D}{IFF0N}}{z^2 - \frac{IFB1N}{IFB1D} z - \frac{IFB2N}{IFB2D}}$$

The delay represented by the Z operator is determined by the radar pulse repetition interval.

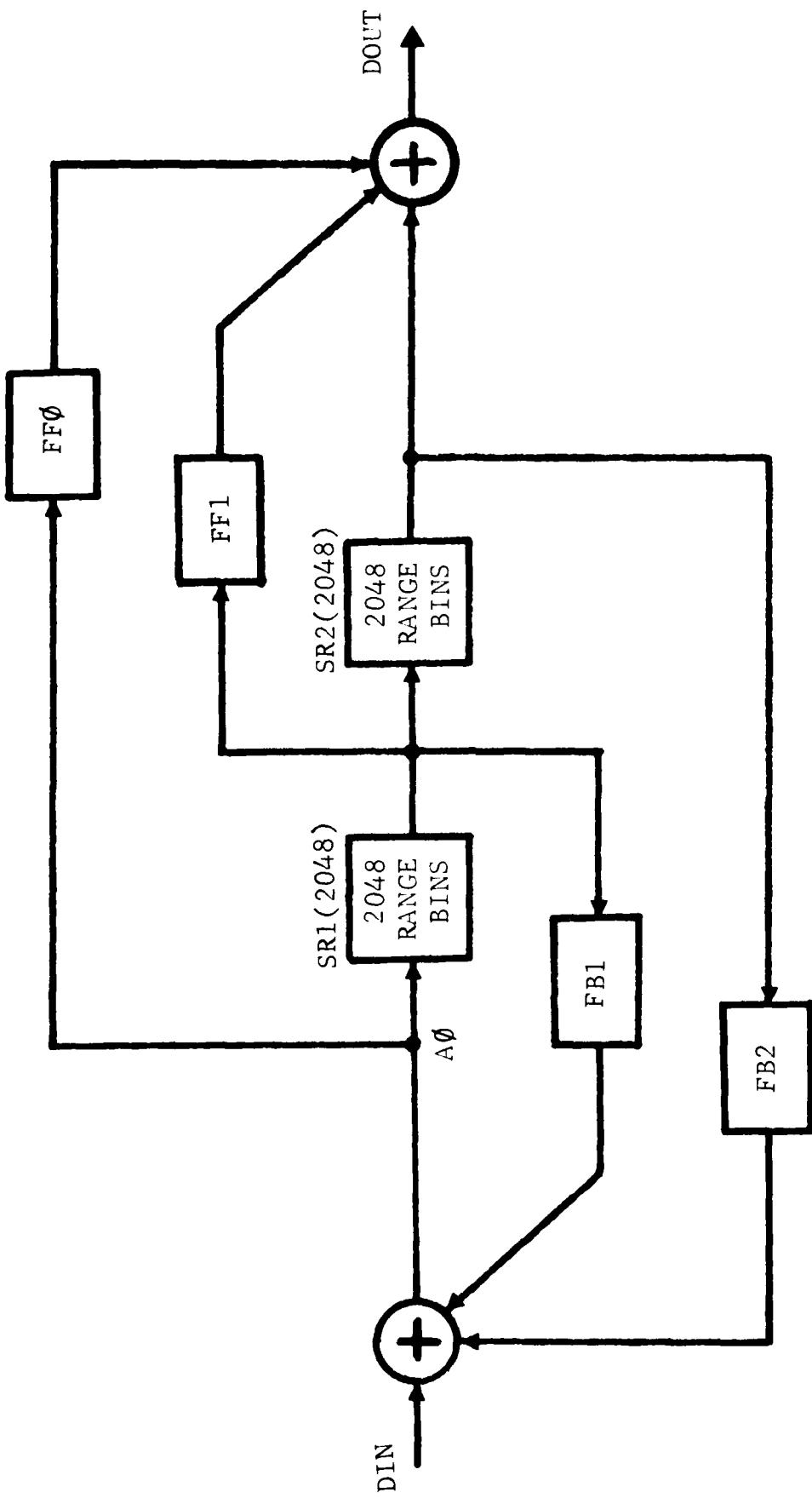


Figure MTIFLT-1 BLOCK DIAGRAM OF MTIFLT/MTINCL
(Floating-point Arithmetic)

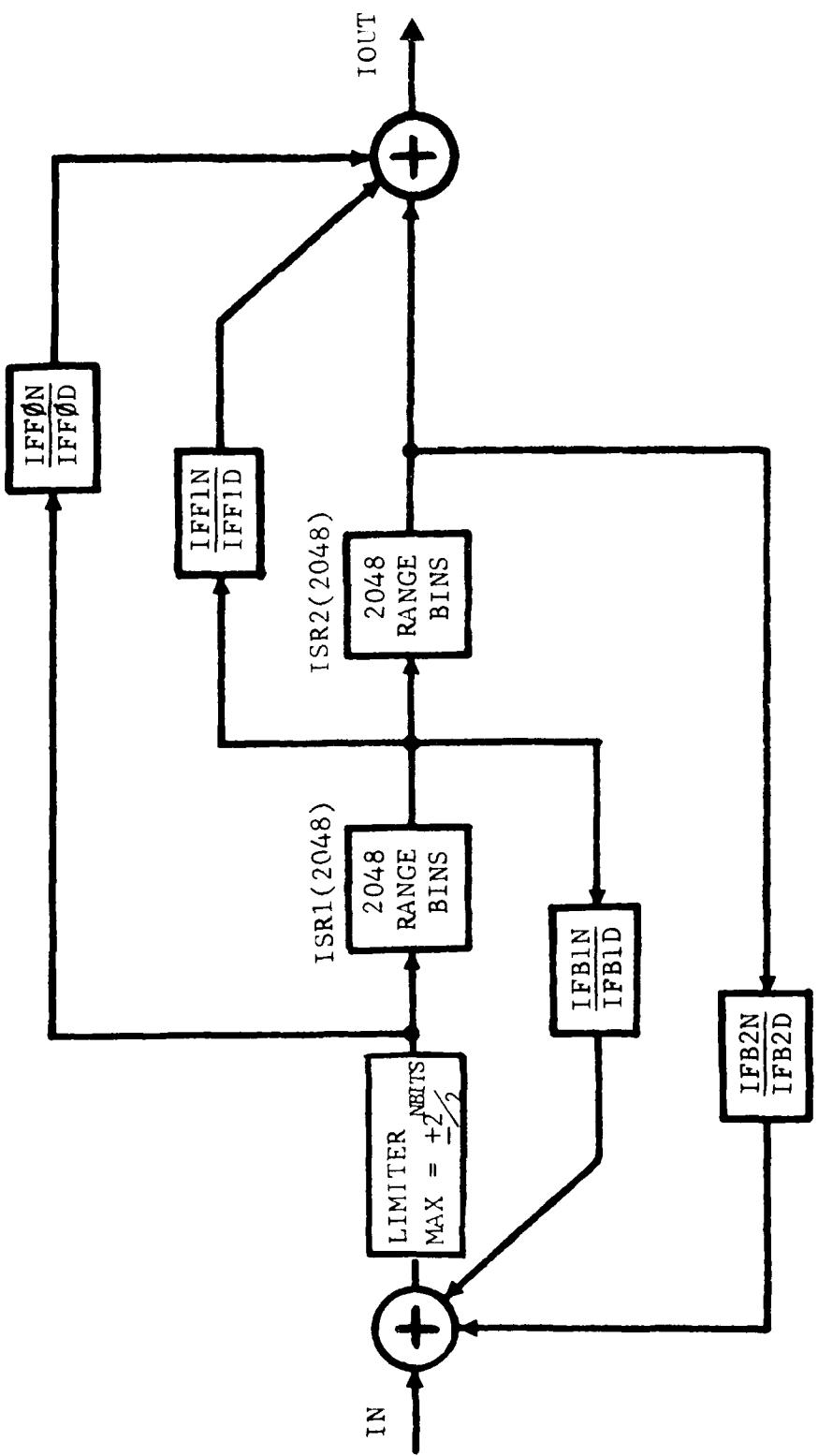


Figure MTIFLT-2 BLOCK DIAGRAM OF MTIFLT/MTINCL (Integer Arithmetic)

5194	SUBROUTINE M11FL1(LIN,DOUT)	UC7TS001
5200	CLMMLN/BK1(500)	UC7TS002
5201	DIMENSION LIN(1),DOUT(1),IN(1),IOUT(1),SK1(2048),SK2(2048),	UC7TS003
5202	* ISK1(2048),ISK2(2048)	UC7TS004
5203	EQUIVALENCE (SK1(1),ISK1(1)), (SK2(1),ISK2(1))	UC7TS005
5204	DATA N193,N194,N195,N196/-3,-2,-1,0/	UC7TS006
5205	DATA JFLG/0/	320
5206	EQUIVALENCE (BK1(21), IDMY) , (BK1(60), FFO) ,	UC7TS008
5207	1 , (BK1(69), FF1) , (BK1(70), FB1) ,	UC7TS009
5208	2 , (BK1(71), FB2) ,	UC7TS010
5209	EQUIVALENCE (BK1(160), IFFON) , (BK1(161), IFFOD) ,	UC7TS011
5210	* (BK1(162), IFFIN) , (BK1(163), IFFI0) ,	UC7TS012
5211	* (BK1(164), IFB1N) , (BK1(165), IFB1D) ,	UC7TS013
5212	* (BK1(166), IFB2N) , (BK1(167), IFB2D) ,	UC7TS014
5213	* (BK1(168), NBITS) ,	UC7TS015
5214	ICON=2	401
5215	GO TO 40	402
5216	ENTRY M11CL(LIN,DOUT)	403
5217	ICON=2	404
5218	40 IF(JFLG.EQ.1.AND.ICON.EQ.2) GO TO 50	405
5219	DO 20 J=1,1048	UC7TS016

08/18/75	INPUT LISTING	AUTOFLUX CHART SET - FNU/SCL RAUSIM
		H-90
CARD NO.	*****	CONTENTS
5220	SK1(J)=0.0	UC7TS017
5221	SK2(J)=0.0	UC7TS018
5222	10 CONTINUE	UC7TS019
5223	IFLG=1	450
5224	50 CONTINUE	451
5225	N = IBUL(DIN(N193))	UC7TS021
5226	IF(N.LE.2048) GO TO 15	UC7TS022
5227	N=2048	UC7TS023
5228	WHITE(6,25)	UC7TS024
5229	25 FORMAT * TOO MANY POINTS IN INPUT ARRAY... FIRST 2048 PROCESSED! UC7TS025	
5230	* 1	UC7TS026
5231	15 DOUT(N193) = BLC(L(N))	UC7TS027
5232	DOUT(N194) = DIN(N194)	UC7TS028
5233	DOUT(N195) = DIN(N195)	UC7TS029
5234	DO 10 J=1,N	UC7TS030
5235	AU= SR1(J)*FB1+SR2(J)*FB2+DIN(J)	UC7TS031
5236	DOUT(J)= AU*FF0+SR1(J)*FF1+ SR2(J)	UC7TS032
5237	SK2(J)=SK1(J)	UC7TS033
5238	SK1(J)=AU	UC7TS034
5239	10 CONTINUE	UC7TS035
5240	RETURN	UC7TS036
5241	ENTRY M11F1(IN,DOUT)	UC7TS037
5242	ICUN=1	621
5243	GO TO 60	622
5244	ENTRY M11NC(IN,ICUT)	623
5245	ICUN=2	624
5246	60 IF(IFLG.EQ.1.AND.ICUN.EQ.2) GO TO 70	625
5247	60 DO 100 J=1,2048	UC7TS038
5248	100 SK1(J)=0	UC7TS039

5244 ISK2(J)=0 4-90a UC7TS040
 5250 100 CONTINUE UC7TS041
 5251 JFLG=1 670
 5252 70 CONTINUE 671
 5253 IF(NBITS.GT.0.AND.NBITS.LE.31) GO TO 95 UC7TS043
 5254 NBITS=31 UC7TS044
 5255 95 CONTINUE UC7TS045
 5256 MAX=2**(NBITS-1) UC7TS046
 5257 N=IN(N193) UC7TS047
 5258 IF(N.LE.2048) GO TO 105 UC7TS048
 5259 N=2048 UC7TS049
 5260 WRITE(6,25) UC7TS050
 5261 105 IOUT(N193)=N UC7TS051
 5262 IOUT(N194)=IN(N194) UC7TS052
 5263 IOUT(N195)=IN(N195) UC7TS053
 5264 DO 110 J=1,N UC7TS054
 5265 IO=(ISK1(J)*IFF1N)/IFF1D +(ISR2(J)*IFF2N)/IFF2D + IN(J) UC7TS055
 5266 IF(IAES(I0).GT.MAX) IO=ISIGN(MAX,IO) UC7TS056
 5267 IOUT(J)=(IO*IFF0N)/IFF0D +(ISK1(J)*IFF1N)/IFF1D + ISR2(J) UC7TS057
 5268 ISR2(J)=ISK1(J) UC7TS058
 5269 ISK1(J)=IO UC7TS059
 5270 110 CONTINUE UC7TS060
 5271 RETURN UC7TS061
 5272 END

SUBROUTINE NONLIN

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
NONLIN	NL-1	401, 402

2. PURPOSE:

This subroutine is used to simulate a zero memory nonlinear device.

3. INPUT PARAMETERS:

Name	O/R	T	Description
NPTS	R	I	Number of points used to specify the transfer function
TFN	R	F	Array containing the specification of the transfer function. The coefficients for the Jth point are the following:

TFN(1,J) = Input voltage

TFN(2,J) = Output voltage

4. CALLING SEQUENCES:

CALL NONLIN (A,\$mmmm)

Where: A contains the Input Waveform

A contains the Output Waveform

\$mmmm is the statement number in the calling program to which control is returned if a discrepancy is detected in the input data.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

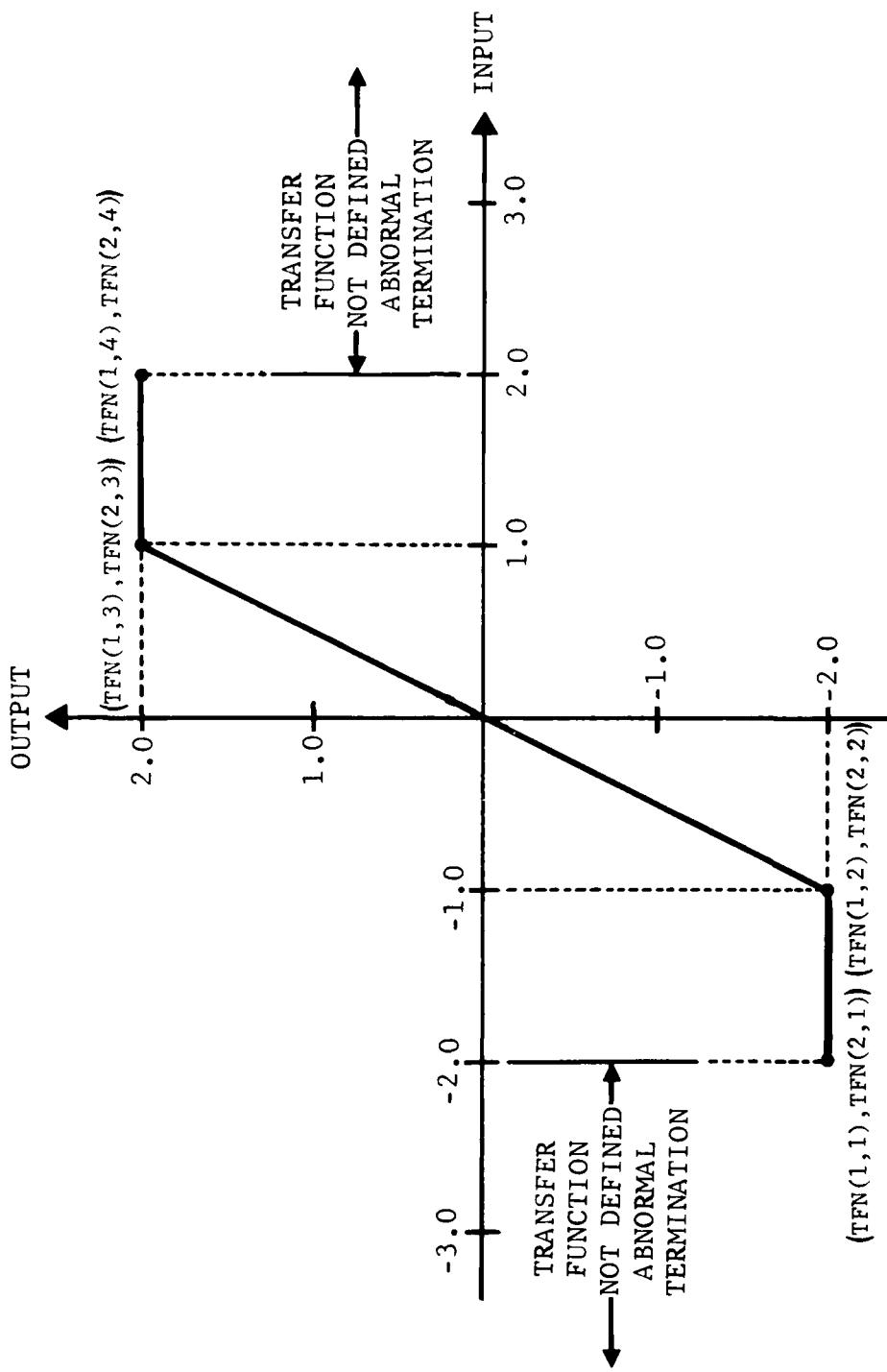
- a. The independent variable in the transfer function specification array must be monotonically increasing.
- b. The input data must be within the limits of the specified transfer function.
- c. Flow Chart: Page 9-135
- d. Cross Reference Table: Page 9-225

6. THEORY OF OPERATION

The input vs output characteristics of the device to be simulated are specified via the array TFN. A table lookup and linear interpolation scheme are used to compute the output value for each sample of the input waveform. An abnormal termination will occur if an input sample is outside the range of input values specified in the array TFN.

An example of the input data for this module is the nonlinear transfer function shown in Figure NONLIN-1. The associated input data statement is as follows:

```
$NL401 TFN = -2.0, -2.0, -1.0, -2.0, 1.0, 2.0, 2.0,  
2.0, NTFN = 4$
```



4-92a

Figure NONLIN-1 EXAMPLE OF NON-LINEAR TRANSFER FUNCTION

3536 SUBROUTINE NNLIN(A,*)
 4-93
 3537 COMMON/BK1/BK1(500)
 3538 DIMENSION A(1),TFN(2,50)
 3539 EQUIVALENCE (BK1(21), IDMY), (BK1(67), NFTS),
 3540 * (BK1(201), TFN(1,1))
 3541 DATA N143,N144,N145,N146/-3,-2,-1,0/
 3542 NIN = ICODE(A(N143))
 3543 K=1
 3544 DO 100 J=1,NIN
 3545 GO TO 105
 3546 105 K=K+1
 3547 GO TO 105
 3548 104 K=K-1
 3549 105 IF(K.GT.NFTS) GO TO 500
 3550 IF(K.LT.1) GO TO 500
 3551 IF(A(J).LT.TFN(1,K))GO TO 104
 3552 IF(A(J).GT.TFN(1,K+1))GO TO 103
 3553 PCT = (A(J)-TFN(1,K)) / (TFN(1,K+1)-TFN(1,K))
 3554 A(J) = TFN(2,K) + PCT*(TFN(2,K+1)-TFN(2,K))
 3555 100 CONTINUE
 3556 RETURN
 3557 500 CONTINUE
 3558 RETURN 1
 3559 END

SUBROUTINE PHDEC

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
PHDEC	LTI-2	508, 509

2. PURPOSE:

This subroutine is used to simulate an analog phase decoder.

3. INPUT PARAMETERS

a. Automatic mode; INPTF = 0

Name	O/R	T	Description
SIMFØ	R	F	Center frequency of waveform previously generated by FGENXY/FGENMP. This parameter is used to specify the center frequency of the tapped delay line.
INPTF	R	I	Set = 0 for this mode
SPW	R	F	Subpulsewidth of waveform previously generated by FGENXY/FGENMP. This parameter is used to specify the delay line tap spacing (TAPSPC).
XMITPC	R	F	Array containing the phase code of the waveform generated by FGENXY/FGENMP.
NSUBP	R	I	Number of subpulses in the waveform generated by FGENXY/FGENMP. This parameter specifies the number of delay line taps.

NOTE: No user supplied inputs required for this mode.
All required parameters are initialized by
FGENXY/FGENMP.

b. User Supplied data mode; INPTF = 1

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
FØDEC	R	F	Center frequency of the tapped delay line.
TAPSPC	O	F	Spacing between delay line taps. This parameter is set equal to SPW if it is not specified by the user.
INPTF	R	I	Set = 1 for this mode
XMITPC	R	F	Array containing the phase code of the waveform generated by FGENXY/FGENMP. (Initialized by FGCEXY/FGENMP)
NSUBP	R	I	Number of subpulses in the waveform generated by FGENXY/FGENMP. This parameter specifies the number of delay line taps. (Initialized by FGENXY/FGENM)

4. CALLING SEQUENCES:

CALL PHDEC (X,Y)

Where: X contains the Output Waveform - R
Y contains the Output Waveform - I

5. RESTRICTIONS, RECOMMENDATIONS, MISCELLANEOUS DATA

- a. If INPTF=1 and TAPSPC is specified, then TAPSPC should be an integral multiple of the period of the waveform center frequency, i.e. TAPSPC = N*1.0/SIMFØ where N is an integer. Otherwise, the taps will not have the desired phase shifters as specified in the array XMITPC.
- b. Flow Chart: Page 9-78
- c. Cross Reference Table: Page 9-218

6. THEORY OF OPERATION

This module generates the transfer function of a tapped analog delay line. The main use of this module is to simulate a surface acoustic wave device. A block diagram of this device represented by this module is shown in Figure PHDEC-1. This module is structured to represent only the taps (energy pickoffs) of the delay line. The wave launches must be specified separately in terms of its transfer function. This can be done via either the FILT or the WEIT modules. A pictorial diagram of a surface acoustic wave device and its representation are shown in Figures PHENC-2(a) and -2(b). The impulse response of the device represented by this module is given by the following expression:

$$h(t) = \sum_{K=1}^{K=NSUBP} g_k \delta(t - kt_d) e^{j\theta_k}$$

where:
 g_k = tap gain
 t_d = tap spacing
 θ_k = tap phase shift

The transfer function computed by this module is given by the following expression:

$$H(f) = F[h(t)] = \int_{-\infty}^{\infty} \cdot \sum_{k=1}^{NSUBP} g_k \delta(t - kt_d) e^{j\theta_k} e^{-j2\pi ft} dt$$

Interchanging the order of integration and summation

$$H(f) = \sum_{1}^{NSUBP} g_k e^{j\theta_k} \int_{-\infty}^{\infty} \delta(t - kt_d) e^{-j2\pi ft} dt$$

$$H(f) = \sum_{1}^{NSUBP} g_k e^{j\theta_k} e^{-j2\pi f k t_d}$$

This version of the phase decoder module sets all $g_k = 1.0$. If a phase decoder with gain weighting or errors is desired then the DFT routine should be used to compute the transfer function.

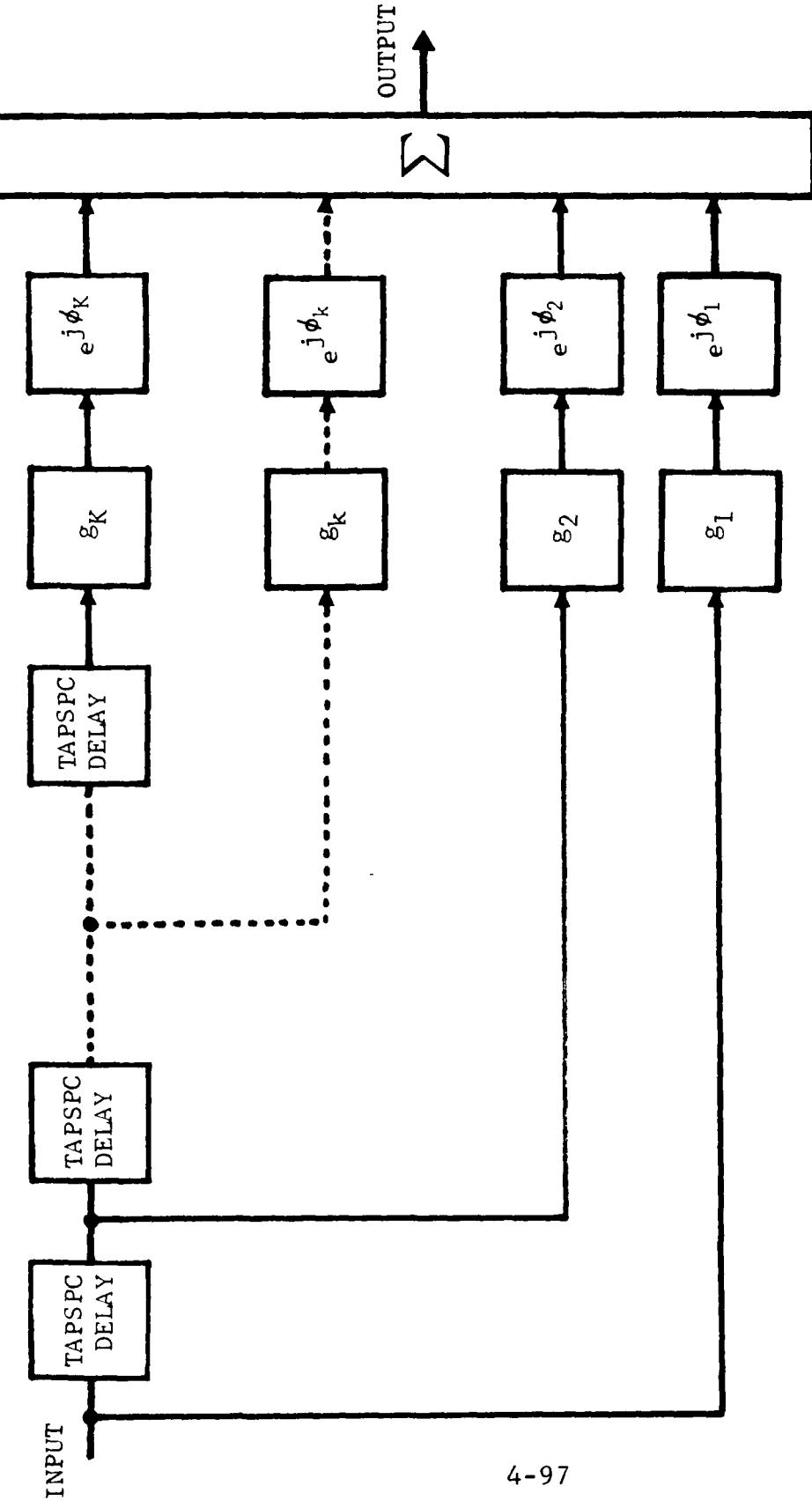


Figure PHDEC-1 BLOCK DIAGRAM OF A TAPPED DELAY LINE PHASE DECODER

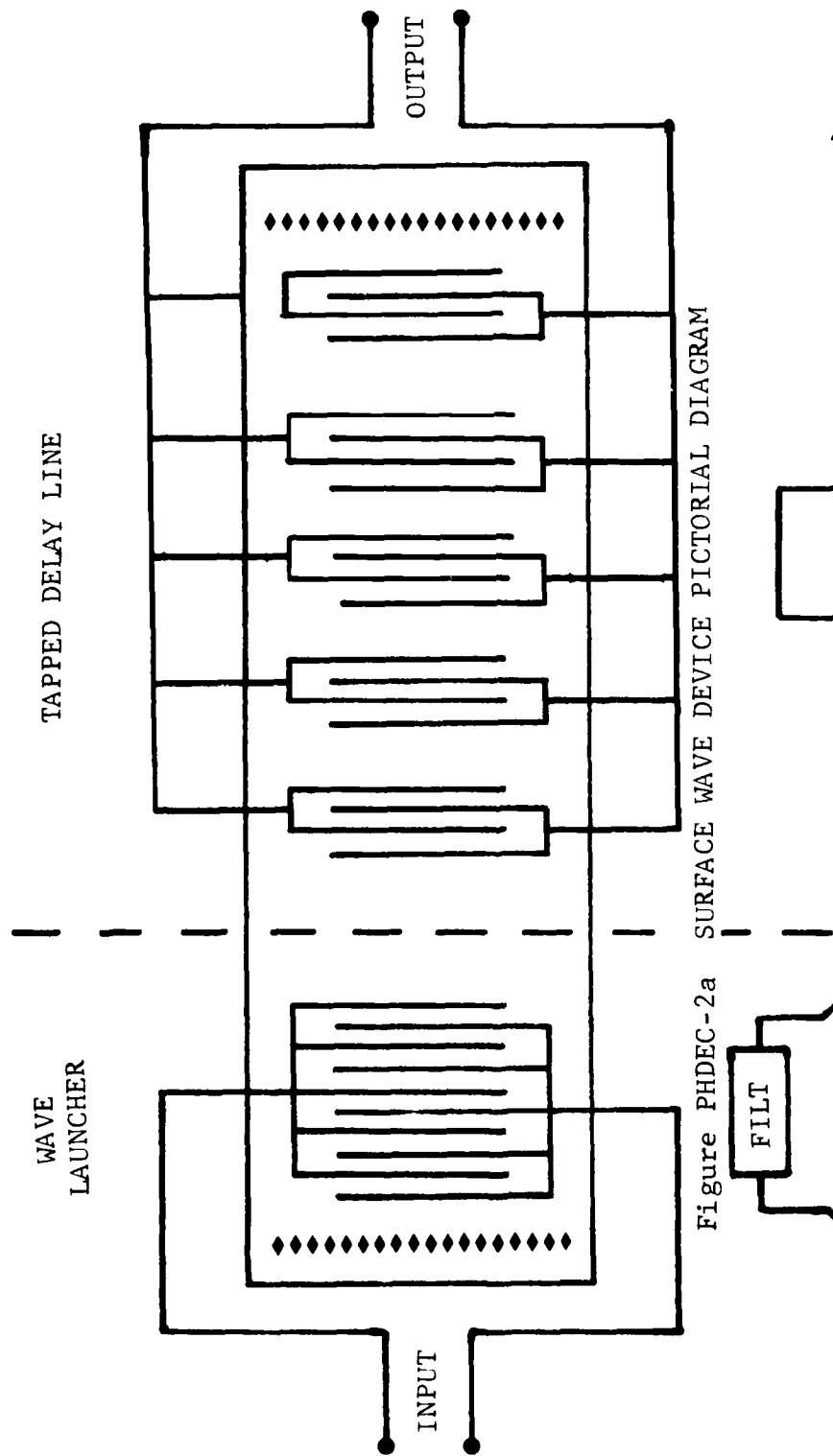


Figure PHDEC-2a SURFACE WAVE DEVICE PICTORIAL DIAGRAM

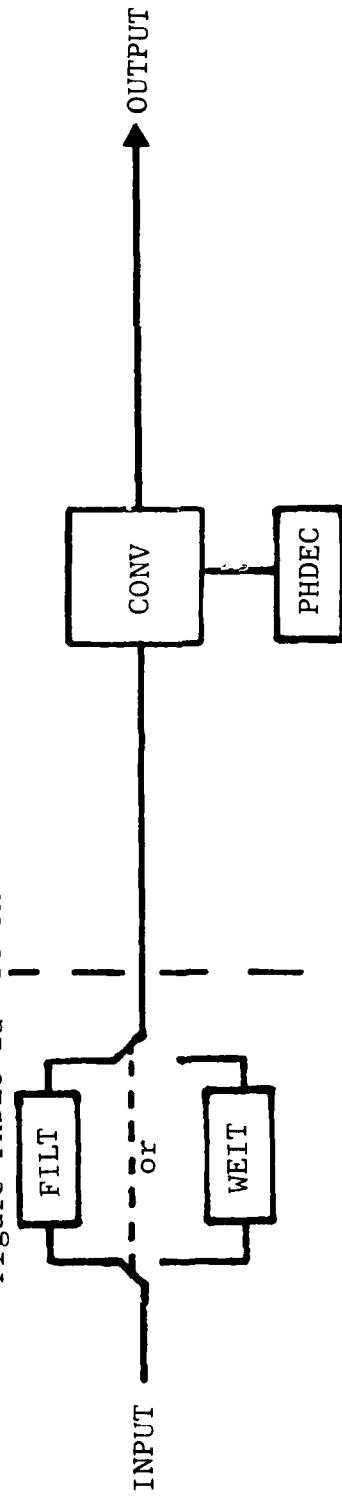


Figure PHDEC-2b SIMULATION MODEL BLOCK DIAGRAM

2244 SINELELINE PDE(X,Y)
 2245 DIMENSION X(1),Y(1)
 2246 COMMON/BLK1/ X,MTPC(300),NSUF,SPW
 2247 COMMON/BLK2/ ITEM(100),NIMF,TIN(100)
 2248 EQUIVALENCE (ITEM(102), EODEL), (ITEM(104), TAESPC),
 2249 * (ITEM(105), SINEL), (ITEM(106), INTEL)
 2250 IF (INTEL.EQ.1) SINEL=SPW
 2251 IF (INTEL.EQ.0) TAESPC=SPW
 2252 IF (INTEL.EQ.1.AND.TAESPC.EQ.0) TAESPC=SPW
 2253 TAESPC=SPW
 2254 TIN=0.0
 2255 DO 100 CONTINUE
 2256 NIMF=100
 2257 IF (TAASS.GT.100) NIMF=100
 2258 L=100 J=L+NIMF
 2259 L1=L+J-1=NITPC(TAASS+1-J)
 2260 L1=L+J-TIME
 2261 L1=L+J-100
 2262 TIME=TIME+TAESPC
 2263 CONTINUE
 2264 IF (TAASS.EQ.100) CALL DTFD(X,Y)
 2265 IF (TAASS.NE.100) CALL DTFLN(X,Y)
 2266 DTFLN(MTPC(200)) RETURN
 2267 TAASS=TAASS-100
 2268 IF (TAASS.EQ.0) RETURN
 2269 GOTO 100
 2270 END

SUBROUTINE PHENC

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
PHENC/FGGNXY	SOU-1 or LTI-3	506
PHENC/FGENMP	SOU-1 or LTI-3	507

2. PURPOSE:

This subroutine generates a phase code which is subsequently used by FGENXY/FGENMP to generate a binary phase coded waveform. Either the module FGENXY or FGENMP is automatically scheduled for execution.

3. INPUT PARAMETERS

a. MODEPH = 1; Barker Phase Code

Name	O/R	T	Description
MODEPH	R	I	Set = 1 for this mode
NSUBP	R	I	Number of subpulses to be generated. The allowable values of this parameter and the corresponding Barker codes are as follows:
	2	+ -	
	3	+ + -	
	4	+ + - +	
	5	+ + + - +	
	7	+ + + - - + -	
	11	+ + + - - - + - - + -	
	13	+ + + + + - - + + - + - +	

b. MODEPH = 2; Pseudo Random Phase Code

Name	O/R	T	Description
MODEPH	R	I	Set = 2 for this mode
NSUBP	R	I	Number of subpulses. Maximum value = 300 for this mode.

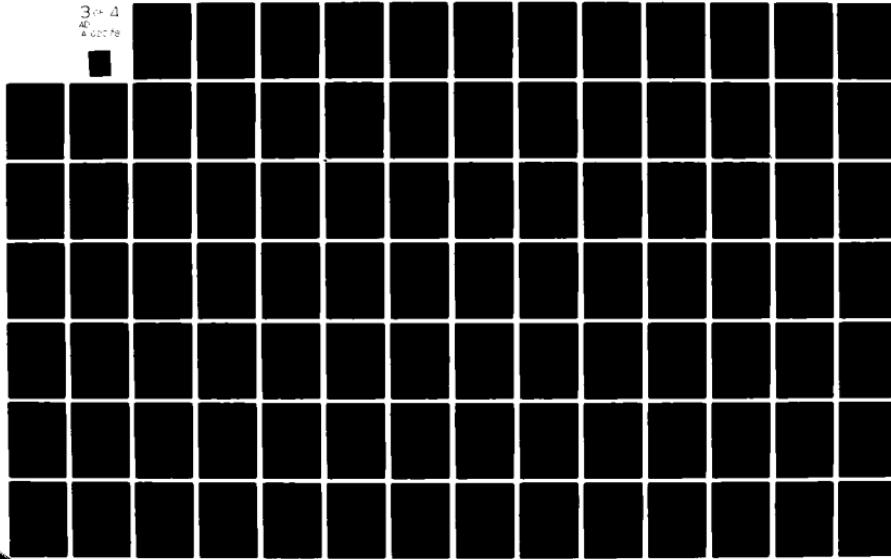
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GENERAL DYNAMICS FORT WORTH TEX CONVAIR AEROSPACE DIV F/6 17/9
ENDO ATMOSPHERIC-EXO ATMOSPHERIC RADAR MODELING, VOLUME II. PAR-ETC(U)
JUN 76 R J HANCOCK, F H CLEVELAND F30602-73-C-0380

RADC-TR-76-186-VOL-2-PT-1 NL

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<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
IPY	R	I	Array representing the shift register used to generate the pseudo random sequence. The storage cells of this shift register contains either 1 or 0. The user can specify the initial condition of this register if desired.
NSR	R	I	Number of stages in the shift register.

c. MODEPH = 3; User Specified Phase Code

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
MODEPH	R	I	Set = 3 for this mode
NSUBP	R	I	Number of subpulses. For this mode this parameter is limited to 35.
CODE	R	B	Word containing the phase code. Each bit of this 36 bit word represents the phase of one subpulse. The phase for the first subpulse is determined by the LSB; i.e. right most bit.

4. CALLING SEQUENCES:

CALL PHENC (\$mmmm)

Where: mmmm is the statement number to which control will be transferred if an error is detected in the input data.

5. RESTRICTIONS, RECOMMENDATIONS, MISCELLANEOUS DATA

a. Reference for Barker and Pseudo random phase codes:

Skolnik, M. I.: RADAR HANDBOOK, McGraw-Hill Book Company, New York, 1970, pp 20-19 and 20-20.

b. Flow Chart: Page 9-167

c. Cross Reference Table: Page 9-229

6. THEORY OF OPERATION

This module generates a phase code determined by the input parameters and loads the array PCODE with the phase code. The operations performed for MODEPH = 1 or 3 consist of connecting bits of the word CODE into phase angles. A binary "1" is converted into 180 degrees and a binary "0" is converted into 0 degrees.

Figure PHDEC-1 is a block diagram of the shift registers used to generate the pseudo random phase codes. The parameter NSR determines the selection of shift register taps (Reference Skolnik, p 20-20, table 6). The output from the delay line is converted to a phase code according to the procedure outlined in the preceding paragraph.

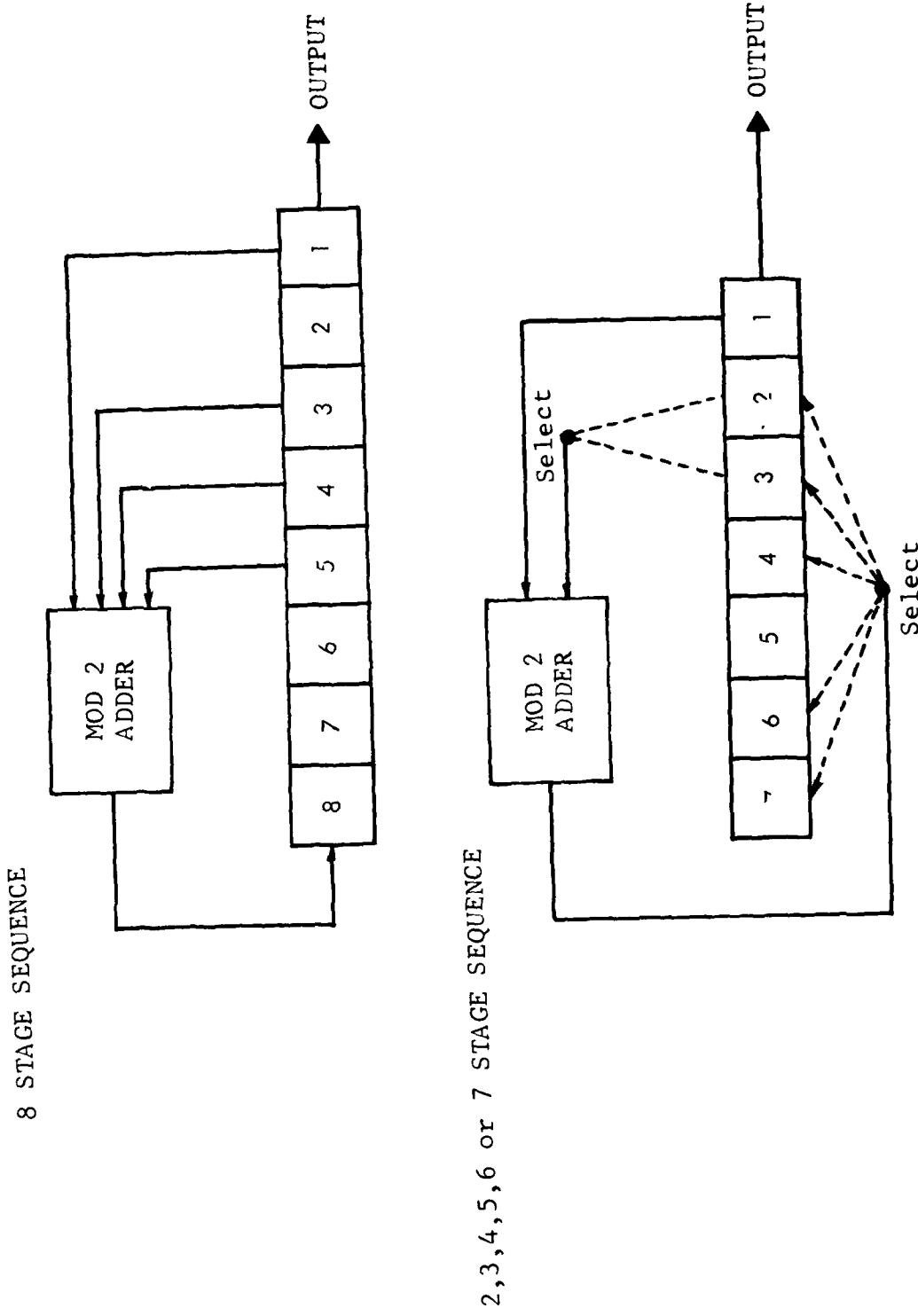


Figure PHENC-1 BLOCK DIAGRAM OF PSEUDO-RANDOM PHASE CODE GENERATORS

4-104
 4010 SUBROUTINE PHNC(*)
 4020 COMMON/BLK2/ B(200),PCODE(300)
 4030 EQUIVALENCE (B(164), NSURF), (B(165), MODEPH),
 4040 * (B(166), NSR) + (B(167), IPY(1)) ,
 4050 * (B(168), CODE)
 4060 DIMENSION IPY(5),RCDE(10)
 4070 DATA ECODE/1,0,0,0,0,0,0,0,0,0/5000,0,0,0,0,0,0,0,0,0/5000,0,0,0/
 4080 IF (MULPH.EQ.1) CODE=BLCPD(NSURF)
 4090 IF (MULPH.EQ.1.0E-6*MODEPH.EQ.0.3) CODE=100
 4100 IT=2
 4110 IF (NSR.EQ.0) NSR=1
 4120 DO 300 J=1,NSURF
 4130 ISUM=IPY(1)+IPY(11)
 4140 IF (ISUM.NE.0) GOTO 150
 4150 ISUM=ISUM+IPY(5)+IPY(51)
 4160 IF (ISUM.EQ.0) ISUM=0
 4170 IF (ISUM.EQ.0) ISUM=1
 4180 IF (ISUM.EQ.0) ISUM=0
 4190 IPY(NSR+IT)=ISUM
 4200 FCODE(1)=ISUM*IPY(1)
 4210 DO 200 K=1,NSR
 4220 IPY(K)=IPY(K+1)
 4230 IT=0
 4240 RETURN
 4250 IT=1
 4260 IF (ISUM.EQ.0) RETURN 1
 4270 K=1
 4280 IF (ISUM.EQ.0) RETURN
 4290 IT=0
 4300 IF (ISUM.EQ.0) IT=1
 4310 FCODE(1)=ISUM*IPY(1)
 4320 FCODE(1)=ISUM*IPY(1)
 4330 IT=1
 4340 RETURN
 4350 IT=0
 4360 RETURN
 4370 IT=1
 4380 RETURN
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 10000 RETURN

SUBROUTINE RDIGFL

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
RDIGFL	LTI-4	405
RDFNCL	LTI-4	406

2. PURPOSE:

This subroutine is used to simulate a double delay digital filter and is capable of synthesizing a filter transfer function having two poles and two zeros.

3. INPUT PARAMETERS:

Name	O/R	T	Description
FF0	0	F	Feed - forward coefficient - 0 delay
FF1	0	F	Feed - forward coefficient - 1 delay
FB1	0	F	Feedback coefficient - 1 delay
FB2	0	F	Feedback coefficient - 2 delay

4. CALLING SEQUENCES:

CALL RDIGFL (X,Y)

Where: X contains the Input Waveform - R
 Y contains the Input Waveform - I
 X contains the Output Waveform - R
 Y contains the Output Waveform - I

The storage registers (RR1, RR2, RI1, and RI2) are cleared before execution begins.

CALL RDFNCL (X,Y)

Where: X contains the Input Waveform - R
 Y contains the Input Waveform - I
 X contains the Output Waveform - R
 Y contains the output Waveform - I

The storage registers are not cleared before execution begins.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. Flow Chart: Page 9-100
- b. Cross Reference Table: Page 9-221

6. THEORY OF OPERATION

The block diagram of the two delay digital filter simulated by this module is shown in Figure RDIGFL-1. The Z-plane transfer function is given by the following expression:

$$T(z) = \frac{FF\emptyset z^2 + \frac{FF1}{FF\emptyset} z + 1/\emptyset}{z^2 - FB1 z - FB2}$$

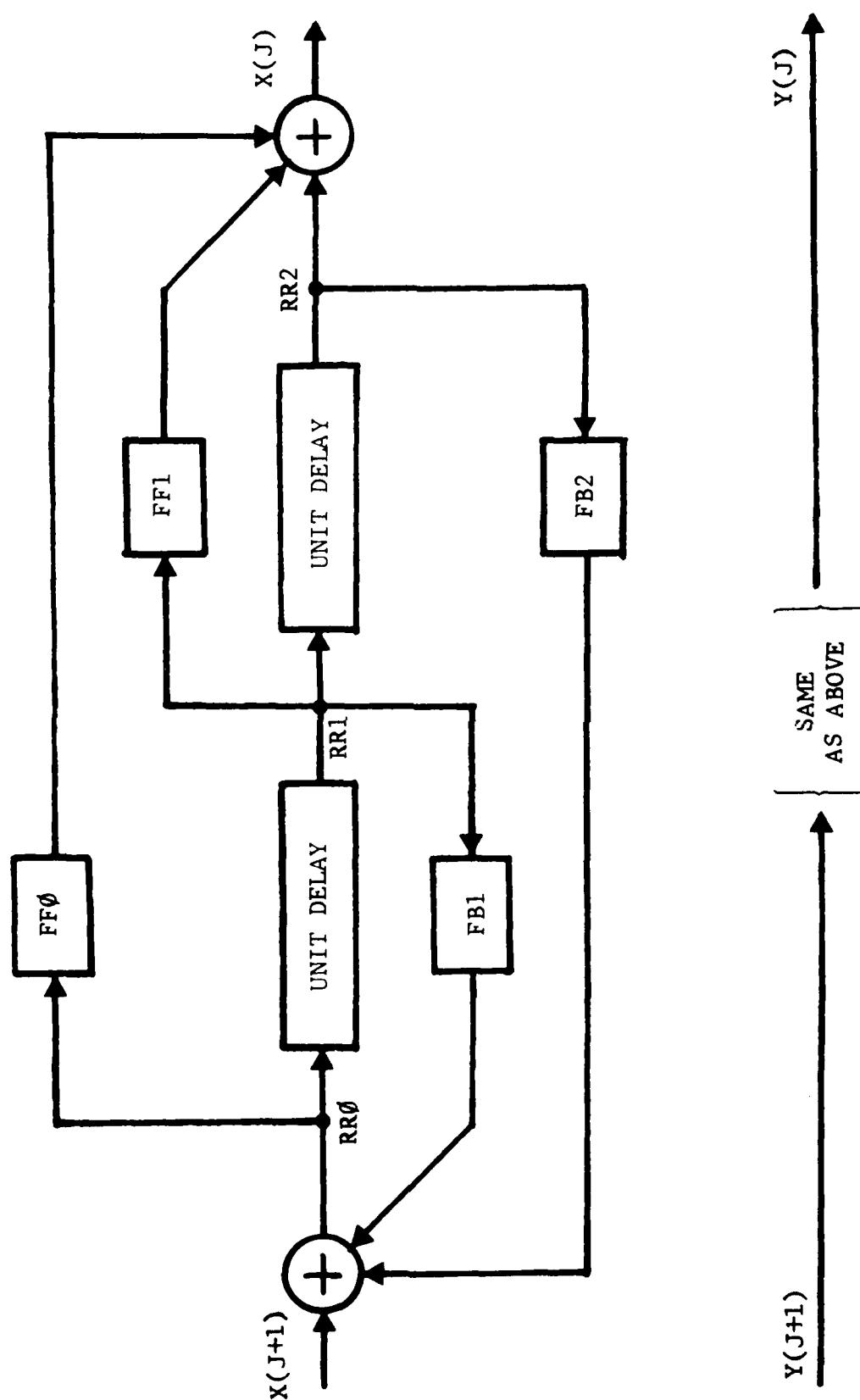


Figure RDIGFL-1 BLOCK DIAGRAM OF RDIGFL/RDFNCL

2670 SUBROUTINE RUDIGFL (X,Y) 4-108
2671 COMMON/BLK1/BK1(500)
2672 EQUIVALENCE (BK1(68), FF0), (BK1(69), FF1), (BK1(70), FF2),
2673 * (BK1(71), FB1), (BK1(72), FB2)
2674 DATA N143/-3/
2675 DIMENSION X(11),Y(11)
2676 RK1=0.0
2677 RK2=0.0
2678 K11=0.0
2679 K12=0.0
2680 ENTRY RUDIGFL (X,Y)
2681 N=BLOC(X(N143))
2682 DO 10 J=1,N
2683 KF0=KK1*FB1+KR2*FB2+X(J)
2684 KI0=K11*FB1+K12*FB2+Y(J)
2685 X(J)=KF0*RF0+KR1*FF1+RR2
2686 Y(J)=KI0*RF0+K11*FF1+R12
2687 RR2=RK1
2688 KK1=KK0
2689 K12=K11
2690 K11=K10
2691 10 CONTINUE
2692 RETURN
2693 END

SUBROUTINE RNDARY

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
RNDARY	SOU-1	214, 215
ADDRND	SOU-1S	235, 236
ADRND	SOU-1S	237

2. PURPOSE:

This subroutine loads an array with random numbers generated by the random number generator function subroutine RRAND.

3. INPUT PARAMETERS:

Name	O/R	T	Description
NPTS	R	I	Number of random distribution samples to be loaded into the array (RNDARY only).
NTYPE	R	I	Code indicating the type of random distribution to be used (RNDARY and ADDRND only).
TI	R	F	Simulation sampling increment (RNDARY only).

4. CALLING SEQUENCES:

CALL RNDARY(RND)

Where: RND contains the Output Waveform

CALL ADDRND(RND)

Where: RND contains the Input Waveform

RND contains the Output Waveform

CALL ADRNDC(RND,RNDY)

Where: RND contains the Input Waveform - R
RNDY contains the Input Waveform - I
RND contains the Output Waveform - R
RNDY contains the Output Waveform - I
This module is used only to add Gaussian samples to the input waveform

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. User supplied function subprogram RRAND is called by the subprogram and must be initialized via NL101 or NL102 before this subroutine is executed.
- b. The random distribution code (NTYPE) is as follows:
 - (1) Floating point uniform distribution with specified mean and extent.
 - (2) Floating point Rayleigh distribution with specified standard deviation.
 - (3) Floating point Gaussian distribution with specified mean and standard deviation.
 - (4) Positive integer uniform distribution from 0 to $2^{**}36$.
 - (5) Not used by this subprogram.
 - (6) Swerling Target Models #1 & #2 with specified mean cross section.
 - (7) Swerling Target Models #3 & #4 with specified mean cross section.
 - (8) Sine distribution.
- c. Flow Chart: Page 9-150
- d. Cross Reference Table: Page 9-227

6. THEORY OF OPERATION

The mechanization equations for each entry point are the following:

RNDARY: $RND(J) = RRAND(NTYPE)$; $KJ \leq NPTS$

ADDRND: $RND(J) = RND(J) + RRAND(NTYPE)$; the range of J is determined by the input array.

ADRND: $RND(J) = RND(J) + RRAND(3)$
 $RNDY(J) = RNDY(J) + DUM$

where: $RRAND(3)$ contains the cosine gaussian distribution sample

DUM contains the sine gaussian distribution sample

4-112

3867	SUBROUTINE RNDARY(FND)	
3868	COMMON/ZK1/ZK1(500)	R
3869	COMMON/ZERKNDZ/RNDDAT(141)	
3870	DIMENSION KND(1),RNODY(1)	
3871	EQUIVALENCE (RK1(44), NPTS - 1),(K1(45), NTYFL)	
3872	EQUIVALENCE (RK1(12), T1)	
3873	DATA N193,N194,N195,N196/-3,-2,-1,0/	R
3874	C	R
3875	DO 10 I=1,NPTS	
3876	KND(I)=RNDRAND(NTYPE)	
3877	10 CONTINUE	
3878	END(N193)=RNDRND(NPTS)	
3879	END(N194)=0.0	
3880	KNL(N195)=T1	
3881	RETURN	
3882	ENTRY ADDRND(FND)	
3883	NPTS=RND(FND(N193))	RN
3884	DO 20 I=1,NPTS	R
3885	KND(I)=RNDRND(1)+RNDRAND(NTYPE)	R
3886	20 CONTINUE	R
3887	C	R
3888	RETURN	R
3889	ENTRY ADDRNDRND(FND,RNODY)	
3890	NPTS=RND(FND(N193))	
3891	DO 40 I=1,NPTS	
3892	FND(I)=KND(I)+RNDRAND(NTYPE)	
3893	RNODY(I)=RNODY(I)+RNDDAT(9)	
3894	40 CONTINUE	
3895	RETURN	
3896	END	

SUBROUTINE SHIFT

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
SHIFT	LTI-1	224,225
SHIFTS	LTI-1S	226,227
RSHIFT	LTI-1	229,230
RSHFTS	LTI-1S	231,232

2. PURPOSE:

This subroutine is used to delay a waveform in time and/or introduce a constant phase shift.

3. INPUT PARAMETERS:

Name	O/R	T	Description
TØ	R	F	Time delay
THT	R	F	Phase shift
TJIT	O	F	Time delay jitter
SIMFØ	R	F	Center frequency to be used in computing time delay effect.

4. CALLING SEQUENCES:

CALL SHIFT (X,Y,A,B)

Where: X contains the Input Waveform - R
 Y contains the Input Waveform - I
 A contains the Output Waveform - R
 B contains the Output Waveform - I

The basic mechanization equation for this entry point is the following:

$$A(J) + jB(J) = [X(J) + jY(J)] * e^{j[THT - 2\pi(FSTART+FI*J)T\theta]}$$

Where: FI = frequency increment
FSTART = frequency corresponding to the first element of the input array

CALL SHIFTS (X,Y,A,B)

Where: X contains the Input Waveform - R
Y contains the Input Waveform - I
A contains the Output Waveform - R
B contains the Output Waveform - I

The basic mechanization equation for this entry point is the following:

$$A(J) + jB(J) = A(J) + jB(J) + [X(J) + jY(J)] * e^{j[THT - 2\pi(FSTART + FI*J)T\theta]}$$

CALL RSHIFT (X,Y,A,B)

Where: X contains the Input Waveform - R
Y contains the Input Waveform - I
A contains the Output Waveform - R
B contains the Output Waveform - I

The basic mechanization equation for this entry point is the following:

$$A(J) + jB(J) = [X(J) + jY(J)] * e^{j[THT - 2\pi(SIMF\theta + FI*J)(T\theta + p \cdot TJIT)]}$$

where p is a sample of a random process having a uniform distribution from -1/2 to 1/2.

CALL RSHFTS(X,Y,A,B)

Where: X contains the Input Waveform - R
Y contains the Input Waveform - I
A contains the Output Waveform - R
B contains the Output Waveform - I

The basic mechanization equation for this entry point is the following:

$$A(J) + jB(J) = A(J) + jB(J) + [X(J) + jY(J)] * e^{j[THT - 2\pi(SIMF\theta + FI * J) \cdot (T\theta + p \cdot TJIT)]}$$

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

a. Flow Chart: Page 9-63

b. Cross Reference Table: Page 9-216

6. THEORY OF OPERATION

If the Fourier transform pair is given for the signal $s(t)$:

$$s(t) \longleftrightarrow S(f)$$

$$\text{then } s(t-t_0) \longleftrightarrow S(f) e^{-j2\pi f t_0}$$

This expression was derived in reference 1.

In addition the introduction of a constant phase shift in the time waveform results in the same constant phase shift in the frequency spectrum, e.g.

$$s(t)e^{j\theta} = S(f) e^{j\theta}$$

Note: Since these subroutines have classification code LTI-1 or 1S the input and output waveforms are in the frequency domain.

4-116

1901 SUBROUTINE SHIFT(X,Y,A,B)
1902 COMMON/BK1/ BK1(200)
1903 EQUIVALENCE (BK1(180),T0),(BK1(181),TH1),(BK1(182),TH11)
1904 * ,(BK1(8),SIMFO)
1905 DIMENSION X(1),Y(1),A(1),B(1)
1906 DATA N193,N194,N195,N196/-3,-2,-1,0/
1907 DATA PI2,EX/6.2831853,2.9103830E-11/ 1780
1908 C
1909 ICOM=0
1910 TUK=TU
1911 GO TO 10
1912 C
1913 ENTRY KSHIFT(X,Y,A,B)

08/11/75

INPUT LISTING

AUTOFLOW CHART SET - FWD/SCL RADSIM

H-116a

CARD NO.

CONTENTS

1914	ICON=0
1915	GD TO 27
1916	C
1917	ENTRY SHIFTS(X,Y,A,B)
1918	ICON=1
1919	TUR=10
1920	GD TO 10
1921	C
1922	ENTRY ASHFTS(X,Y,A,B)
1923	ICON=1
1924	GD TO 27
1925	C
1926	TO NPTS=1000(LA(1931))
1927	TF((TUR+0.0)*GD TO 20
1928	NPTS2= NPTS/2
1929	TRANS=1
1930	KERFES=1
1931	KULI=1
1932	TF1=TF2=0.0
1933	PH1=1.0*PI+TUR+TF1
1934	DEFLH=X(N195)*TUR
1935	PH= (PH-AINT(PH))*PI?
1936	DEFLH= DEFLH-AINT((LELPH))*PI2
1937	ACDEF= COS(DEFLH)
1938	ASDEF= SIN(DEFLH)
1939	GD= COS(FS)
1940	GD= SIN(FS)
1941	GD TO 45
1942	C

4-17

2. Title Information
1944 ACTEL=1.0
1947 ASCEL=0.0
1948 USE= USE (THT)
1949 USE= USE (THT)
1950 RELOCATE
1951 TRASPR
1952 N=1
1953 KLL=2
1954 C
1955 ZD=1.0 (ZD=1.0) X=0.0
1956 C
1957 J=1.0 (J=1.0) X=(J+1)Y(J+1)
1958 J=1.0 (J=1.0) X=(J+1)Y(J+1)
1959 J=1.0 (J=1.0) X=(J+1)Y(J+1)
1960 J=1.0 (J=1.0) X=(J+1)Y(J+1)
1961 J=1.0 (J=1.0) X=(J+1)Y(J+1)
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1968 J=1.0 (J=1.0) X=(J+1)Y(J+1)
1969 J=1.0 (J=1.0) X=(J+1)Y(J+1)
1970 J=1.0 (J=1.0) X=(J+1)Y(J+1)

CRZ1177

ROUTINE LISTING

AUTOFLOW CRATE 001 - FNU/SCL - FAD5JM

4-117a *****

LINE NO.	*****	CONTENTS
1972		DL=4000.0=E1*NETSC
1973		TIME=X(K)
1974		Z(K)=A(K)+TIME*CS-Y(K)*SN
1975		C(K)=B(K)+Y(K)*US+TIME*SN
1976		TIME=CS
1977		US=US*ALUE-LIN*VALUE
1978		SUM=SALUE+TIME*VALUE
1979		K=N+KUE
1980		END=OUTFILE
1981	C	
1982		END=11*(TIME+CS)+DL-TIME
1983		TIME=CS
1984		K=N+KUE
1985		K=N+LUE-1
1986		TIME=VALUE
1987		US=VALUE-VALUE
1988		END=OUTFILE
1989		END=10-LUE
1990		END=OUTFILE
1991	C	
1992		Z(0,18)=X(0,18)
1993		X(0,19)=X(0,19)
1994		A(0,19)=X(0,19)
1995		C(0,19)=X(0,19)
1996		U(0,19)=X(0,19)
1997		D(0,19)=X(0,19)
1998		E(0,19)=X(0,19)
1999	C	
2000		END=1
2001		END

SUBROUTINE SWPINT

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
SWPINT	LTI-4	434,435
NCSWPI	LTI-4	436,437

2. PURPOSE:

This subroutine is used to simulate a video post detection sweep integrator.

3. INPUT PARAMETERS:

Name	O/R	T	Description
FBCK	R	F	Feedback coefficient

4. CALLING SEQUENCES:

CALL SWPINT (DIN, DOUT)

Where: DIN contains the Input Waveform

DOUT contains the Output Waveform

The range bin storage array (SRI) is cleared before execution begins.

CALL NCSWPI (DIN, DOUT)

Where: DIN contains the Input Waveform

DOUT contains the Output Waveform

The range bin storage array (SR1) is not cleared prior to execution except for the first execution of this subroutine.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. The maximum number of range bins simulated is 2048. If more than 2048 range samples are contained in

the input array, only the first 2048 are processed.

b. Flow Chart: Page 9-204

c. Cross Reference Table: Page 9-234

6. THEORY OF OPERATION

The block diagram of the video sweep integrator simulated by this module is shown in Figure SWPINT-1. The Z-plane transfer function for each range bin is given by the following expression:

$$T(Z) = \frac{Z}{Z - FBCK}$$

The delay represented by the Z operator is determined by the radar pulse repetition interval.

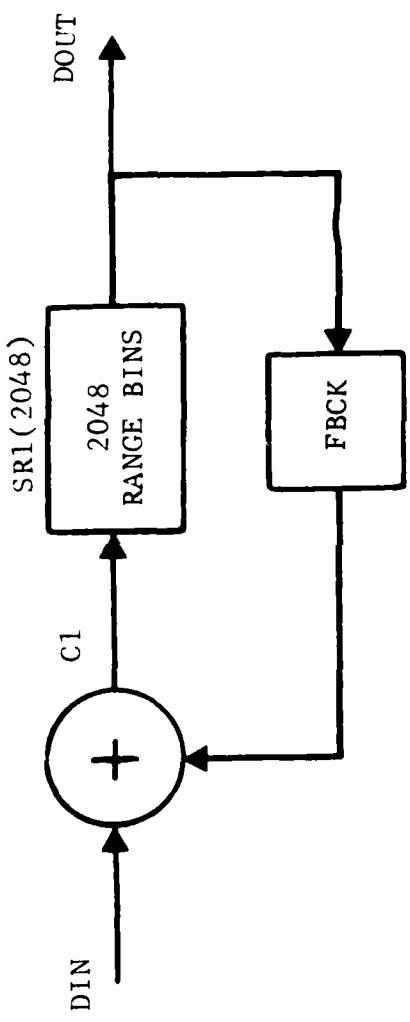


Figure SWPINT-1 BLOCK DIAGRAM OF SWPINT/NCSWPI

4-121

5273.	EXECUTIVE SWPRINT(DIN,DOUT)	UC7PL004
5274.	COMMON/DK1/ZK1(500)	UC7PL001
5275.	DIMENSION DIN(1),DLUT(1),SR1(2048)	UC7PL002
5276.	EQUIVALENCE (DK1(21), IDMY) , (DK1(75), FCK)	UC7PL003
5277.	DATA N143,N144,N145,N146/-3,-2,-1,0/	UC7PL004
5278.	DATA TFLG/0/	UC7PL005
5279.	ICON=1	60
5280.	DE TL 40	61
5281.	ENTRY ALSWH(DIN,DOUT)	62
5282.	ICON=0	63
5283.	40 IF(TFLG,LW=1,AND=ICON,LW=2) DE TL 50	64
5284.	DE 20 J=1,2,48	65
5285.	SR1(J)=0.0	UC7PL006
5286.	DE TL,ICON,DE	UC7PL007
5287.	TFLG=1	66
5288.	DE CONTINUE	67
5289.	N = 1000000.0*(1.0+1.0E-11)	UC7PL011
5290.	DE TL,ICON,DE	UC7PL012
5291.	DE, 0.048	UC7PL013
5292.	WHILE(J<N)	UC7PL014
5293.	35 FORMAT * TOO MANY POINTS IN INPUT ARRAY...FIRST 2048 PROCESSED*)UC7PL015	
5294.	20 DOUT(N)=0.0*ONE(N)	UC7PL016
5295.	DCUT(N)=0.0194	UC7PL017
5296.	DCUT(N)=1.0*(N/1000)	UC7PL018
5297.	DE TL J=1,48	UC7PL019
5298.	DCUT(J)+SR1(J)*FCK	UC7PL020
5299.	DCUT(J)=SR1(J)	UC7PL021
5300.	SR1(J)=0.0	UC7PL022
5301.	DE CONTINUE	UC7PL023
5302.	END	UC7PL024
5303.	END	UC7PL025

SUBROUTINE TARGET

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
TARGET	LTI-2	501
TGTNCL	LTI-2S	502

2. PURPOSE:

This subroutine simulates a target represented by a set of discrete scattering centers.

3. INPUT PARAMETERS:

Name	O/R	T	Description
F \emptyset	R	F	RF Center Frequency
FEXT	R	F	Simulation bandwidth
FI	R	F	Frequency increment of the output transfer function
HTGT	0	F	Height of Target
RTGT \emptyset	0	F	Range to target (R in Figure 1) (Used to compute target return variation as a function of range and altitude)
ANGTGT	0	F	Angle from the radar reference line to the target (θ in Figure 1)
TORINT	0	F	Angle from Reference line #1 to the target coordinate system reference line (\emptyset in Figure 1). Reference line #1 is parallel to the radar coordinate system reference line and passes through the center of target rotation.

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
NSCAT	R	I	Number of scatterers
TSCAT	R	F	Array containing the location and radar cross section of each scatterer. TSCAT (1,k) is the radar cross section of the kth scatterer (σ_k in Figure 1). TSCAT(2,k) is the range coordinate of the kth scatterer in the target coordinate system (r_k in Figure 1). TSCAT(3,k) is the angle coordinate of the kth scatterer in the target coordinate system (β_k in Figure 1).
R000	R	F	Range of target in the simulation (used to compute time delay only)
TGTVEL	0	F	Target radial velocity
TIME	0	F	Elapsed time since beginning of simulation

4. CALLING SEQUENCES:

CALL TARGET (X,Y)

Where: X contains the Output Waveform - R
Y contains the Output Waveform - I

CALL TGTNCL (X,Y)

Where: X contains the Input Waveform - R
Y contains the Input Waveform - I
X contains the Output Waveform - R
Y contains the Output Waveform - I

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. The discrete scattering center representation used herein is obtained by imaging coherent short pulse measurements made on the target or a model of the target. The imaging procedure is described in Appendix H of this report.

b. The target representation implemented herein includes the pulse to pulse phase shift due to target motion with respect to the radar system. However, the intrapulse phase shift is not included in this model.

c. Flow Chart: Page 9-109

d. Cross Reference Table: Page 9-222

6. THEORY OF OPERATION

The discrete scatterer target scintillation model is based on the premise that a target can be represented as an ensemble of scattering centers. These scattering centers are assumed to be sufficiently small that they can be represented by impulses. Therefore, this model can be described by the following expression:

$$g(t) = \sum_{n=1}^N \sqrt{\sigma_n^-} \delta(t - t_n)$$

where σ_n is the radar cross section of the nth scatterer

t_n is the time delay of the nth scatterer

$\delta(\)$ is the Dirac delta function.

The Fourier transform of the above expression is given by the following equation:

$$G(f) = \int_{-\infty}^{\infty} \sum_{n=1}^N \sqrt{\sigma_n^-} \delta(t - t_n) e^{-j2\pi ft} dt$$

$$G(f) = \sum_{n=1}^N \sqrt{\sigma_n^-} e^{-j2\pi f t_n}$$

In the target model the following equations were used in evaluating the target response in the frequency domain.

NSCAT

$$X(K) = G_{\epsilon}(\text{ELANG}) * G_{\downarrow}(\text{ANGTGT}) * \sum_{J=1}^{\text{NSCAT}} \sqrt{\sigma_J} \cos 2\pi K(FI+FSTART)t_n$$

NSCAT

$$Y(K) = G_{\epsilon}(\text{ELANG}) * G_{\downarrow}(\text{ANGTGT}) * \sum_{J=1}^{\text{NSCAT}} \sqrt{\sigma_J} \sin 2\pi K(FI+FSTART)t_n$$

where:

K is the frequency index

FI is the frequency increment

FSTART is the starting frequency

FSTART = FO - FEXT/2

G_{\downarrow} is the antenna azimuth gain function

G_{ϵ} is the antenna elevation gain function

$$\text{ELANG} = \text{SIN}^{-1} (\text{HTGT}/\text{RTGT})$$

t_n is the time displacement of the scatterer

$$t_n = \frac{1}{0.149896} \text{RTGT} + \text{TSCAT}(2,J) * \text{COS}(\theta - \phi - \text{TSCAT}(3,J))$$

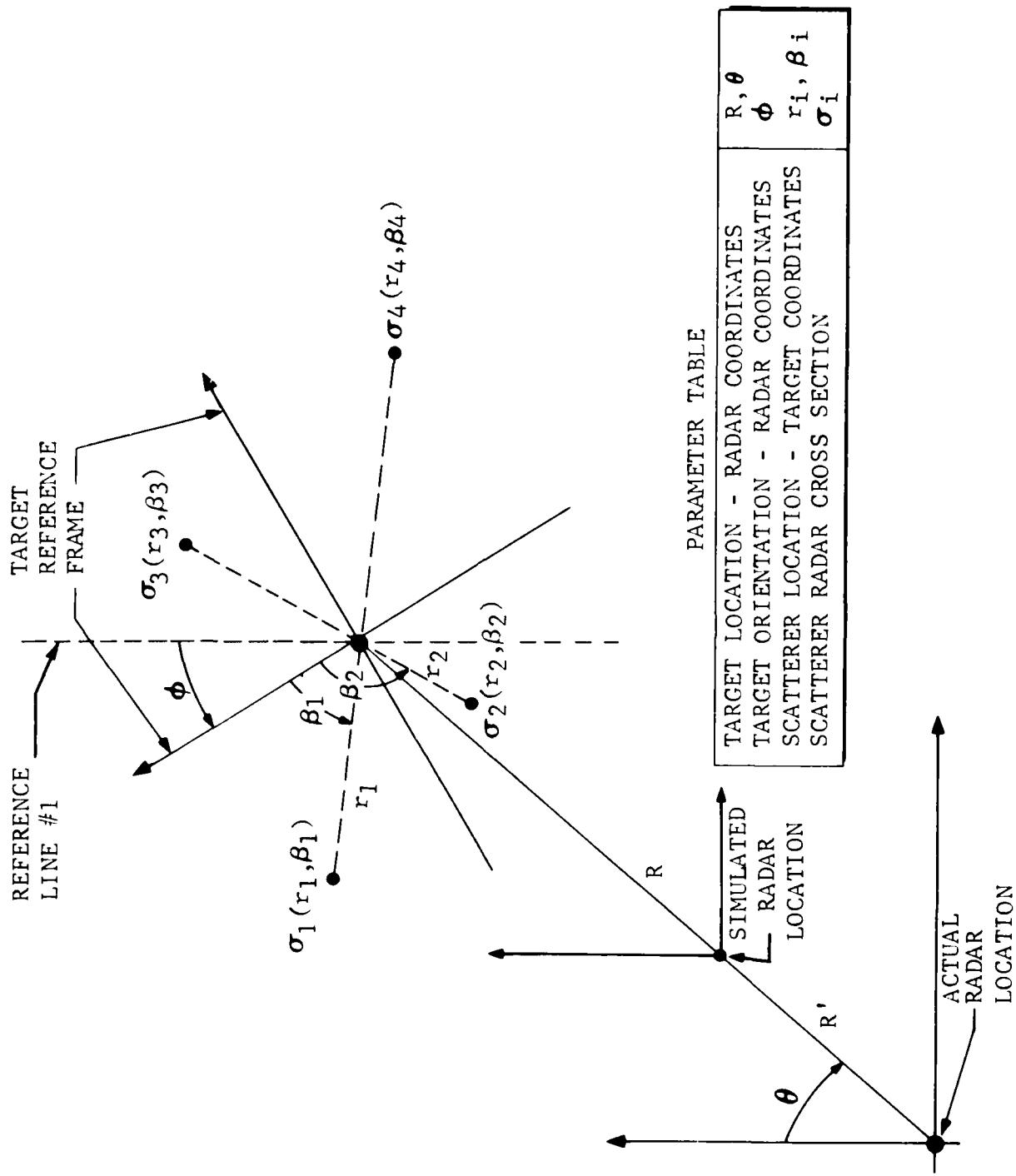


Figure TARGET-1 Target Model Geometry

4-12
 2072 SUBROUTINE TARGET(X,Y)
 2073 COMMON/BK1/ EK1(200),TSCALE(3,100)
 2074 EQUIVALENCE (EK1(3), F0) , (EK1(4), FEXT) ,
 2075 F1 ,
 2076 F2 ,
 2077 F3 ,
 2078 F4 ,
 2079 F5 ,
 2080 F6 ,
 2081 DIMENSION X(1) , Y(1)
 2082 DATA N140,N141,N142,N143/-3,-2,-1,0/
 2083 DATA PI/3.141592653/
 2084 C
 2085 TOTINT
 2086 GO TO 20
 2087 C
 2088 C X,Y = TOTAL(X,Y) 4-127
 2089 TOTINT
 2090 C
 2091 C CONTINUE
 2092 RET1 = TOTINT(FEXT / F1)
 2093 RET2 = RET1*2
 2094 RET3 = RET2*2
 2095 RET4 = RET3*2
 2096 RET5 = RET4*2
 2097 RET6 = RET5*2
 2098 RET7 = RET6*2
 2099 RET8 = RET7*2
 2100 RET9 = RET8*2
 2101 RET10 = RET9*2
 2102 RET11 = RET10*2
 2103 RET12 = RET11*2
 2104 RET13 = RET12*2
 2105 RET14 = RET13*2
 2106 RET15 = RET14*2
 2107 RET16 = RET15*2
 2108 RET17 = RET16*2
 2109 RET18 = RET17*2
 2110 RET19 = RET18*2
 2111 RET20 = RET19*2
 2112 RET21 = RET20*2
 2113 RET22 = RET21*2
 2114 RET23 = RET22*2
 2115 RET24 = RET23*2
 2116 RET25 = RET24*2
 2117 RET26 = RET25*2
 2118 RET27 = RET26*2
 2119 RET28 = RET27*2
 2120 RET29 = RET28*2
 2121 RET30 = RET29*2
 2122 RET31 = RET30*2
 2123 RET32 = RET31*2
 2124 RET33 = RET32*2
 2125 RET34 = RET33*2
 2126 RET35 = RET34*2
 2127 RET36 = RET35*2
 2128 RET37 = RET36*2
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 2131 RET40 = RET39*2
 2132 RET41 = RET40*2
 2133 RET42 = RET41*2
 2134 RET43 = RET42*2
 2135 RET44 = RET43*2
 2136 RET45 = RET44*2
 2137 RET46 = RET45*2
 2138 RET47 = RET46*2
 2139 RET48 = RET47*2
 2140 RET49 = RET48*2
 2141 RET50 = RET49*2
 2142 RET51 = RET50*2
 2143 RET52 = RET51*2
 2144 RET53 = RET52*2
 2145 RET54 = RET53*2
 2146 RET55 = RET54*2
 2147 RET56 = RET55*2
 2148 RET57 = RET56*2
 2149 RET58 = RET57*2
 2150 RET59 = RET58*2
 2151 RET60 = RET59*2
 2152 RET61 = RET60*2
 2153 RET62 = RET61*2
 2154 RET63 = RET62*2
 2155 RET64 = RET63*2
 2156 RET65 = RET64*2
 2157 RET66 = RET65*2
 2158 RET67 = RET66*2
 2159 RET68 = RET67*2
 2160 RET69 = RET68*2
 2161 RET70 = RET69*2
 2162 RET71 = RET70*2
 2163 RET72 = RET71*2
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 2171 RET80 = RET79*2
 2172 RET81 = RET80*2
 2173 RET82 = RET81*2
 2174 RET83 = RET82*2
 2175 RET84 = RET83*2
 2176 RET85 = RET84*2
 2177 RET86 = RET85*2
 2178 RET87 = RET86*2
 2179 RET88 = RET87*2
 2180 RET89 = RET88*2
 2181 RET90 = RET89*2
 2182 RET91 = RET90*2
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 2184 RET93 = RET92*2
 2185 RET94 = RET93*2
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 2187 RET96 = RET95*2
 2188 RET97 = RET96*2
 2189 RET98 = RET97*2
 2190 RET99 = RET98*2
 2191 RET100 = RET99*2
 2192 RET101 = RET100*2
 2193 RET102 = RET101*2
 2194 RET103 = RET102*2
 2195 RET104 = RET103*2
 2196 RET105 = RET104*2
 2197 RET106 = RET105*2
 2198 RET107 = RET106*2
 2199 RET108 = RET107*2
 2200 RET109 = RET108*2
 2201 RET110 = RET109*2
 2202 RET111 = RET110*2
 2203 RET112 = RET111*2
 2204 RET113 = RET112*2
 2205 RET114 = RET113*2
 2206 RET115 = RET114*2
 2207 RET116 = RET115*2
 2208 RET117 = RET116*2
 2209 RET118 = RET117*2
 2210 RET119 = RET118*2
 2211 RET120 = RET119*2
 2212 RET121 = RET120*2
 2213 RET122 = RET121*2
 2214 RET123 = RET122*2
 2215 RET124 = RET123*2
 2216 RET125 = RET124*2
 2217 RET126 = RET125*2
 2218 RET127 = RET126*2
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 2223 RET132 = RET131*2
 2224 RET133 = RET132*2
 2225 RET134 = RET133*2
 2226 RET135 = RET134*2
 2227 RET136 = RET135*2
 2228 RET137 = RET136*2
 2229 RET138 = RET137*2
 2230 RET139 = RET138*2
 2231 RET140 = RET139*2
 2232 RET141 = RET140*2
 2233 RET142 = RET141*2
 2234 RET143 = RET142*2
 2235 RET144 = RET143*2
 2236 RET145 = RET144*2
 2237 RET146 = RET145*2
 2238 RET147 = RET146*2
 2239 RET148 = RET147*2
 2240 RET149 = RET148*2
 2241 RET150 = RET149*2
 2242 RET151 = RET150*2
 2243 RET152 = RET151*2
 2244 RET153 = RET152*2
 2245 RET154 = RET153*2
 2246 RET155 = RET154*2
 2247 RET156 = RET155*2
 2248 RET157 = RET156*2
 2249 RET158 = RET157*2
 2250 RET159 = RET158*2
 2251 RET160 = RET159*2
 2252 RET161 = RET160*2
 2253 RET162 = RET161*2
 2254 RET163 = RET162*2
 2255 RET164 = RET163*2
 2256 RET165 = RET164*2
 2257 RET166 = RET165*2
 2258 RET167 = RET166*2
 2259 RET168 = RET167*2
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 2262 RET171 = RET170*2
 2263 RET172 = RET171*2
 2264 RET173 = RET172*2
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 2266 RET175 = RET174*2
 2267 RET176 = RET175*2
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 2269 RET178 = RET177*2
 2270 RET179 = RET178*2
 2271 RET180 = RET179*2
 2272 RET181 = RET180*2
 2273 RET182 = RET181*2
 2274 RET183 = RET182*2
 2275 RET184 = RET183*2
 2276 RET185 = RET184*2
 2277 RET186 = RET185*2
 2278 RET187 = RET186*2
 2279 RET188 = RET187*2
 2280 RET189 = RET188*2
 2281 RET190 = RET189*2
 2282 RET191 = RET190*2
 2283 RET192 = RET191*2
 2284 RET193 = RET192*2
 2285 RET194 = RET193*2
 2286 RET195 = RET194*2
 2287 RET196 = RET195*2
 2288 RET197 = RET196*2
 2289 RET198 = RET197*2
 2290 RET199 = RET198*2
 2291 RET200 = RET199*2

2924 Y(K)=Y(K)+S4 4-128
2930 TURFUS
2931 CFSU*ACELL-EM*ASDEL
2932 CF=SN*ACELL+ELMF*ASDEL
2933 K=K+KEL
2934 40 CONTINUE
2935 C
2936 IF(IAACELL.LT.10) T=200
2937 ITADSF
2938 FADSF
2939 KULL=1
2940 DFACELEPA=0.0E+0
2941 ZLEPF=ZLEPF
2942 G= T/ V
2943 20 CONTINUE
2944 C
2945 X(1194)=ZC(LRFTS)
2946 X(1194)=X(1194)+T*FLOAT(NFTS)
2947 X(1194)=T
2948 Y(1194)=X(1194)
2949 Y(1194)=X(1194)
2950 Y(1194)=X(1194)
2951 C
2952 C
2953 C
2954 C

SUBROUTINE WEITRE

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
WEITRE	LTI-1 or LTV-4	221
WEITCP	LTI-1 or LTV-4	222
WEITMP	LTI-1 or LTV-4	223

2. PURPOSE:

This subroutine is used to represent (1) a linear time variant device in terms of its measured transfer functions or (2) a linear time varying device in terms of its measured gain (complex) as a function of time.

3. INPUT PARAMETERS:

Name	O/R	T	Description
NPWT	R	I	Number of points used to specify the weighting function
WT	R	F	Array containing the specified weighting function. The specification for the Jth sample is the following:

WEITRE or WEITCP

WT (1,J) = Real component

WT (2,J) = Time

WT (3,J) = Imaginary component
(WEITCP only)

WEITMP

WT (1,J) = Gain

WT (2,J) = Time

WT (3,J) = Phase angle

ORIG O F Amount the independent variables
of the weighting function is to
be shifted.

4. CALLING SEQUENCES:

Real Weighting Function

CALL WEITRE (X, Y, \$mmmm)

Where: X contains the Input Waveform - R
Y contains the Input Waveform - I
X contains the Output Waveform - R
Y contains the Output Waveform - I

Complex Rectangular Weighting Function

CALL WEITCP (X, Y, \$mmmm)

Where: X contains the Input Waveform - R
Y contains the Input Waveform - I
X contains the Output Waveform - R
Y contains the Output Waveform - I

Complex Polar Weighting Function

CALL WEITMP (X, Y, \$mmmm)

Where: X contains the Input Waveform - M
Y contains the Input Waveform - P
X contains the Output Waveform - M
Y contains the Output Waveform - P

\$mmmm is the number of the statement to which
control is transferred if an error is detected.
in the input data.

5. RESTRICTIONS, REQUIREMENTS, AND MISCELLANEOUS DATA

- a. The input weighting function independent variable must be monotonically increasing, except that two adjacent points may be specified with the same value. In this case, if the input value to be weighted falls exactly on that point, the first dependent value specified will be used.
- b. If the extent of the weighting function does not include any part of the input data, the subroutine will perform a nonstandard exit.

- c. If the extent of the weighting function contains only a portion of the input data, all other input points are set to zero.
- d. The subroutine performs a linear interpolation between specified points.
- e. Flow Chart: Page 9-57
- f. Cross Reference Table: Page 9-215

6. THEORY OF OPERATION

The basic mechanization equations for each entry point are as follows:

WEITCP:

$$\begin{aligned} X(J) &= X(J) * XWT - Y(J) * YWT \\ Y(J) &= X(J) * YWT + Y(J) * XWT \end{aligned}$$

A table lookup/linear interpolation scheme is used to determine the complex weight, $XWT + j YWT$. The value of the independent variable used in computing the weight for the Jth sample is given by the following expression:

$$VIV = XORIG + J \cdot DEL - ORIG$$

where: $XORIG$ = Independent variable for first element of the input arrays.

DEL = Independent variable increment between samples of the input array.

WEITRE:

$$X(J) = X(J) * XWT$$

$$Y(J) = Y(J) * XWT$$

The procedure for determination of the weight, XWT , is the same as that described above except YWT is not computed.

WEITMP:

$$X(J) = X(J) * AMPL$$

$$Y(J) = Y(J) + PHAS$$

A table lookup/interpolation scheme is used to determine the complex weight AMPL * EXP (PHAS). The procedure for determining value of the independent variable used in computing the weight is described under WEITCP.

REPORT LISTING

SUBROUTINE WVGU1D

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
WVGU1D	LTI-1	510

2. PURPOSE:

This routine is used to simulate a length of waveguide for the purpose of predicting the effect of nonlinear phase behavior on waveforms.

3. INPUT PARAMETERS:

Name	O/R	T	Description
RFF	R	F	Center frequency of the electromagnetic wave propagating in the waveguide
CFREQ	R	F	Cutoff frequency of the waveguide
XWLENG	R	F	Length of the waveguide

4. CALLING SEQUENCES:

CALL WVGU1D (X,Y)

Where: X contains the Input Waveform - R
Y contains the Input Waveform - I
X contains the Output Waveform - R
Y contains the Output Waveform - I

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

a. References:

Atwater, H. A.; Introduction to Microwave Theory,
McGraw-Hill, New York, 162, Chapter 3.

b. Flow Chart: Page 9-116

c. Cross Reference Table: Page 9-223

6. THEORY OF OPERATION

A hollow rectangular perfectly conducting waveguide excited in only one of its modes has a propagation function which is described by the following expression:

$$\beta_g(f) = \sqrt{k^2 - k_c^2}$$

where: $k = 2\pi f \sqrt{\mu_0 \epsilon_0}$

$$k_c = 2\pi f_c \sqrt{\mu_0 \epsilon_0}$$

f_c = cutoff frequency

Substituting $\frac{1}{C^2} = \mu_0 \epsilon_0$ the following expression is obtained:

$$\beta_g(f) = \frac{2\pi}{C} \sqrt{f^2 - f_c^2}$$

Therefore the transfer function for a length of waveguide considering only the phase term is given by the following expressions:

$$G(f) = e^{-j \frac{2\pi}{C} z \sqrt{f^2 - f_c^2}} ; f_c < f$$

$$= e^{-j \frac{2\pi}{C} z \sqrt{f_c^2 - f^2}} ; f \leq f_c$$

where z is the length of the waveguide.

06/11/75

INPUT LISTING

AUTOFLOW CHART SET - FNU/SCL RADSIM

CARD NO.

CONTENTS

4-137 ****

3074 SUBROUTINE NWGODE(X,Y)
 3075 COMMON/BLK1Z/ VAR(500)
 3076 DIMENSION X(1),Y(1)
 3077 EQUIVALENCE (VAR(140), TFLW), (VAR(147), XWLLNG)
 3078 EQUIVALENCE (VAR(31), FFLW)
 3079 DATA NBS,NEM,N195/-1,-2,-1Z,INST/3,02237,PI/26.263125/
 3080 * (NBS= NUMBER OF ELEMENTS) , (INST=NANOSCALE PER SEC)
 3081 CFL=CFLOW*FFLW
 3082 T1=CNST*XWLLNG
 3083 T2= FFLW
 3084 RFL=SFBL(X(N195))
 3085 FFLW=X(N194)*FFLW
 3086 CFL=FAINST
 3087 DE = 200 J-1,NBS
 3088 FFLW=FFLW*FFLW
 3089 T1=(FFLW*CFL)/CFL 100
 3090 THETA= T1*(TA+FLUAT((J+1)*(THETA)))* PI/2
 3091 CFL=CFL*(TA)
 3092 DE=DEIN(THETA)
 3093 CFL=CFL
 3094 T1=0
 3095 T2= C-1*(CFL*FLUAT(CFL-FL))
 3096 CFL=CFL
 3097 T1=0
 3098 X(J)=X(J)+C-Y(J)*S
 3099 Y(J)=FLW+S+Y(J)*C
 3100 FFLW=FFLW + CFL
 3101 T1=0 CONTINUE
 3102 RETURN

S E C T I O N 5
C O N N E C T I O N M O D U L E S

This section includes all those modules that bind the stimulus/transfer function modules together in order to form the core of the simulation. The functions performed by these modules include array addition or array multiplication (CONV) and conversion between time and frequency domain representations (ZFFT).

SUBROUTINE CONV

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
CONV	Connection	204
CONVMP	Connection	205
DIVA	Connection	206
ADDA	Connection	207, 239

2. PURPOSE:

This subroutine serves to connect simulation modules together by performing array addition, multiplication and division.

3. INPUT PARAMETERS:

None

4. CALLING SEQUENCES:

Complex Rectangular Array Multiplication

CALL CONV (XI, XQ, FI, FQ, \$mmmm)

Where: XI contains the Input Waveform - R Complex
 XQ contains the Input Waveform - I Array #1
 FI contains the Input Waveform - R Complex
 FQ contains the Input Waveform - I Array #2
 XI contains the Output Waveform - R
 XQ contains the Output Waveform - I

mmmm is the return address for a non-standard
return

$$\begin{aligned} XI(J) &= XI(J) * FI(J) - XQ(J) * FQ(J) \\ XQ(J) &= XI(J) * FQ(J) + XQ(J) * FI(J) \end{aligned}$$

Complex Polar Array Multiplication

CALL CONVMP (XI, XQ, FI, FQ, \$mmmm)

Where: XI contains the Input Waveform - M Complex
 XQ contains the Input Waveform - P Array #1
 FI contains the Input Waveform - M Complex
 FQ contains the Input Waveform - P Array #2
 XI contains the Output Waveform - M
 XQ contains the Output Waveform - P

mmmm is the return address for a non-standard return.

$$\begin{aligned} XI(J) &= XI(J) * FI(J) \\ XQ(J) &= XQ(J) + FQ(J) \end{aligned}$$

Complex Polar Array Division

CALL DIVA (XI, XQ, FI, FQ, \$mmmm)

Where: XI contains the Input Waveform - M Complex
 XQ contains the Input Waveform - P Array #1
 FI contains the Input Waveform - M Complex
 FQ contains the Input Waveform - P Array #2
 XI contains the Output Waveform - M
 XQ contains the Output Waveform - P

mmmm is the return address for a non-standard return

$$\begin{aligned} XI(J) &= XI(J)/FI(J) \\ XQ(J) &= XQ(J)-FQ(J) \end{aligned}$$

Array Addition

CALL ADDA (XI, FI, \$mmmm)

Where: XI contains the Input Waveform
 FI contains the Input Waveform
 XI contains the Output Waveform

mmmm is the return address for a non-standard return

$$XI(J) = XI(J) + FI(J)$$

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. The difference in the independent variable increment of the input arrays must be less than or equal to 10^{-4} .
- b. The output is set to zero for any cases where the independent variables of the two arrays do not overlap.
- c. When polar operations are performed the phase angle is measured in degrees.
- d. If the arrays do not overlap, or if they must be shifted more than 4097 increments, the problem will abort and the non-standard return will be used.
- e. Flow Chart: Page 9-60
- f. Cross Reference Table: Page 9-216.

6. THEORY OF OPERATION

Depending upon the entry point through which the subroutine is called, a control flag is set to an integer number 1 to 4. This number indicates to the subroutine the type of operation which is to be performed, either rectangular multiplication, polar multiplication, polar division, or addition. After the flag is set, the two arrays are examined (beginning at statement number 1000) to verify that the values of the increments of the two arrays are within 1/10000 of each other. The arrays are inspected to verify that they overlap, at least in part, and one array is shifted, if required, to align the two origins. If the increments are not within 1/10000 of each other, or if the arrays do not overlap, or if the origins of the two arrays are not within 4097 increments of each other, the problem is aborted. Otherwise, the proper arithmetic manipulation is performed, according to the value of the control flag and the results are placed in the X array(s). The F array(s) remain unmodified after exit from the subroutine. For the divide operation, the X complex array is the dividend and the F complex array is the divisor.

08/11/74

INPUT LISTING

AUTOFLOW CHART SET - FWD/SCL RADSIM

CARD NO.	*****	CONTENTS	S-5a *****
1056		$IXI=IXI+1$ IF(IGN=XI(N194))/ XI(N195) + 0.40)	
1057		IF(I=1+1) IF(IGN=F1(N194))/ XI(N195) + 0.40)	
1058		IF(IXI+NPTS.GT.NXI+1) NPTS=NPTS-1	
1059		IF(I+F1+NPTS.GT.NF1+1) NPTS=NPTS-1	
1060		WRT(6,50) NPTS,IXI,JFI,NXI,NF1,IGN,ENDATA,XI(N194),F1(N194)	
1061		DO 1000 FORMAT(1H ,5I12+4E14.6)	
1062		XI(N195)=B00L(NPTS)	
1063		XI(N194)=IGN	
1064		IF(1.LT.EW.4) GO TO 700	
1065		701 XI(N195)=XI(N193)	
1066		XI(N194)=XI(N194)	
1067		702 CONTINUE	
1068		*****	
1069		GO TO J=1+NPTS	
1070		GO TO (101,102,103,104),ICCN	
1071	C		
1072		101 CONTINUE	
1073		A=XI(IXI)	
1074		XI(J)= A*F1(IF1) ~ XI(IXI)*F1(IF1)	
1075		XU(J)= A*FU(IF1) + XI(IXI)*F1(IF1)	
1076		GO TO 25	
1077	C		
1078		102 CONTINUE	
1079		XI(J)= XI(IXI)*F1(IF1)	
1080		XU(J)= XU(IXI)*FU(IF1)	
1081		GO TO 25	
1082	C		
1083		103 CONTINUE	
1084		XI(J)= XI(IXI)/F1(IF1)	

1688 $XU(J)= XU(IX1)+FU(IF1)$
1689 GO TO 25
1690 C
1691 104 CONTINUE
1692 $XI(J)= XI(IX1)+FI(IF1)$
1693 C
1694 29 IX1=IX1+1
1695 IF1=IF1+1
1696 40 CONTINUE
1697 WRITE(6,201) IX1,IF1
1698 C
1699 RETURN
1700 200 WRITE(6,201)
1701 FORMAT(' INDEPENDENT VARIABLE INCREMENTS DO NOT MATCH ')
1702 RETURN 1
1703 END.

5-6

SUBROUTINE ZFFT

1. MODULE IDENTIFICATION:

<u>Name</u>	<u>Classification Code</u>	<u>Reference Number</u>
ZFFT	Connection	202
ZIFFT	Connection	203
IFT	Connection	Not User Referenced

2. PURPOSE:

This subroutine performs the finite discrete Fourier Transform (ZFFT) and inverse Fourier Transform (ZIFFT or IFT) of a sequence of input data samples. The mechanization is based on the Fast Fourier Transform (FFT) algorithm developed by Langdon and Sande from the approach of J. W. Tukey and J. Cooley.

3. INPUT PARAMETERS:

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
N2	R	I	Power of 2 which determines the total number of prints (NTHPOW) transformed by the FFT.
FSHIFT	R	F	Frequency shift to be applied to frequency domain representation of the waveform.
ICPLXI	O	I	Control flag which indicates the nature of the inverse transform (ZIFFT) input data = 1 complex waveform $Z = X + jY$ = 0 real waveform $Z = X$
ICPLXF	O	I	Control flag which indicates the nature of the forward transform (ZFFT) input data = 1 complex waveform $Z = X + jY$ = 0 real waveform $Z = X$
SIMBW	R	F	Width of output spectrum when forward transform (ZFFT) is performed

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
INORM	R	I	Normalization flag
	= 0;	$f_N = TI$	$\frac{ZFFT}{f_N} = FI$
	= 1;	$f_N = 1.0 / NP$	$f_N = FI$
	= 2;	$f_N = TI$	$f_N = 1.0 / (2^{**N2})$
	= 3;	$f_N = 1.0 / NP$	$f_N = 1.0 / (2^{**N2})$
	= 4;	$f_N = 1.0$	$f_N = 1.0$

4. CALLING SEQUENCES:

Fourier Transform

CALL ZFFT (X,Y)

Where: X contains the Input Waveform - R

Y contains the Input Waveform - I

X contains the Output Waveform - R

Y contains the Output Waveform - I

Increase Fourier Transform

CALL ZIFFT (X, Y)

Where: X contains the Input Waveform - R

Y contains the Input Waveform - I

X contains the Output Waveform - R

Y contains the Output Waveform - I

Inverse FFT only

CALL IFT (X, Y)

Where:

X contains the Input Waveform - R

Y contains the Input Waveform - I

X contains the Output Waveform - R

Y contains the Output Waveform - I

This entry point is used in computing antenna patterns and is called by ANTPAT module only.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. The maximum value of N2 is 13 which gives 8192 transformed samples.
- b. The number of points transformed by the FFT algorithm is 2 raised to an integer power. If the number of input samples is not equal to a power of 2, then zeros are used to fill in the array elements not defined by the input data; i.e., zeros are placed in the input array locations from NP + 1 to 2^{**N2} .
- c. When the Forward Transform is executed the output spectrum is shifted by FSHIFT and has a width of SIMBW: i.e., the output spectrum extends from FSHIFT - SIMBW/2 to FSHIFT + SIMBW/2.
- d. When the Forward Transform is executed the origin of the independent variable X (N194) is set to the discrete frequency nearest FSHIFT - SIMBW/2 since the FFT output consists of a discrete set of frequency samples. When the Inverse Transform is executed the origin of the independent variable X(N194) is set to zero.
- e. The independent variable increment is set to $1.0 / (X(N195)*(2^{**N2POW}))$ for both the forward and inverse transform.
- f. When the inverse transform is executed the input spectrum is shifted by FSHIFT before the FFT is executed. The value of FSHIFT when the inverse transform is performed can be different from the value used when the forward transform was performed.

The following relationship must be satisfied

$$- \frac{FS}{2} \leq FSHIFT \pm SIMBW/2 < \frac{FS}{2}$$

g. Flow Chart: Page 9-125

h. Cross Reference Table: 9-224

6. THEORY OF OPERATION

- a. ZFFT - This entry point connects the time domain representation of a waveform into the corresponding frequency domain representation. The Fourier transform relationship is given by the following expression:

$$S(f) = \int_{-\infty}^{\infty} s(t) e^{-j2\pi ft} dt$$

The basic mechanization equation used in computing the discrete Fourier transform is the following:

$$S_k = f_N \sum_{i=0}^{NP-1} s_i W^{-ki}$$

where: k is the frequency index 0 ≤ k ≤ NTHPOW-1
i is the time index 0 ≤ i ≤ NP-1
 f_N is the normalization factor
 $W = \exp(j2\pi/NTHPOW)$

In general s_i and S_k are complex arrays.

- b. ZIFFT and IFT - These entry points connect the frequency domain representation of a waveform into the corresponding time domain representation. The inverse Fourier transform relationship is given by the following expression:

$$s(t) = \int_{-\infty}^{\infty} S(f) e^{j2\pi ft} dt$$

The basic mechanization equation used in computing the inverse discrete Fourier transform is the following:

NTHPOW-1

$$s_i = f_N \sum_0^{NTHPOW-1} s_k w^{ki} \quad 0 \leq i \leq NTHPOW-1$$

The only difference between ZIFFT and IFT is that IFT performs the inverse FFT only and no normalization is performed. The FFT mechanization utilized in this module evaluates the above expression directly. In order to compute the forward transform using the same inverse FFT the following expression is used.

$$s_k = f_N \left[\sum_0^{NP-1} s_i^* w^{ki} \right]^*$$

SELECTING ZERI(X,Y) 5-12

COMMON/ZERI/ ZERI(60)

DOUBLE PRECISION ZERI,SZERI,C5,SN,C3,P12,SCALE 31

EQUIVALENCE (NZ ,ZR1(1)) ,(ZERI(1,1)),,(ZERI(1,6)),,
+ (ZERI(2,1)),,(ZERI(2,6)),,(ZERI(3,1)),,(ZERI(3,6))

DATA NZ/0/ DATA SZERI/0.666700/ 31

DATA C5/0.8660254,0.5,0.19673,-0.1,-1,0/

DATA SN/0.5,0.866,0.19673,-0.1,-1,0/

DATA X(1),Y(1),L(1),L1,L2,L3,L4 31

PARAMETER RADG, DEGCG, D(16)

EQUIVALENCE (D(8,1)),,(N4ROW,0),,(RADG,0),
+ (C4XLTB,0),,(LENGTH,0),,(CCCGCG,0),,(SCAL,0),
+ (CASC,0),,(AL,0),,(CC,0),,(C,0),,(C1,0),
+ (C2,0),,(C3,0),,(R1,0),,(R2,0),,(R3,0),,(R4,0),
+ (R5,0)

EQUIVALENCE (L1,L(1)),,(L12,L(1)),,(L13,L(1)),,(L14,L(1)),
+ (L15,L(1)),,(L16,L(1)),,(L2,L(1)),,(L3,L(1)),,(L4,L(1)),
+ (L5,L(1)),,(L6,L(1)),,(L7,L(1)),,(L8,L(1)),,(L9,L(1)),
+ (L10,L(1)),,(L11,L(1)),,(L12,L(1)),,(L13,L(1)),,(L14,L(1))

PARAMETER PI 3.141592653589793

COMMON/ZERI/ ZERI(60)

COMMON/ZERI/ ZERI(60)

COMMON/ZERI/ ZERI(60)

COMMON/ZERI/ ZERI(60)

```

3277      * CONTINUE
3278      NTHPOW = 2** N2
3279      NTTL2=NTHPOW/2
3280      NP= BOOL(X(N193))
3281      GO TO(502,501,411),IFLAG
3282      S02 R1=X(N195)
3283      R2=1.0/R1
3284      IF(SIMBW.EQ.1.OR.INCRM.EQ.3) R1=1.0/FLOAT(NP)
3285      IF(INCRM.EQ.4) R1=1.0
3286      IF(ICPLXF.EQ.0) GO TO 700
3287      DO 11 J=1,NP
3288      X(J)= X(J)*R1
3289      Y(J)=-Y(J)*R1
3290      11 CONTINUE
3291      GO TO 701
3292      700 DO 702 J=1,NP
3293      X(J)= X(J)*R1
3294      Y(J) = 0.0
3295      702 CONTINUE
3296      701 CONTINUE
3297      IF(NTHPOW-NP) 32,31,30
3298      30   L1=NP+1
3299      DO 10 J=L1,NTHPOW
3300      X(J) = 0.0
3301      Y(J) = 0.0
3302      10 CONTINUE
3303      GO TO 500
3304      32    WRITEL(6,33) NP,NTHPOW
3305

```

5-13

260

08/22/75 INPUT LISTING AUTOCFLW CHART SET - FWL/SCL RADSIM
 CARD NO. **** CONTENTS 5-14 ****

 3306 J3 FORMAT(* NUMBER OF INPUT SAMPLES*,14,*EXCEEDS SPECIFIED TIME*,
 3307 * * SFAN=2**N2=0,14)
 3314 J2 CONTINUE
 3309 GO TO 500
 3310 500 CONTINUE
 3311 IF (NFILE>NTHFWLCK,N2,EW,13) GO TO 349
 3312 I1=I2+1
 3313 WRITE (6,310) N2
 3314 END FORMAT (* THE SIZE OF THE TRANSFORM ARRAY HAS BEEN EXPANDED*,
 3315 * *EW,2**I,12)
 3316 GO TO 4
 3317 395 R1= X(N144)+FSHIFT
 3318 R2=FLAT(N112)*X(N145)
 3319 NSHIFT= IF(X1 (R1-R2) > X(N145) + 0.40)
 3320 T1= R1 - X(N145)/2.0
 3321 T1= R1 + X(N145)/2.0
 3322 59 R2=R2+ X(N145)* FLAT(NSHIFT)
 3323 WRITE (6,300) NSHIFT,NP,P1,R2,R3,E1,T1,X(N144)
 3324 END FORMAT(1H ,2I10,0E15+0)
 3325 IF(I1>GMAX,ANU,R3,L1,T1) GO TO 60
 3326 IF(R3<L1) NSHIFT=NSHIFT+1
 3327 IF(R3>L1) NSHIFT=NSHIFT-1
 3328 GO TO 59
 3329 60 IF(NSHIFT=L1,C1) GO TO 404
 3330 L2=N1+NSHIFT
 3331 L3=N1
 3332 IF(L1>L2,NTHFWL) GO TO 370
 3333 IF(L1>L3+1) GO TO 380
 3334 N1=N1+1

3335 WRITE(6,310) NC
3336 GO TO 4
3337 380 WRITE(6,385) L2,NTHPOW
3338 385 FORMAT(* THE NUMBER OF ARRAY ELEMENTS REQUIRED AFTER HETERODYNING*,
3339 *15, *EXCEEDED AVAILABLE STORAGE...ARRAY REDUCED TO*,15,
3340 * * BY DELETING HIGH FREQ TERMS*)
3341 L3=NTHPOW-NSHIFT
3342 L2=NTHPOW
3343 .70 IF(NSHIFT.EQ.0) GOTO 430
3344 UC 4(0 L1=1,NF
3345 X(L2)= X(L3)
3346 Y(L2)= Y(L3)
3347 L2=L2-1
3348 L3=L3-1
3349 400 CONTINUE
3350 UC 401 L1=1,NSHIFT
3351 X(L1)=0.0
3352 Y(L1)=0.0
3353 401 CONTINUE
3354 400 L2=NTHPOW-NSHIFT+1
3355 IF(L2.GE.NTHPOW) GOTO 403
3356 UC 402 L1=L2,NTHPOW
3357 X(L1)=0.0
3358 Y(L1)=0.0
3359 402 CONTINUE
3360 UC 403 L1=1,NF
3361 404 IF(NL.EQ.13) GOTO 407
3362 NC=NC+1
3363 WRITE(6,310) NC

6074270

INPUT LISTING

AUTOFLOW CHART SET - FNU/SCL RADSIM

5-16

CARD NO.

CONTENTS

0204 GOTO 4
 0205 GOTO L5=NPN+NSHIFT
 0206 DE 405 L=FILE3
 0207 X(L1)=X(L1-NSHIFT)
 0208 Y(L1)=Y(L1-NSHIFT)
 0209 GOTO CONTINUE
 0210 L5=NPN+1
 0211 DE 405 L=L1,NTHPOW
 0212 X(L1)=0.0
 0213 Y(L1)=0.0
 0214 GOTO CONTINUE
 0215 L1=LADDL(NP1,L1)
 0216 WRITE(0,0001) L1
 0217 *FORMAT(* NUMBER OF LOCATIONS FIELD AFTER RETEADING)*
 0218 * RELEASED AVAILABLE STORAGE...*IS* ELEMENTS DELETED*,
 0219 * PERIOD INDICATE END OF ARRAY*)
 0220 4-1 CONTINUE
 0221 IF (LOCAL=L1) GO TO 410
 0222 L=L1+NPN+1
 0223 L=L-NPN+1
 0224 L=L-1
 0225 X(L)= C05*(X(L)+X(L3))
 0226 X(L2)=X(L1)
 0227 Y(L)= C05*(Y(L)-Y(L2))
 0228 Y(L1)=Y(L2)
 0229 4-1 CONTINUE
 0230 4-1 CONTINUE
 0231 L=L-NPN+1
 0232 IF (L.LT.1) GO TO 410/ELEMENTFLOW)

3393	IF (INERH=0.0) RS=1.0	
3394	L1=NITL2	5-17
3395	DO 404 J=1,NITL2	
3396	L1=L1+1	
3397	F1=X(L1)*RS	
3398	R2=Y(L1)*RS	
3399	A(L1)=A(J)+RS	
3400	Y(L1)=Y(J)+RS	
3401	X(J)=F1	
3402	Y(J)=R2	
3403	404 CONTINUE	
3404	411 CONTINUE	1050
3405	X(N143)=FLCLL(INTHPW)	
3406	X(N144)=0.0	
3407	500 CONTINUE	
3408	X(N145)=1.0/(FLCLL(INTHPW)*X(N145))	
3409	N4PW = -N2 - 72	
3410	IF (N4PW<0.0) GO TO 3	
3411	DO 2 PASS=1,N4PW	1120
3412	NXTLTH=2*(N2 - 2*PASS)	
3413	LENTH=4*NXTLTH	
3414	SCALE=PI2/DBLC(FLCLL(LENGTH))	1160
3415	CDEF=FOCUS(SCALE)	1151
3416	SCL=DSIN(SCALE)	1152
3417	CS=1.000	1153
3418	SN=0.000	1154
3419	DO 2 J=1,NXTLTH	
3420	C1=CS	1180
3421	SI=SN	1190

CO/1175	INPUT LISTING	AUTODEWU CHART SET - FWC/SOL RADSIM
LAKE NO.	*****	5-18
	CONTENTS	*****
3422	0.7E0*U-SN*SN	1200
3423	0.7E0*0.0E0*U-SN	1210
3424	0.7E0*U-S1*S2	1220
3425	S2-U2*S1+0.7*U	1230
3426	0.7E0	1240
3427	0.7E0*U-L1*D2L	1250
3428	0.7-E*SN*L1+SN*D2L	1260
3429	L1 = SN*L1-LNTH,NTROW,LENTH	1410
3430	J1 = SELECT-LENTH+J	
3431	J2 = J1+NTROW	
3432	J3 = J2+LENTH	
3433	J4 = J3+LENTH	
3434	R1 = X(J1)+X(J2)	
3435	R2 = X(J3)-X(J4)	
3436	R3 = X(J2)+X(J4)	
3437	R4 = X(J3)-X(J4)	
3438	T1 = Y(J1)+Y(J3)	
3439	T2 = Y(J2)+Y(J4)	
3440	T3 = Y(J3)+Y(J4)	
3441	T4 = Y(J2)-Y(J3)	
3442	X(J1) = T1+R1	
3443	Y(J1) = T1+T2	
3444	X(J2) = T2*(T2-T4)+T1*(T2+R4)	
3445	Y(J2) = T2*(T2-T4)+T1*(T2+R4)	
3446	X(J3) = T3*(T3-T1) + S1*(T1-T3)	
3447	Y(J3) = T3*(T3-T1) + S2*(T1-T3)	
3448	X(J4) = T4*(T4-T1) + S3*(T1-T4)	
3449	Y(J4) = T4*(T4-T1) + S4*(T1-T4)	
3450	END	

5-19

3451 D IF(N2 .EQ. 2*N4P0W) GO TO 5
3452 DO 4 J=1,NTHPLW,2
3453 K=X(J)+X(J+1)
3454 X(J+1)=X(J)-X(J+1)
3455 X(J) = K
3456 I=Y(J)+Y(J+1)
3457 Y(J+1)=Y(J)-Y(J+1)
3458 + Y(J)=I
3459 D DO 6 J=1,14
3460 L(J)=1
3461 O IF(J.LE. N2) L(J)=2**(-N2 +I-J)
3462 IJ=1
3463 DL 7 J1=1,L1
3464 DL 7 J2=J1,L2,L1
3465 DL 7 J3=J2,L3,L2
3466 DL 7 J4=J3,L4,L3
3467 DL 7 J5=J4,L5,L4
3468 DL 7 J6=J5,L6,L5
3469 DL 7 J7=J6,L7,L6
3470 DL 7 J8=J7,L8,L7
3471 DL 7 J9=J8,L9,L8
3472 DL 7 J10=J9,L10,L9
3473 DL 7 J11=J10,L11,L10
3474 DL 7 J12=J11,L12,L11
3475 DL 7 J13=J12,L13,L12
3476 DL 7 J14=J13,L14,L13
3477 IF(IJ.GE.JI) GO TO 7
3478 K=X(IJ)
3479 X(IJ)=X(JI)

10/11/75

INPUT LISTING

AUTOFLOW LHMKT SET - FWD/SEL KADSIM

5-20

CAKO No.	*****	CONTENTS
3480	X(J1)=K	
3481	I=Y(IJ)	
3482	Y(IJ)=Y(J1)	
3483	Y(J1)=I	
3484	Y(IJ)=I+1	
3485	IF(IFLAG.EQ.0) GO TO 15	
3486	L1=N1TL2	
3487	LL 14 J=1,N1TL2	
3488	L1=L1+1	
3489	R1=X(L1)	
3490	K1=Y(L1)	
3491	X(L1)=X(J)	
3492	Y(L1)=Y(J)	
3493	X(J)=K1	
3494	Y(J)=K2	
3495	14 CONTINUE	
3496	K2=-X(N195)*FLCAT(N1TL2)	
3497	X(N194)=K2	
3498	IF(IFLAG.EQ.3) GO TO 15	
3499	NP=1EIX(SIMBW/X(N195))/2	
3500	F1=FSHIFT-X(N195)*NP	
3501	NSHIFT=1EIX(FSHIFT/X(N195))-NP+N1TL2	
3502	NP=NP*K	
3503	B1=K1-X(N195)/2.0	
3504	T1=F1+X(N195)/2.0	
3505	46 K3=K2+X(N195)*NSHIFT	
3506	WRITE(6,3001) NSHIFT, NP, R1, R2, K3, B1, T1	
3507	IF(K3.GE.B1.ANU.R3.LE.T1) GOTO 47	
3508	IF(K3.LT.B1) NSHIFT=NSHIFT+1	

3514 IF (K2.GE.0) NSHIFT=NSHIFT-1
 3515 GO TO 46
 3516 47 IF (NSHIFT.GE.0) GO TO 49
 3517 WRITE (6,50)
 3518 48 FORMAT (* THE VALUE OF NSHIFT IS NEGATIVE...NSHIFT SET TO 0*)
 3519 GO TO 50
 3520 49 L1=NSHIFT+NP
 3521 IF (L1.LE.NINPUT) GO TO 50
 3522 WRITE (6,51) NSHIFT+NP
 3523 51 FORMAT (* THE SUM OF NSHIFT*,I1,I2* AND I1*,I2,I3* IS GT NTHPW***
 3524 *NSHIFT SET TO 0*)
 3525 52 NSHIFT=0
 3526 53 CONTINUE
 3527 X(N1M)=C1(L1NP)
 3528 X(N1M)=X(N1M)* (NP/2)
 3529 WHILE (L1.GE.0) NSHIFT+NP+R1+R2*X(N1M)
 3530 L1=L1-1+N1
 3531 NSHIFT=NSHIFT+1
 3532 X(1)=X(NSHIFT)
 3533 Y(1)=Y(NSHIFT)
 3534 54 CONTINUE
 3535 55 CONTINUE
 3536 Y(N1M)=X(N1M)
 3537 Y(N1M)=X(N1M)
 3538 Y(N1M)=X(N1M)
 3539 C1=0.0
 3540 END

5-21

S E C T I O N 6

P E R I P H E R A L M O D U L E S

This section includes all those modules that do not participate in the actual simulation process, but serve as the interface between the simulation and the user. In some cases this is as simple as outputting data to a disc file. In other cases the data is processed to extract some parameter, e.g. energy in a waveform, or to map data into a different representation space, e.g. the generation of a probability histogram. The following modules are included in this group:

CLINT
CUMDIS
ERGYCP
PLOTR
PLTFMT
PTLIST
RTOPDB
SCANNR

Also included in this group is the module SPCAVG, which is located in Volume III.

The following peripheral modules are related to the bistatic target model and target imaging and are included in Volume I, Part 3:

ERRPRC
(BISTATIC ANTENNA INITIALIZATION)

SUBROUTINE CLINT

1. MODULE IDENTIFICATION:

<u>Name</u>	<u>Classification Code</u>	<u>Reference Number</u>
CLINT	PERIP.	302

2. PURPOSE:

This subroutine initializes the clutter model scatterers and parameters.

3. INPUT PARAMETERS:

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
LAMBDA	O	F	Wavelength of the transmitted waveform. This parameter is used to compute the doppler shift of weather or chaff clutter.
TCELL	R	F	Range dimension of clutter element.
IDMP	O	I	Output data print flag. IDMP ≠ 0 (a) Scatterer arrays are printed (CLINT) (b) Antenna Azimuth and Elevation arrays are printed (cluttr) IDMP = 1 Clutter impulse response is printed by (cluttr).
NRCS	R	I	Scatterer RCS probability distribution flag.
RWPH	O	F	Scatterer random walk maximum phase shift. Represents the random motion of cluttr from one transmit cycle to the next.
WNDVEL	O	F	Speed of the clutter volume due to wind, meters/second.

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
TI	R	F	Time increment between samples (used to compute number of storage cells required by clutter impulse response).
VELANG	O	F	Relative angle of clutter velocity vector with respect to the radar site.
RNEXT	O	F	Range dimension of the clutter volume in monoseconds.
RNØØØ	O	F	Clutter volume starting range.
AZEXT	O	F	Azimuth dimension of the clutter volume in degrees
AZØØØ	O	F	Clutter volume starting azimuth angle.
MM	O	I	Number of clutter volume azimuth increments.
ELEXT	O	F	Elevation dimension of the clutter volume in degrees.
ELØØØ	O	F	Clutter volume starting elevation angle.
NN	O	I	Number of clutter volume elevation increments.

4. CALLING SEQUENCES:

CALL CLINT (\$NNNN)

WHERE: NNNN Statement number for abnormal return

5. RESTRICTION, REQUIREMENTS, MISCELLANEOUS DATA:

- a. The clutter model was split into two subroutines in order that the initialization process would be separate and easily changed to allow modeling of more complex clutter environments.
- b. The total number of scatterers (NSCAT) is limited only by the amount of available disc space and is approximately equal to 160 times the number of blocks of available disc space. The number of scatterers is equal to NN times MM times KK, where KK = RNEXT/TCELL. Other than their product; NN, MM and KK have no limitations.
- c. The random number generator function (RRAND) is called from this subroutine.
- d. The clutter scatterer element arrays are stored in a random disc file, FC = 02, the record size is 500 words.
- e. Flow Chart: Page 9-198
- f. Cross Reference Table: Page 9-234

6. THEORY OF OPERATION

This program can be divided into two functional sections and each will be discussed in the following paragraph.

- a. User parameter testing and clutter model parameter calculation. Refer to Figures CLINT - 1(a) and 1(b).

XVLANG The angle between the wind velocity vector and a radial line from the first clutter scatterer element (0,0,0) to the radar.

$$XVLANG = (AZ\theta\theta\theta - VELANG)/57.29578$$

DOPFRQ The maximum doppler frequency shift due to the wind.

$$\text{DOPGRQ} = -2.0 * \text{WNDVEL/LAMBDA}$$

If LAMBDA is zero this calculation is not performed and DOPFRQ is set to zero.

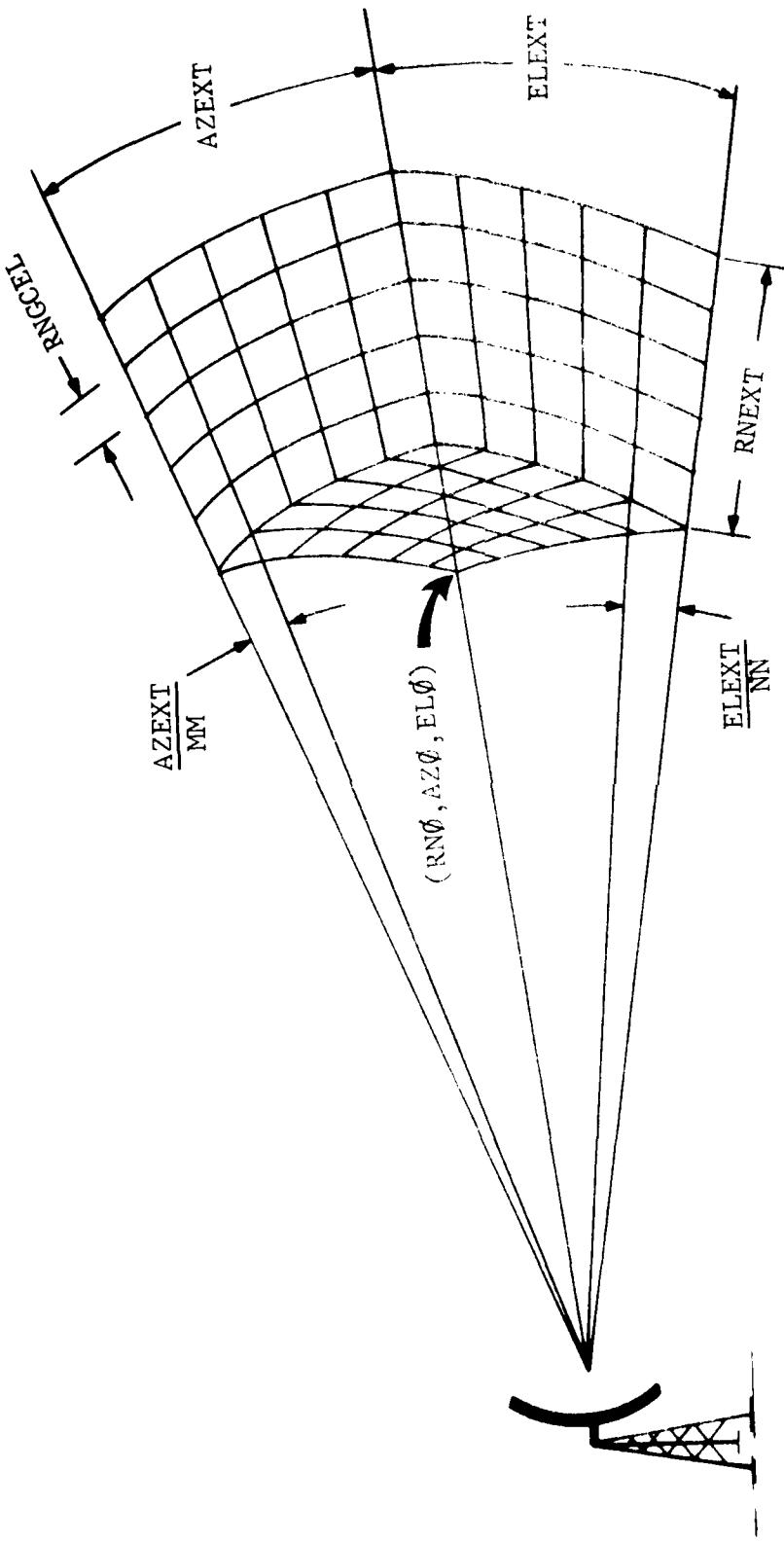


Figure CLINT-1a CLUTTER MODEL GEOMETRY

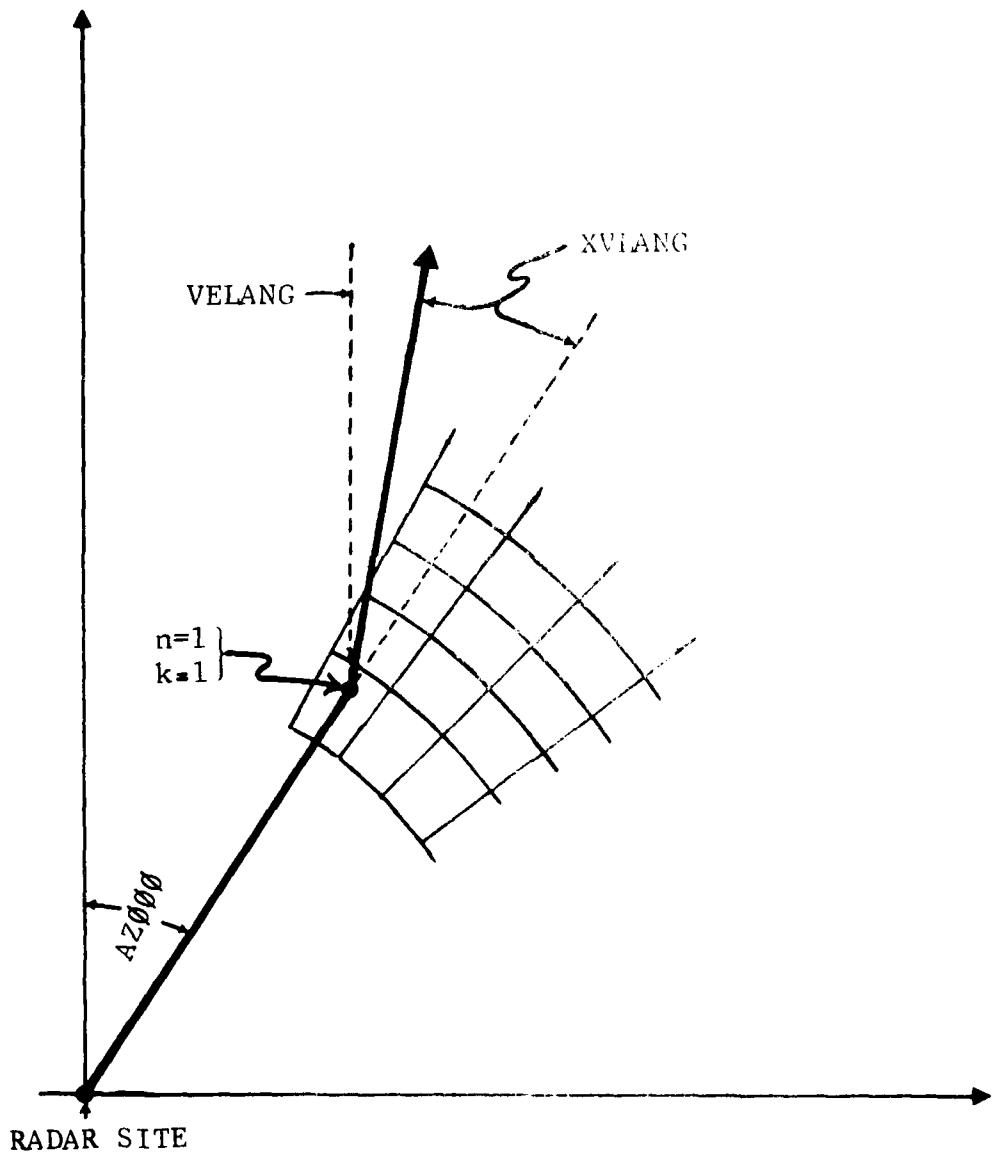


Figure CLINT-1b CLUTTER MODEL GEOMETRY
(PLANE VIEW)

MM	If this parameter was not specified it is set to 1.
NN	If this parameter was not specified it is set to 1.
KCELL	The total number of storage cells required to represent the clutter impulse response. If this parameter exceeds 4096 (half the available storage) then RNEXT is automatically reduced to make KCELL < 4096. $\text{KCELL} = \text{RNEXT}/\text{TI}$
KK	Number of clutter volume range increments. $\text{KK} = \text{RNEXT}/\text{TCELL}$
NBLKS	The number of random disc records required to store the clutter scatterer. This parameter is arbitrarily limited to 200 and can be increased providing the control cards for DSRN 02 are changed accordingly.
DELAZ	Azimuth increment between clutter scatterers. $\text{DELAZ} = \text{AZEXT}/\text{MM}$
DELEL	Elevation increment between clutter scatterers. $\text{DELEL} = \text{ELEXT}/\text{NN}$
ICFLG	This parameter is set to 1 if the clutter model has been successfully initialized. This is tested before CLUTTR can be executed.
MODE	This parameter is used to indicate if stationary (MODE=1) or time varying (MODE=2) clutter is to be modeled. When stationary clutter is modeled certain simplifications can be made in the processing performed in the clutter model routine CLUTTR.

- b. Each clutter scatter element is represented by a radar cross section value and a phase angle. These two parameters are converted to rectangular representation and stored in the arrays CLUX and CLUY.

CLUX(J) = A*RRAND(8)
CLUY(J) = A*DUM

where $A = \sqrt{RCS(J)} = \sqrt{RRAND(NRCS)}$

RRAND(8) = COS(θ)

DUM = SIN(θ)

θ is a sample of a random uniform distribution $300.0 < \theta \leq 0.0$

5122 SUBROUTINE CLINT(*)
5123 CMMMLN/BLK1/ CLUX(250),CLUY(250) 6-9
5124 CMMMLN/BLK2/ BK2(5.0)
5125 COMMON/BLKEND/ IDMR(2),DUM
5126 DIMENSION CSCAT(500) C
5127 EQUIVALENCE (CLUX(1),CSCAT(1))
5128 EQUIVALENCE (BK2(13), LAMBDA) , (BK2(14), TCELL) ,
5129 * (BK2(21), JUMP) , (BK2(46), NACS) ,
5130 * (BK2(47), NEWPH) , (BK2(48), RWPH) ,
5131 * (BK2(49), WNUVLL) , (BK2(50), VELANG) ,
5132 * (BK2(51), ENEXT) , (BK2(52), KNUUU)

5133 * (BK2(53), AZEXT) , (BK2(54), AZ000) , 6-9a
 5134 * (BK2(55), MM) , (BK2(56), ELEXT) ,
 5135 * (BK2(57), EL000) , (BK2(58), NN) ,
 5136 * (BK2(120), KK) , (BK2(121), NELKS) ,
 5137 * (BK2(122), MODE) , (BK2(123), DLLAZ) ,
 5138 * (BK2(124), DESEL) , (BK2(125), XVLANG) ,
 5139 * (BK2(126), ICFLG) , (BK2(127), DOPFRG) ,
 5140 * , (BK2(128), KCELL) , (BK2(12), T1)
 5141 REAL LAMEDA
 5142 CALL RANSIZ(0Z,500)
 5143 XVLANG= (AZ000-VELANG)/57.2957e
 5144 IF (MM.GT.0) GO TO 200
 5145 MM=1
 5146 WRITE(6,95)
 5147 95 FORMAT(1HO,* THE VARIABLE MM HAS BEEN SET TO 1 *)
 5148 100 IF (NN.GT.0) GO TO 200
 5149 NN=2
 5150 WRITE(6,195)
 5151 195 FORMAT(1HO,* THE VARIABLE NN HAS BEEN SET TO 1 *)
 5152 200 CONTINUE
 5153 KCELL=IFIX(KNLXT/T1)
 5154 IF (KCELL.LT.6192) GOTO 50
 5155 KCELL=6192
 5156 RNEXT=T1*6192.0
 5157 50 KK=IFIX(RNEXT/TCELL)
 5158 IF (KK.GT.0) GO TO 211
 5159 KK=1
 5160 211 WRITE(6,212) KK
 5161 212 FORMAT(1HO,* THE VARIABLE KK HAS BEEN SET TO 1,15)

06/16/75

INPUT LISTING

AUTOFLOW CHART SET - FWD/SCL - RADSIM

CARD NO.	****	CONTENTS	6-10 ****
5162		NSCAT-MM*NN*KK	
5163		NELKS= NSCAT/250	C
5164		IF(NELKS*250.LT.NSCAT) NELKS=NELKS+1	C
5165		IF(NELKS.GT.200) GO TO 888	
5166		DELAZ= AZLX1/FLUAT(MM)	
5167		DELEL= ELEX1/FLUAT(NN)	
5168		MGLB=Z	
5169		IF(LAMBDA.NE.0.0) DIFFRQ=-2.0*WNDVLL/LAMBDA	
5170		IF(DIFPRQ.EQ.0.0.AND.RWPH.EQ.0.0) MUDL=1	
5171		IPNT=1	
5172		IREC=1	
5173		DL 1000 N-LBN	
5174		DL 1010 N-LBN	
5175		DL 1020 M-LMM	
5176		IF(IPNT.LE.250) GO TO 950	C
5177		IF(IDMP.EQ.0) GO TO 940	
5178		WRITE(6,930) (CLUX(J),CLUY(J), J=1,IPNT)	
5179		930 FORMAT(1H ,0L20.0)	
5180		940 WRITE(6,1REC) (SCAT	
5181		1REC-IREC+1	
5182		IPNT=1	
5183		950 A=RKAND(NELKS)	
5184		CLUX(IPNT)= A*RKAND(L)	
5185		CLUY(IPNT)= A*DUM	
5186		1020 IPNT=IPNT+1	
5187		1010 CONTINUE	
5188		1000 CONTINUE	
5189		IF(IPNT.EQ.250) GO TO 887	
5190		WRITE(6,2*IREC) (SCAT	

5141 IF(IOMP.NE.0) WRITE(6,930) (CLUX(J),CLUY(J), J=1,LHNT)
5142 667 IFLG=1
5143 RETURN
5144 680 WRITE(6,804) KK,NN,MM,NSCAT
5145 884 FLKMAT1 IH,* THE PRODUCT OF KK=*,14,* NN=*,14,* MM=*,14,* IS TOO
5146 *LARGE,*,110,* THIS JOB WILL TERMINATE*)
5147 RETURN 1
5148 END

(6-10a)

SUBROUTINE CUMDIS

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
CUMDIS	Peripheral	208,209
CUM2	Peripheral	Not User Referenced
OUTCUM	Peripheral	210,211
PDF	Peripheral	212,213

2. PURPOSE:

This subroutine processes a sequence of input samples in order to generate the probability density histogram and cumulative probability distribution.

3. INPUT PARAMETERS (CUMDIS):

Name	O/R	T	Description
TLIM	R	F	The upper limit of the histogram independent variable
BLIM	R	F	The lower limit of the histogram independent variable
NIXF	R	I	The number of elements in the histogram

INPUT PARAMETERS (OUTCUM):

Name	O/R	T	Description
NCPACK	R	I	The number of histogram elements combined to form one element of the output cumulative distribution

INPUT PARAMETERS (PDF):

Name	O/R	T	Description
NDPACK	R	I	The number of histogram elements combined to form one element of the output probability density.

4. CALLING SEQUENCES:

Initial histogram computation

CALL CUMDIS (DATAIN, XF)

Where: DATAIN contains the Input Waveform

XF contains the Output Histogram

Add additional data to histogram

CALL CUM2 (DATAIN, XF)

Where: DATAIN contains the Input Waveform

XF contains the Output Histogram

Cumulative distribution

CALL OUTCUM (DATOUT, XF)

Where: XF contains the Input Histogram

DATOUT contains the cumulative distribution

Probability density

CALL PDF (DATOUT, XF)

Where: XF contains the Input Histogram

DATOUT contains the probability density

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. The number of points NIXF in the histogram XF cannot exceed 8000.
- b. Any value of the input array which lies below the bound of BLIM will be placed in the lowest element of the histogram. Any value of the input array which lies above the bound of TLIM will be placed in the highest element of the histogram.

c. The variables NCPACK and NDPACK must be greater than or equal to 1.

d. Flow Chart: Page 9-152

e. Cross Reference Table: Page 9-228

6. THEORY OF OPERATION

a. The width of the histogram elements is determined using the following expression

$$DINC = (TLIM - BLIM) / NIXF$$

b. The value of each sample in the input array DATAIN is divided by DINC to determine the corresponding histogram element. The number of samples which lie within the bounds of that histogram element is incremented by one.

c. After the histogram is generated an entry through OUTCUM causes the cumulative distribution to be calculated and placed in array DATOUT. The number of histogram elements combined to generate one output sample is determined by the variable NCPACK.

d. If the density function is desired, entry is made through the entry point PDF. The number of histogram elements combined to generate one output sample is determined by the variable NDPACK.

3917 SUBROUTINE LUMZIS(DATAIN,XF) 6-14 C
 3918 C
 3919 COMMON/BK1/BK1(500) C
 3920 C
 3921 DIMENSION DATAIN(1),DATOUT(1),XF(1) C
 3922 EQUIVALENCE (BK1(24), TLIM),
 3923 1 (BK1(40), FLIM), (BK1(41), NIXF),
 3924 2 (BK1(42), NCHECK), (BK1(43), NUFLCK)
 3925 DATA N143,N144,N145,N146/-3,-2,-1,0/
 3926 C
 3927 C CALCULATE HISTOGRAM ELEMENT WIDTH C
 3928 DINC = (TLIM-FLIM)/FLOAT(NIXF) C
 3929 LADD = 1-1FIX(BLIM/DINC) C
 3930 XF(N143)=BLUL(NIXF) C
 3931 XF(N144)=BLIM C
 3932 XF(N145)=DINC C
 3933 XF(N146)=BLUL(LADD) C
 3934 C
 3935 DO 20 J=1,NIAF C
 3936 20 XF(J)=0.0 C
 3937 C C 1000 C
 3938 ENTRY LUMZ(DATAIN,XF) C
 3939 NIXF=1LLL(XF(N143)) C
 3940 DINC=XF(N145) C
 3941 LADD=BLUL(XF(N146)) C
 3942 C
 3943 C ADD POINTS TO FREE-DENSITY HISTOGRAM C

06/11/75 INPUT LISTING AUTOFLOW DRAFT SET - FWD/SLC RADSIM

LARD N#	*****	CONTENTS	674A *****
3944	C		C
3945	1000 CONTINUE		C
3946	NDATA = IELLL(DATAIN(N195))		C
3947	DINC=1.0/DINC		C
3948	DO DO J=1,NDATA		C
3949	IADD=1+FIX(DATAIN(J)*DINC) + LADD		C
3950	IF(IADD.GT.N1XF) IADD=N1XF		C
3951	IF(IADD.LT.1) IADD=1		C
3952	50 XF(IADD)=XF(IADD)+1.0		C
3953	C		C
3954	RETURN		C
3955	C		C
3956	ENTRY CUMULM(DATOUT,XF)		C
3957	C		C
3958	C CALCULATE CUMULATIVE FREQUENCY DISTRIBUTION		C
3959	C		C
3960	IF(NCPACK.LE.0) NCPACK=1		C
3961	N1XF=IELL(XF(N195))		C
3962	DINC=XF(N195)		C
3963	KLEN = N1XF/NCPACK		C
3964	DATOUT(N195) = DINC*FLDAT(NCPACK)		C
3965	JJ = NCPACK		C
3966	CLM=0.0		C
3967	C		C
3968	DO DO J=1,KLEN		C
3969	JJ = JJ + NCPACK		C
3970	DO K=1,KLEN		C
3971	Z= CLM+CLM+XF(K+CLM)		C
3972	DO DATOUT(J)=CLM		C

3870	C	C
3871	1001=N0	6-15
3872	DL TL Z00	C
3873	C	C
3874	ENTRY EDU(DATOUT,XF)	C
3875	C	C
3876	1001=N1	C
3877	IF (NDPACK .LE. 0) NDPACK=1	C
3878	NIXE=N0(XI(N195))	C
3879	NDPACK=XF(N195)	C
3880	KEND = NIXE/NDPACK	C
3881	DATOUT(N195)=INC*FLOAT(NDPACK)	C
3882	JJ= -NDPACK	C
3883	C	C
3884	CUM=0.0	C
3885	DL 100 J=1,KEND	C
3886	LEN=0.0	C
3887	JJ=JJ + NDPACK	C
3888	DL 50 K=1,NDPACK	C
3889	LEN=LEN+XF(K+JJ)	C
3890	50 CONTINUE	C
3891	CUM=CUM+LEN	C
3892	DATOUT(J)=DEN	C
3893	100 CONTINUE	C
3894	C	C
3895	100 CONTINUE	C
3896	CUM=1.0/CUM	C
3897	IF (ICUN .LE. 1) CUM=CUM/DATOUT(N195)	C
3898	DL 500 K=1,KEND	C

07/11/73 INPUT LISTING AUTOFLOW CHART SET - FWU/SCL RADSIM

CARD NO.	*****	CONTENTS	*****
4002		DATOUT(K)=DATOUT(K)*CUM	C
4003		300 CONTINUE	C
4004		DATOUT(N193) = 600L(KEND)	C
4005		DATOUT(N194)=XF(N194)	C
4006		RETURN	C
4007		END	C

SUBROUTINE ERGYCP

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
ERGYCP	Peripheral	118
ERGYRE	Peripheral	116,117

2. PURPOSE:

This subroutine computes the energy contained in a waveform.

3. INPUT PARAMETERS:

None

4. CALLING SEQUENCES:

Complex waveform

CALL ERGYCP (X,Y)

Where: X contains the Input Waveform - R

Y contains the Input Waveform - I

$$\text{Energy} = \Delta \sum_{J=1}^{\text{NPTS}} X(J) **(J) + Y(J) * Y(J)$$

NPTS = Number of waveform samples

Δ = Independent variable increment between samples

Real Waveform

CALL ERGYRE (X)

Where: X contains the Input Waveform

$$\text{Energy} = \Delta \sum_{J=1}^{\text{NPTS}} X(J) * X(J)$$

- a. The computed energy is printed on the output listing.
The measurement unit is watt-nanoseconds, normally.
- b. Flow Chart: Page 9-70
- c. Cross Reference Table: Page 9-217.

```

2012      SUBROUTINE EGYCF(X,Y)
2013      DIMENSION X(1),Y(1)
2014      DATA N195/0.194,N195/-3,-2,-1/
2015      MUL1=1
2016      OUTC=100
2017      CALL YCF(YCF,X)
2018      MUL2=0
2019      DO J=1,100,N195
2020      MUL2=MUL2*(X(N195))
2021      DO Y=0.1
2022      DO Z=0.0,OUTC,N195
2023      EGY=EGY+X(J)*Z
2024      DO Z=0.0,OUTC,N195
2025      IF (MUL2*EGY>0) OUTC=500
2026      EGY=EGY+Z*Y
2027      EGY=EGY+Y*Z
2028      DO Z=0.0,OUTC,N195
2029      EGY=EGY*Z
2030      WRITE(6,1000) EGY
2031      1000 FORMAT(' ENERGY IN THE WAVEFORM =',E10.5,' WATT-NANoseconds')
2032      RETURN
2033      END

```

SUBROUTINE PLOTTR

1. MODULE IDENTIFICATION:

<u>Name</u>	<u>Classification Code</u>	<u>Reference Number</u>
PLOTTR	PERIP	307,308,309,310

2. PURPOSE:

This subroutine converts the data contained in the input array into a form suitable for plotting by a HP9820 desk calculator. In addition, the output can also be listed on a TTY via TSS or punched on cards.

3. INPUT PARAMETERS:

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
SIVST	R	F	Value of the independent variable at the start of the plot
XIVRNG	R	F	Range of the independent variable which is to be plotted
LOGFLG	R	I	Control index which indicates the nature of the input data
NSKP	O	I	This variable controls the number of input samples skipped between each plotted point. For example, if NSKP=0 or 1, each point is plotted; if NSKP=2, every other point is plotted.
NAUTO	O	I	Control flag for automatic data scanner which determines the maximum and minimum values of the dependent variable. If NAUTO=0, the scanner determines the value of TH and TL. If NAUTO=1, the user provided input parameters TH and TL are used.
TH	O	F	Maximum dependent variable value to be plotted

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
IC	R	I	Logical unit designator for output file
VIL	0	C	Independent variable label
VDL	0	C	Dependent variable label
GLBL	0	C	Plot title and miscellaneous data

4. CALLING SEQUENCES:

CALL PLOTTR (DV)

Where: DV contains the Input Waveform

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. If an output file code (IC) is not specified then no data will be transferred and control will immediately be transferred back to the calling program.
- b. If the user specified parameters, XIVST and SIVRNG, specify a plot that is outside the range of the input data array then the complete input array is processed and transferred to the output file.
- c. If the file code is negative, specifying HP paper tape format, then all plot labels and miscellaneous data are suppressed. Only TH, TL, XIVOR, DELTA, and NPTS and the plot data are transferred.
- d. All floating point output values are in E13.5 format.
- e. Flow Chart: Page 9-90
- f. Cross Reference Table: Page 9-219.

6. THEORY OF OPERATION

- a. Upon entering the subroutine the parameter IC is tested to determine that IC is not zero and what operating mode is to be used. If IC > 0 then the HP paper tape mode (ICON = 2) is selected. If IC < 0 then the card image mode (ICON=1) is selected.
- b. If (ICON=1) the following lines (records) are transmitted to the output file.
 1. Header line "## Punch Card Data Output"
 2. XIVST, XIVRNG, XIVFR (not used), LOGFLG, VIL (first 12 characters)
 3. VIL (last 60 characters)
 4. VDL (first 60 characters)
 5. VDL (last 12 characters), GLBL (first 48 characters)
- c. The input parameters, XVST and XIVRNG, are tested to verify that the range of the desired plot is within the limit of the input array, DV. If the desired plot extends past either end of DV, then the values of XIVST and XIVRNG are changed to be compatible with the available data. If the desired plot is totally outside the available data, then the complete input array is processed.
- d. If NAUTO = 0 the input data is scanned to determine the maximum, TH, and the minimum, TL, values of the dependent variable to be plotted.
- e. IF(ICON=1) the following lines (records) are transmitted to the output file.
 1. GLBL (last 10 characters)
 2. NSKP, NAUTO, IC
- f. The following lines (records) are transmitted to the output file.
 1. TH, TL, XIVOR, DELTA, NPTS
 2. 5 dependent variable values
 3. 5 dependent variable values
 - .
 - .
 - .
- N. Last line of plot data

2440 C FLUTTR
 2441 SUBROUTINE FLUTTR(BV)
 2442 COMMON/LEN1/ EK1(200),VIL(50),VDE(50),GLB(50)
 2443 EQUIVALENCE (EK1(59), X1VST) , (EK1(60), X1VKNG)
 2444 * (EK1(61), X1VER) , (EK1(62), EUGFLG)
 2445 * (EK1(63), NSKP) , (EK1(64), NAUTO)
 2446 * (EK1(65), TH) , (EK1(66), TL)
 2447 * (EK1(113), TC) ,
 2448 DATA N143,N144,N145,N146/-3,-2,-1,0/
 2449 DIMENSION A(113)
 2450 A(1)=1.0,A(2)=0.0,A(3)=0.0
 2451 A(4)=0.0,A(5)=0.0,A(6)=0.0
 2452 A(7)=0.0,A(8)=0.0,A(9)=0.0
 2453 A(10)=0.0,A(11)=0.0,A(12)=0.0
 2454 A(13)=0.0,A(14)=0.0,A(15)=0.0
 2455 A(16)=0.0,A(17)=0.0,A(18)=0.0
 2456 A(19)=0.0,A(20)=0.0,A(21)=0.0
 2457 A(22)=0.0,A(23)=0.0,A(24)=0.0
 2458 A(25)=0.0,A(26)=0.0,A(27)=0.0
 2459 A(28)=0.0,A(29)=0.0,A(30)=0.0
 2460 A(31)=0.0,A(32)=0.0,A(33)=0.0
 2461 A(34)=0.0,A(35)=0.0,A(36)=0.0
 2462 A(37)=0.0,A(38)=0.0,A(39)=0.0
 2463 A(40)=0.0,A(41)=0.0,A(42)=0.0
 2464 A(43)=0.0,A(44)=0.0,A(45)=0.0
 2465 A(46)=0.0,A(47)=0.0,A(48)=0.0
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 2468 A(55)=0.0,A(56)=0.0,A(57)=0.0
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 2472 A(67)=0.0,A(68)=0.0,A(69)=0.0
 2473 A(70)=0.0,A(71)=0.0,A(72)=0.0
 2474 A(73)=0.0,A(74)=0.0,A(75)=0.0
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 2479 A(88)=0.0,A(89)=0.0,A(90)=0.0
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6-21a

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2465      L
2466      WRITE(1C,6) ( VDL(J), J=1,10 )
2467      L
2468      WRITE(1C,6) ( VDL(J), J=11,12 ), ( GLBL(J), J=1,8 )
2469      L
2470      12  CONTINUE
2471      NTTL = 1B00UL(DV(N143))
2472      XIVUR = DV(N144)
2473      DELTA = DV(N145)
2474      ENDDAT = XIVUR + DELTA*(NTTL-1)
2475      NST=IFIX((XIVST-XIVUR)/DELTA)+1
2476      IF(NST.LT.1) NST=1
2477      NSTUF=IFIX((XIVST-XIVUR+XIVRNG)/DELTA)+1
2478      IF(NSTUF.GT.NTTL) NSTOP=NTTL
2479      IF(NSTUF.GT.NST) GOTO 11
2480      NSTUF=NTTL
2481      NST=1
2482      12  CONTINUE
2483      L
2484      XIVUK=XIVUK+(NST-1)*DELTA
2485      NFTS=(NSTUF-NST)/NSKP+1
2486      DELTA=DELTA*FLOAT(NSKP)
2487      IF(NAUTL.EQ.1) GE TO 100
2488      TH=DV(NST)
2489      TL=JH
2490      DO 50 J=NST,NSTUF
2491      TH=AMAX1(DV(J),TH)
2492      TL=AMIN1(DV(J),TL)
2493      50  CONTINUE
```

DATE	LINE	TEXT
2800	100	CONTINUE
2800	100	PRINTED ON COL 664
2800	100	WHITE(10,601,(CLRL(J),J=15,18),1H)
2800	100	FORMAT(20,*,0.000,1E-6)
2800	100	WHITE(10,10,10,NONE,RAUTO,1C)
2800	100	FORMAT(20,*,0.000,1E-6)
2800	100	WHITE(10,10,10,TH1L,XIVCF,DELTA,NFL1)
2801	100	FORMAT(10,*,0.000,1E-6)
2801	100	NONE=NONE
2801	100	LCOUNT=N1,N2,L1,N3M1
2802	100	E = 34490ME
2802	100	WHITE(10,10,10,(EV(N),N=J+K,NSKP))
2803	100	FORMAT(10,*,0.000,1E-6)
2804	100	NO CONTINUE
2804	100	C
2805	100	FORMAT
2805	100	WHITE(10,601)
2806	100	FORMAT* FILE DATA FILE IMPROPERLY DESIGNATED...FILE DATA*
2806	100	* * TRANSFERRED*)
2807	100	RETURN
2807	100	END

SUBROUTINE PLTFMT

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
PLTFMT	PERIP	113

2. PURPOSE:

This subroutine is used to transform input data which is provided at equal increments of sine θ into an output array which is equally incremented in θ . The new points are determined using a parabolic interpolation. In addition, the input array is tested to determine if all input points are in visible space (independent variable between ± 1), and superfluous data is eliminated.

3. INPUT PARAMETERS:

Name	O/R	T	Description
DELTHE	R	F	Output array independent variable increment
STARPT	O	F	Lower limit of the output array
STOPT	O	F	Upper limit of the output array

4. CALLING SEQUENCES:

CALL PLTFMT (GXIN, GYIN, GOUT, \$nnnn)

Where:
GXIN contains the Input E-field - Real Component
GYIN contains the Input E-field - Imaginary Component
GOUT contains the Output gain

nnnn is the statement number to which control is transferred when a non-recoverable error is detected.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- The lower and upper limits of the output array must be specified in ascending order in order to

be effective. If the upper limit is less than or equal to the lower limit or no limits are specified, all valid input data will be interpolated.

- b. A double parabolic interpolation is performed to determine each output sample except in the vicinity of the end points.
- c. Flow Chart: Page 9-175
- d. Cross Reference Table: Page 9-231.

6. THEORY OF OPERATION

PLTFMT is intended primarily for converting antenna pattern data from equal increments of sine θ , generated by the Fast Fourier Transform, to equal increments of θ . This conversion is important in that it allows the pattern array to be stored as an array of gain points, equally spaced in angle. This eliminates the necessity of storing a gain-angle data pair, since the location of any point in angle can be determined from the ordinal number of the point, the origin of the array, and the angle increment. It is especially important in converting antenna pattern data for plots, since it is desirable that the points be equispaced in the independent variable direction. An additional feature of PLTFMT is that it will automatically eliminate the extraneous output from the Fast Fourier Transform, which is contained in the region commonly known as "invisible space", i.e., that region where the dependent variable lies outside $-1 \leq \text{sine } \theta \leq +1$. Furthermore, by specifying angle limits for the region of interest, superfluous data is eliminated, thereby reducing processing time and storage requirements.

- a. In the first section of the program the input array input parameters are initialized. The end points specified for the input data are examined to determine if they are realistic and within the boundaries of the input array. If not, one of three things happens. (1) If the specified end points exceed the array limits or ± 90 degrees, they are reduced to a useable value. (2) If the limits are equal or reversed, i.e., start point equals stop point or start point is greater than stop point, the limits are set to ± 90 degrees or to be array limits, whichever is less. (3) If the specified

end points are in the proper order, but do not encompass any of the array data, the problem is terminated. If the adjusted end points do not encompass all of the input array, the portion of the input array to simplify processing and the array definition parameters are adjusted accordingly.

- b. The output array elements are computed by interpolating between the input array points. A double parabolic interpolation is used except in the end segments where a single parabolic interpolation is used.

The double parabolic interpolation is performed by generating two quadratic equations, using three adjacent points to generate each equation. Assuming the points are labeled X1, X2, X3, and X4, and the required location is between X2 and X3, then the equations are generated using X1, X2, X3, and X2, X3, X4. Once the quadratic coefficients have been determined, the value of each quadratic at the point of interest is determined, and the two values are averaged to find the value of the dependent variable.

Within the end segments, adjacent points are not available to obtain two quadratic equations. Therefore, a single quadratic is generated and the necessary points are interpolated from this single equation. In all cases, if the point of interest falls exactly on a point in the input array, the actual value of that point is used.

470	ROTATION - PATTERN (GXIN, YIN, GOUT,*)	1940
471	*****	6-26
472	CHECKS THE COINCIDENCE EXTRACTS THE SPECIFIED DATA FROM THE GENERATED	UC7PLT02
473	INTERVAL PATTERNS DETERMINES THE ANGLE OF EACH SCAN POINT,	UC7PLT03
474	AND INTERPOLATES BETWEEN DATA POINTS TO PRODUCE AN OUTPUT	UC7PLT04
475	ANGLE OF GAIN POINTS EQUALLY SPACED IN ANGLES ***** UC7PLT05	
476	COMPUTE THE TOTAL (500)	UC7PLT06
477	*****	
478	INTERPOLATION (XIN, YIN, GOUT) EXECUTED	2000
479	DECODED DATA (XIN, YIN, GOUT) CENTERED	UC7PLT09
480	* DECODED START DECODED STOP *	UC7PLT10
481	DATA FROM AIMS/NIST READ BY 28-1,57-295/EZ	2040
482	DECODED DATA READ BY 28-1,57-295/EZ	2050
483	WRITE LOGFILE	2060
484	THE FINEST ANGLE INCREMENT WAS NOT FINELY CALCULATED FOR THE OUT	2070
485	TEST ARRAY - EXECUTION WILL NOT BE ATTEMPTED	2080
486	REDEFINE	2090
487	END OF LOGFILE (GOUT(019*))	2100

4553 ORIGIN=GXIN(N144) 6-26a 2110
 4554 DELIN=GXIN(N145) 2120
 4555 IF(STARPT.GE.-90.0) GO TO 302 2130
 4556 STARPT=-90.0 2140
 4557 WRITE(6,106)
 4558 106 FORMAT(*START POINT WAS DEFINED BELOW HORIZON. START POINT HAS BEEN
 LEN REDEFINED TO -90 DEG.)
 4559 2150
 4560 302 IF(STOPT.LE.90.0) GO TO 303 2160
 4561 STARPT=90.0 2170
 4562 WRITE(6,111)
 4563 111 FORMAT(*STOP POINT WAS DEFINED BELOW HORIZON. STOP POINT HAS BEEN
 LEN REDEFINED TO 90 DEG.)
 4564 2180
 4565 303 IF(STARPT.LE.STOPT) GO TO 305 2190
 4566 STARPT=-90.0
 4567 STARPT=90.0
 4568 WRITE(6,109)
 4569 109 FORMAT(*STARTING POINT SPECIFIED AS GREATER THAN OR EQUAL TO END
 * POINT. ALL AVAILABLE VISIBLE SPACE WILL BE INTERPOLATED.*)
 4570 2200
 4571 SINSTE=SIN(STARPT/RAD)
 4572 SINSTE=SIN(STOPT/RAD)
 4573 DELTHE=DELTHE /RAD
 4574 9. NINTEFIX((SINSTE-ORIGIN)/DELIN*0.5)
 4575 IF(NINTET.GE.2) GO TO 10 2210
 4576 STARTE=STARPT+DELTHE
 4577 SINSTE=SIN(STARPT/RAD)
 4578 GO TO 9 2220
 4579 10. NINTEFIX((SINSTE-ORIGIN)/DELIN*0.5)
 4580 IF(NSTOP+2.LE.NPTS) GO TO 15 2230
 4581 STARTE=STARPT+DELTHE 2240

06/11/75 INPUT LISTING AUTOFLOW CHART SET - FWD/SCL RADSIM
 CARD NO. **** CONTENTS 6-27 ****

 4562 SINSTP=SIN(STOPT/RAD) 2400
 4583 GO TO 10 2410
 4584 15 STPRAD=STOPT/RAD 2420
 4585 ANGLE=STARHT/RAD 2430
 4586 VIV=ORIGIN+DELIN*FLOAT(NSTRT-2) 2400
 4587 K=1 2441
 4588 WRITE(6,1011) STOPT,STARPT,ORIGIN,DELIN,NPTS,NSTRT,NSTUP 2411
 4589 1011 FOPEN(1H ,4E15.7,3110)
 4590 DU 300 J=NSTRT,NSTUP 2450
 4591 X1=ARSIN(VIV) 2460
 4592 X2=AFSIN(VIV+DELIN) 2470
 4593 VIV=VIV+DELIN 2480
 4594 X3=ARSIN(VIV+DELIN) 2490
 4595 BREAK=(X3+X2)/2.0 2500
 4596 IF(BREAK.GT.STPRAD) BREAK=STPRAD 2510
 4597 Y1=GXIN(J-1) 2520
 4598 Y2=UXIN(J)
 4599 Y3=GXIN(J+1) 2540
 4600 MODE=1 2550
 4601 X12=X1-X2 2560
 4602 350 YX12=(Y1-Y2)/X12 2570
 4603 C1=(YX12-((Y1-Y3)/(X1-X3)))/(X2-X3) 2580
 4604 C2=YX12-C1*(X1+X2) 2590
 4605 C3=Y1-(C1*X1+C2)*X1 2600
 4606 GO TO (401,402), MODE 2610
 4607 401 UX1=C1 2620
 4608 UX2=C2 2630
 4609 CX1=C3 2640
 4610 MODE=2 2650

4011 Y1=Y1+YIN(J-1) 6-27-a 2660
 4012 Y2=YIN(J)
 4013 Y3=YIN(J+1)
 4014 GO TO 300 2670
 4015 CY1=0 2680
 4016 CY2=0 2690
 4017 CY3=0 2700
 4018 IF(ANGLE.GT.0.0)GO TO 294 2710
 4019 CF=(CX1+ANGLE+CX2)*ANGLE+CX3 2720
 4020 CI=(CY1+ANGLE+(CY2))*ANGLE+CY3 2730
 4021 GOUT(K)=2D.0*ALG10(GR*GR+6)*6J 2740
 4022 ANGLE=ANGLE+DELKAB 2750
 4023 K=K+1 2760
 4024 GO TO 400 2770
 4025 299 IF(ANGLE.GT.5TPRAD) GO TO 301 2780
 4026 300 CONTINUE 2790
 4027 GOUT(N143)=BEGL(K-1) 2800
 4028 GOUT(N144)=STARBT 2810
 4029 GOUT(N145)=DELTHE 2820
 4030 RETURN 2830
 4031 END 2840

SUBROUTINE PTLIST

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
PTLIST	PERIP	303,304,305,306

2. PURPOSE:

This subroutine converts the data contained in the input array into a compact form for transmission to a remote processing station which has a CRT plotter.

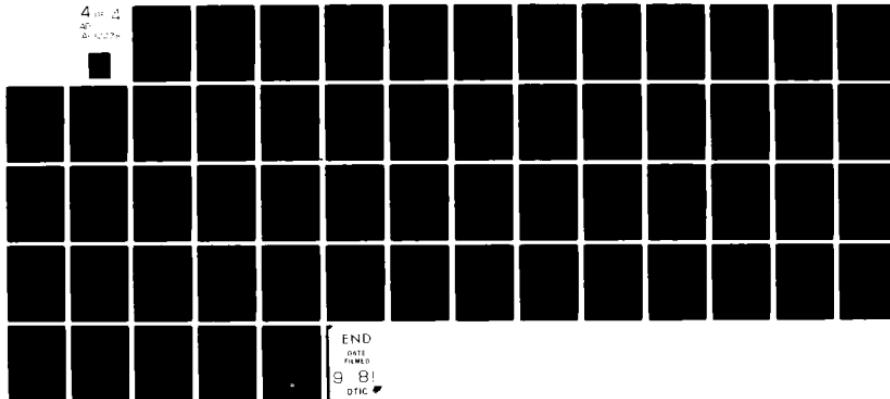
3. INPUT PARAMETERS:

Name	O/R	T	Description
ST	R	F	Value of the independent variable at the start of the plot
RNG	R	F	Range of the independent variable which is to be plotted
LF	R	I	Control index which indicates the nature of the input data
NSKP	O	I	This variable controls the number of input samples skipped between each plotted point. For example, if NSKP = 0 or 1, each point is plotted; if NSKP = 2, every other point is plotted.
NAUTO	O	I	Control flag for automatic data scanner which determines the maximum and minimum values of the dependent variable. If NAUTO = 0 the scanner determines the value of TH and TL. If NAUTO = 1, the user provided input parameters TH and TL are used
TH	O	F	Maximum dependent variable value to be plotted

AD-A102 278 GENERAL DYNAMICS FORT WORTH TEX CONVAIR AEROSPACE DIV F/G 17/9
ENDO ATMOSPHERIC-EXO ATMOSPHERIC RADAR MODELING, VOLUME II. PAR--ETC(U)
JUN 76 R J HANCOCK, F H CLEVELAND F30602-73-C-0380
RADC-TR-76-186-VOL-2-PT-1 NL

UNCLASSIFIED

4 10 4
4P
B 42276



END
DATE
9 81
DTIC

Name	O/R	T	Description
TL	O	F	Minimum dependent variable value to be plotted
IFCODE	R	I	Logical unit designator for output file

4. CALLING SEQUENCES:

CALL PTLIST (DV)

Where: DV contains the Input Waveform

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. A number of tests are performed on the input data to ensure that a plot can be successfully completed. If all the necessary conditions are not satisfied, a condition code index is set and the plotter is bypassed with control returned to the calling program. The following is a list of the condition code values and the meaning of each:

CONDITION CODE INDEX	Error Message
1	The starting point, ST, is outside the input data array. (Too large)
2	The starting point, ST, is outside the input data array. (Too small)
3	The input data variables, ST, RNG, are improperly defined and result in a condition which places the stopping point before the starting point.
4	The user supplied value of TH is less than TL when NAUTO = 1.

b. The subroutine PACK is used to convert the fixed point output data into a form suitable for transmission to remote terminal via TSS.

c. If an output file code (IFCODE) is not specified then no data will be transferred and control will immediately be transferred back to the calling program.

d. Flow Chart: Page 9-82

e. Cross Reference Table: Page 9-218

6. THEORY OF OPERATION

a. Upon entering the subroutine the input parameters are first tested to verify that the range of the desired plot is within the limits of the input data array, DV.

b. If NAUTO = 0, the input data is scanned to determine the maximum, TH, and minimum, TL, values to be plotted. From these two variables the upper and lower limits of the plot are determined.

c. For magnitude data, TH and TL are tested to determine if the input data is bipolar or unipolar.

d. From TH and TL the dependent variable range of the plot is computed and the LSB and BIAS to be used in the conversion from floating point to fixed point is computed.

e. The following plot parameters are processed as one record:

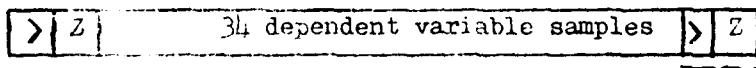
1. TH - Maximum value of input array
2. TL - Minimum value of input array
3. IVST - First value of input array which was processed for output
4. NSTOP - Last value of input array which was processed for output
5. OR - Independent variable value for first output point
6. DEL - Independent variable spacing
7. RNG - Independent variable range of the output data

f. The following plot parameters are processed for output as one record:

1. BIAS - Number subtracted from input data before conversion to fixed point
 2. XLSB - LSB of output data
 3. - Not used
 4. ITH - Largest dependent variable output value
 5. ITL - Smallest dependent variable output value
 6. NOUT - Number of output samples
- g. The dependent variable values are processed for output. The mechanization equation for this conversion is the following:

$$IDAT = (DV(J) - BIAS) / XLSB \quad IVST \leq J \leq NSTOP$$

The integer IDAT is then processed by the routine PACK which converts it into 2 characters and packs it into the array line which represents our output record and has the following structure:



header character pair

trailer character pair

6-32

```
2200      SUBROUTINE PELISTC(DV)
2207      COMMON/PELIC/  BR1(200),ML1(50),VL1(50),RLD1(50)
2208      EQUIVALENCE  C  BR1( 50), ST      F,F  BR1( 50), RRD
2209      *          C  BR1( 62), LF      F,F  BR1( 62), NSRP    16
2210      *          C  BR1( 63), NAUTO   F,F  BR1( 63), IR      20
2211      *          C  BR1( 64), TL      F,F  BR1( 64), INCLUDE  1
2212      DIMENSION DV(11),ML1(50)
2213      DATA N195,N196,N197/ -3.0,-2.0,-1.0 /,XMIN1/-1.0,-1.0 /
2214      DATA LL100/0.7617/0.000000/
2215      IF(LL100.EQ.0.0) GOTO 200
2216      IF(LL100.LT.0.0) GOTO 200
2217      NEL = ILL100(DV(19),33)
2218      LF = DV(NEL+1)
2219      LL = DV(NEL+1)
2220      TAU1=LN(LF)
2221      TAU2=LNLG(LL)
2222      KNL=LN(LL+LF+1)
2223      S1=0
2224      N=1
2225      DO 100 I=N,1,-1
2226      TAU3=LN(LL+LF+1)
2227      LF=LN(LL+1)
2228      LL=LN(LL)
2229      TAU4=LN(LL+LF+1)
2230      S1=S1+(TAU3-TAU4)*LN(LL+1)
```

6-32a

```
2291      IF (IVST+GE+NITL) NCTRL = 1
2292      NSTOP = IFIX((ST-CR+RNG)/DEL) + 1
2293      CR=CR+(IVST-1)*DEL
2294      IF (NSTOP.GT.NITL) NSTOP = NITL
2295      IF (NSTOP.LE.IVST) NCTRL = 0
2296      IF (NCTRL.NE.0) GO TO 1100
2297      IF (LF.LT.2) LL TO 40
2298      DL 45 J=IVST+NSTOP
2299      X=AMAX1(AE(UV(J)),XMINDE)
2300      IF (LF.LT.2) GO TO 41
2301      DV(J)=DL*ALG-10(X)
2302      GO TO 42
2303      41 DV(J)=ALG10(X)
2304      42 CONTINUE
2305      43 CONTINUE
2306      44 CONTINUE
2307      TH = DV(IVST)
2308      TL = TH
2309      IF (NCTRL.NE.0) GL TL 1100
2310      DL 1100 J=IVST+NSTOP
2311      TH = AMAX1(UV(J),TH)
2312      TL = AMIN1(DV(J),TL)
2313      100 CONTINUE
2314      IF (TH.GT.TL) GO TO 2001
2315      NCTRL=5
2316      GO TL 1100
2317      2001 CONTINUE
2318      DEL=DEL*ELLAT(NSKP)
2319      NCUT=(NSTOP-IVST)/NSKP+1
```

06/12/73

INPUT LISTING

AUTOFLOW CHART SET - FNU/SLL FAUSIM

6-33

CARD NO.

CONTENTS

2320 LINE(1)=BLUL(TH)
 2321 LINE(2)=BLUL(TL)
 2322 LINE(3)=IVST
 2323 LINE(4)=NSTUP
 2324 LINE(5)=BLUL(UR)
 2325 LINE(6)=BLUL(LEFT)
 2326 LINE(7)=BLUL(RNG)
 2327 WRITE(LFILEDE) LINE
 2328 IF(FLLE.LT.0.0.E+0.3) GOTO 700
 2329 IF(TH.LE.0.0) ICUN=1
 2330 IF(TL.GE.0.0) ICUN=2
 2331 IF(TH.GT.0.0.AND.TL.LT.0.0) ICUN=3
 2332 FTH= AMAX1(AJS(TH),APS(TL))
 2333 FILE= ALLOCATE(FTH)
 2334 ITEST = 1FIX(FTH)
 2335 IF(FLLE.LT.0.0) GO TO 150
 2336 X=FTH/(10.0**ITEST)
 2337 GO TO 150
 2338 150 X=FTH*(10.0**(IABS(ITEST)+1))
 2339 160 CONTINUE
 2340 N=20
 2341 IF(X.GE.+1.0 AND X.LE.+5.0) N=2
 2342 IF(X.GE.-1.0 AND X.LE.-3.0) N=4
 2343 IF(X.GE.-5.0 AND X.LE.-9.0) N=5
 2344 IF(X.GE.-9.0 AND X.LE.-7.0) N=1
 2345 IF(X.GE.-7.0 AND X.LE.-4.0) N=10
 2346 IF(FLLE.LT.0.0) GO TO 350
 2347 FILE= ALLOCATE(FTH*(10.0**ITEST))
 2348 GO TO 350

```

2344      DO 500 RTH = FLLAT(N) / (10.0**((IABS(ITALST)+1))
2345      500 CONTINUE
2351          ALSD=RTH/40000.0
2352          BIAS=0.0
2353          GO TO(344,401,402),ICON
2354      340 AMX = 0.0
2355      400 AMN = -RTH
2356          AMD = -RTH/2.0
2357          DINC = RTH/100.0
2358          GO TO 404
2359      401 AMX = RTH
2360          AMN = 0.0
2361          AMD = RTH/2.0
2362          DINC = RTH/100.0
2363          GO TO 404
2364      402 AMX = RTH
2365          AMN = -RTH
2366          AMD = 0.0
2367          DINC = RTH/50.0
2368          GO TO 404
2369      400 AMD=ABS(RTH-TL)
2370          N = (IFIX (AMD/10.0))*10
2371          IF (AMD.GT.100.0) N=100
2372          AMX = (FLLAT(IFIX(RTH/10.0)))*10.0
2373          IF (AMX.LT.-1.0) AMX=AMX+10.0
2374          AMN= AMX-FLLAT(N)
2375          IF (AMN.GT.1.0 .AND. N.LT.100) N=N+10
2376          IF (N.GT.90) N=100
2377          IF (N.LE.50) N=50

```

06/11/75

INPUT LISTING

AUTOFLOW CHART SET - FMC/SCL RADSIM

634 ****

CARD NO.

CONTENTS

2373 IF(N.EQ.00,0K,N.EQ.70) N=0
 2374 EIAS= AMX-FLUAT(N)
 2380 XLSB=0.05
 2381 IF(N.LE.40) XLSB=0.01
 2382 IF(N.LT.40.AND.N.LE.60) XLSB=0.02
 2383 404 IF(NCTRL.NE.0) GL TL 1100
 2384 ITL=(TL-EIAS)/XLSB
 2385 ITH=(TH-EIAS)/XLSB
 2386 LINE(1)=BLDL(EIAS)
 2387 LINE(2)=BLDL(XLSB)
 2388 LINE(3)=N
 2389 LINE(4)=ITH
 2390 LINE(5)=ITL
 2391 LINE(6)=RBL
 2392 WRITE(1F000) LINE
 2393 LINE(1)=LSTCH
 2394 LINE(1C)=LSTCH
 2395 501 IWD=1
 2396 101T=10
 2397 CALL PACK(INUT,IWD,IBIT,LINE,31100)
 2398 DO 400 J=1VST,NSTLP+NSKF
 2399 400 IJAT=(UV(J)-EIAS)/XLSB
 2400 IF(IJAT.GT.+0.05) IJAT=+0.05
 2401 IF(IJAT.LT.-0.05) IJAT=-0.05
 2402 CALL FAUT(IJAT,IWD,IBIT,LINE,3500)
 2403 UC TL 400
 2404 502 WRITE(1F000) LINE
 2405 1W0=1
 2406 101T=10

29-6 2000 Undefined b-34a
29-6 2000 Inflow from mainline Federal Building
29-6 2000 Watermarks Federal
29-6 2000 No flow
29-6 2000 Watermarks Federal
29-6 2000 No flow
29-6 2000 NO FLOW NOT ATTEMPTED due to condition code -9999
29-6 2000 Watermarks Federal
29-6 2000 NO FLOW NOT ATTEMPTED due to condition code -9999
29-6 2000 NO FLOW NOT ATTEMPTED due to condition code -9999
29-6 2000 NO FLOW NOT ATTEMPTED due to condition code -9999

SUBROUTINE RTOPDB

1. MODULE IDENTIFICATION:

<u>Name</u>	<u>Classification Code</u>	<u>Reference Number</u>
RTOPDB	Peripheral	103
RTOPM	Peripheral	110
RTOPM2	Peripheral	111
XYTOM	Peripheral	105
XYTOM2	Peripheral	106
XYTODB	Peripheral	104, 108

2. PURPOSE:

This subroutine performs a rectangular to polar conversation on the input arrays. Depending on the entry point used, the output is in two arrays in the form of linear magnitude and phase (RTOPM), magnitude squared and phase (RTOPM2) or magnitude in decibels and phase (RTOPDB); or in one array of linear magnitude (XYTOM), linear magnitude squared (XYTOM2) or magnitude in decibels (XYTODB).

3. INPUT PARAMETERS: None

4. CALLING SEQUENCES:

Phase and decibel magnitude

CALL RTOPDB (X,Y,M,P)

Where:

X contains the Input Waveform - R

Y contains the Input Waveform - I

M contains the Output Waveform

P contains the Output Waveform - P

$$M(J) = 10.0 * \text{ ALOGIO} [X(J) * X(J) + Y(J) * Y(J)]$$

$$P(J) = \frac{180.0}{\pi} * \text{ ATAN2} (Y(J), X(J))$$

Phase and linear magnitude

CALL RTOPM (X,Y,M,P)

Where:

X contains the Input Waveform - R

Y contains the Input Waveform - I

M contains the Output Waveform - M

P contains the Output Waveform - P

$$M(J) = \sqrt{X(J) * X(J) + Y(J) * Y(J)}$$

$$P(J) = \frac{180.0}{\pi} * \text{ATAN2 } (Y(J), X(J))$$

Phase and magnitude squared

CALL RTOPM2 (X,Y,M,P)

Where:

X contains the Input Waveform - R

Y contains the Input Waveform - I

M contains the Output Waveform - M

P contains the Output Waveform - P

$$M(J) = X(J) * X(J) + Y(J) * Y(J)$$

$$P(J) = \frac{180.0}{\pi} * \text{ATAN2 } (Y(J), X(J))$$

Linear magnitude and no phase

CALL XYTOM (X, Y, M)

Where:

X contains the Input Waveform - R

Y contains the Input Waveform - I

M contains the Output Waveform

$$M(J) = \sqrt{X(J) * X(J) + Y(J) * Y(J)}$$

Magnitude squared and no phase

CALL XYTOM2 (X,Y,M)

Where:

X contains the Input Waveform - R

Y contains the Input Waveform - I

M contains the Output Waveform

$$M(J) = X(J) * X(J) + Y(J) * Y(J)$$

Magnitude in dB and no phase

CALL XYTODB (X,Y,M)

Where:

X contains the Input Waveform - R

Y contains the Input Waveform - I

M contains the Output Waveform

$$M(J) = 10.0 * \text{ ALOGIO} [X(J) * X(J) + Y(J) * Y(J)]$$

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. For entry points RTOPDB and XYTODB the minimum output value is -200 dB.
- b. The range of the output phase angle is from -190° to $+170^{\circ}$. The break point where phase "rolls over" was chosen to be 170° instead of 180° because many waveforms have a large number of samples around 180° and each time the waveform's phase changes from $180-E$ to $180+E$ the output phase would change from $180-E$ to $-180+E$. This results in a phase plot with many undesirable and unnecessary discontinuities.
- c. Flow Chart: Page 9-156
- d. Cross Reference Table: Page 9-228.

4000 SUBROUTINE KTEPDB(X,Y,M,P)
4005 COMMUN/DEK1/ DK1(500)
4010 EQUIVALENCE (DK1(36), NAVG)
4011 DIMENSION X(1),Y(1),M(1),P(1)
4012 REAL M
4013 DATA N193,N196,N4/-3,0+4/
4014 DATA A1/57.29578/
4015 ICLN = 0
4016 NPHASE=1
4017 GO TO 10
4018 ENTRY KTEFMEX,X,Y,M,P)
4019 ICLN = 2
4020 NPHASE=1
4021 GO TO 10
4022 ENTRY KTEFN2(X,Y,M,P)
4023 ICLN = 0
4024 NPHASE=2
4025 GO TO 10
4026 ENTRY XYELM(X,Y,M)
4027 ICLN=1
4028 NPHASE=0
4029 GO TO 10
4030 ENTRY XYELM2(X,Y,M)

6-38a k

```

4031          ICLN=0
4032          NPHAS=0
4033          GO TO 10
4034          ENTRY XYDLDE(X,Y,M)
4035          ICLN=2
4036          NPHAS=0
4037          L
4038          TO CONTINUE
4039          N=1000L(X(N1Y0))
4040          CALL DLKX(N1Y0,N4,X,M)
4041          IF(NPHAS.EQ.0) CALL DLKX(N1Y0,N4,X,P)
4042          IF(NPHAS.EQ.0.AND.NAVU.GT.1) OUTL 200
4043          IF(NPHAS.EQ.0) P(N1Y0)=0.0
4044          *****+
4045          DL 100 J=1,N
4046          IF(NPHAS.EQ.0) GO TO 50
4047          IF(X(J).EQ.0.0.AND.Y(J).EQ.0.0) GL TL 40
4048          P(J) = A1 * ATAN2(Y(J),X(J))
4049          IF(P(J).GT.17.0) P(J)=P(J)-360.0
4050          GL TL 50
4051          H(J) = P(J-1)
4052          TO CONTINUE
4053          M(J)= X(J)*X(J)+Y(J)*Y(J)
4054          IF(1.0E-12.LT.M(J)) M(J)=SQR(M(J))
4055          IF(1.0E-12.LT.M(J)) GO TL 100
4056          IF(M(J).LT.1.0E-20) M(J)=1.0E-20
4057          M(J)= 1.0E-12*LCLN(M(J))
4058          100 CONTINUE
4059          RETURN

```

00/12/75

INPUT LISTING

AUTOFLOW CHART SET - FWG/SCL RAUSIM

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L48D.FW

CONTENTS

4060 L00 LC 210 J=1,N
4061 M(J)=X(J)*X(J)+Y(J)*Y(J)
4062 L10 CONTINUE
4063 AV=0.0
4064 LC 220 J=1,NAVG
4065 AV=AV+M(J)
4066 L20 CONTINUE
4067 N=N-NAVG
4068 XAVG=1.0/FLUAT(NAVG)
4069 LC 230 J=1,N
4070 DUM=M(J)
4071 M(J)=AV*XAVG
4072 IF (ICUN.LW.1) M(J)=SQRT(M(J))
4073 IF (ICUN.NE.2) GOTO 225
4074 IF (M(J).LT.1.0E-20) M(J)=1.0E-20
4075 M(J)= 10.0*ALLG10(M(J))
4076 L25 AV=AV-DUM+M(J+NAVG)
4077 L30 CONTINUE
4078 M(N195)=B0UL(N)
4079 RETURN
4080 END

R

SUBROUTINE SCANNR

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
SCANNR	PERIP	313

2. PURPOSE:

This subroutine scans an antenna pattern in the form of an input array and determines the location and gain of (1) the main lobe, (2) the highest ten sidelobes, and (3) the first twenty sidelobes on either side of the main lobe. In addition, the first minimum on either side of the main lobe is determined.

3. INPUT PARAMETERS:

None

4. CALLING SEQUENCES:

CALL SCANNR (DV)

Where: DV contains the Input Waveform in
dB gain

5. RESTRICTION, REQUIREMENTS, MISCELLANEOUS DATA

- a. All output data from this subroutine is in the form of a printed listing which is formatted for ease of interpretation.
- b. If a vestigial lobe exists, the minimum between it and the main lobe will be detected as the main lobe null.
- c. Flow Chart: Page 9-161
- d. Cross Reference Table: Page 9-229

6. THEORY OF OPERATION

- a. The antenna pattern data is scanned from left to right (increasing θ) and the gain maxima are stored in a 22 element array. Within this array, the maxima are ordered according to gain with the highest in element 1 and the lowest in element 22.
- b. The pattern data to the right of the main lobe is scanned to locate the main lobe null and the first twenty sidelobes. After this data is processed and printed, a third scan is made to the left of the main lobe for the first null and the first twenty sidelobes.
- c. The logical equation used to determine the peaks of the lobes is as follows:

Given three adjacent points DV(NTHPT-1), DV(NTHPT), and DV(NTHPT+1) the following difference parameters are computed.

$$\begin{aligned} \text{DELDV1} &= \text{DV}(\text{NTHPT}) - \text{DV}(\text{NTHPT}-1) \\ \text{DELDV2} &= \text{DV}(\text{NTHPT}+1) - \text{DV}(\text{NTHPT}) \end{aligned}$$

then if $\text{DELDV1} \geq 0$ and $\text{DELDV2} \leq 0$,
the point DV(NTHPT) is considered to be a
maxima, i.e., the peak of a lobe.

- d. In order to find the nulls of the main lobe, the difference parameters defined in 6(c) are tested for the following condition:

$$\text{DELDV1} < 0 \text{ and } \text{DELDV2} \geq 0$$

If this condition is satisfied then DV(NTHPT) is considered to be a null. After the first null is found, a flag is set which causes the null test to be bypassed for the remainder of the scan on that side of the main lobe. It should be noted that the null logic will consider the minimum between the main lobe and a vestigial sidelobe (if one exists) to be the main lobe null.

4142 SUBROUTINE SCANNER(DV) 6-42 UC7SCN01
 4143 C UC7SCN02
 4144 **** THIS SUBROUTINE SCANS THE UNINTERPOLATED ANTENNA PATTERN DATA AND UC7SCN03
 4145 COMPUTES THE MAIN Lobe NULL POINTS AND SIGNIFICANT SIDE-LobES. ***** UC7SCN04
 4146 C UC7SCN05
 4147 C IMPLICIT DOUBLE PRECISION ALLEGRA(22), ALLEGN(22), DV(11)
 4148 DATA N193, N194, N195, N196/-3,-2,-1,0/
 4149 EQUIVALENCE (NPTS,XPTS)
 4150 C UC7SCN06
 4151 C WRITE(6,414)
 4152 ! FORMAT(1H0/47X,* * * * * ANTEENA Lobe SCANNER * * * * * //) UC7SCN11
 4153 NPTS = ALLEG(DV(N193)) UC7SCN22
 4154 XPTS = DV(N194) UC7SCN13
 4155 PTSPT = DV(N195) UC7SCN14
 4156 **** INITIALIZE Lobe STORAGE ARRAY **** UC7SCN15
 4157 DO 10 N=1,CC UC7SCN16
 4158 L0PFT(N) = 0 UC7SCN17
 4159 10 ALLOCATE(L0PFT) = -20000 UC7SCN18
 4160 C UC7SCN19
 4161 **** FIND MAXIMA **** UC7SCN37
 4162 DO 70 NI=NPT-1,NPTS UC7SCN38
 4163 DO 60 MI=NPT-1,1 UC7SCN39

6-43 UC7SLN40
 6-43 UC7SLN41
 6-43 UC7SLN42
 6-43 UC7SLN43
 6-43 UC7SLN44
 6-43 UC7SLN45
 6-43 UC7SLN46
 6-43 UC7SLN47
 6-43 UC7SLN48
 6-43 UC7SLN49
 6-43 UC7SLN50
 6-43 UC7SLN52
 6-43 UC7SLN53
 6-43 UC7SLN54
 6-43 UC7SLN55
 6-43 UC7SLN56
 6-43 UC7SLN57
 6-43 UC7SLN58
 6-43 UC7SLN59
 6-43 UC7SLN60
 6-43 UC7SLN61
 6-43 UC7SLN62
 6-43 UC7SLN63
 6-43 UC7SLN64
 6-43 UC7SLN65
 6-43 UC7SLN66
 6-43 UC7SLN67

***** COMPUTE TWENTY-ONE HIGHEST MAXIMA *****
 6-43 ALGON(21-NF) = ALGON(21-NF) + UC7SLN70
 6-43 ANTRB = ALGON(21-NF)
 6-43 ALGON(22-NF) = ALGON(22-NF)
 6-43 ALGON(23-NF) = ANTRB
 6-43 ALGON(24-NF) = LUSFT(23-NF)
 6-43 ALGON(25-NF) = NLCLBT
 6-43 ANTRB = ALGON(25-NF)
 6-43 ANTRB = ALGON(26-NF)
 6-43 ANTRB = ALGON(27-NF)
 6-43 ANTRB = ALGON(28-NF)
 6-43 ANTRB = ALGON(29-NF)
 6-43 ANTRB = ALGON(30-NF)
 6-43 ANTRB = ALGON(31-NF)
 6-43 ANTRB = ALGON(32-NF)
 6-43 ANTRB = ALGON(33-NF)
 6-43 ANTRB = ALGON(34-NF)
 6-43 ANTRB = ALGON(35-NF)
 6-43 ANTRB = ALGON(36-NF)
 6-43 ANTRB = ALGON(37-NF)
 6-43 ANTRB = ALGON(38-NF)
 6-43 ANTRB = ALGON(39-NF)
 6-43 ANTRB = ALGON(40-NF)
 6-43 ANTRB = ALGON(41-NF)
 6-43 ANTRB = ALGON(42-NF)
 6-43 ANTRB = ALGON(43-NF)
 6-43 ANTRB = ALGON(44-NF)
 6-43 ANTRB = ALGON(45-NF)
 6-43 ANTRB = ALGON(46-NF)
 6-43 ANTRB = ALGON(47-NF)
 6-43 ANTRB = ALGON(48-NF)
 6-43 ANTRB = ALGON(49-NF)
 6-43 ANTRB = ALGON(50-NF)
 6-43 ANTRB = ALGON(51-NF)
 6-43 ANTRB = ALGON(52-NF)
 6-43 ANTRB = ALGON(53-NF)
 6-43 ANTRB = ALGON(54-NF)
 6-43 ANTRB = ALGON(55-NF)
 6-43 ANTRB = ALGON(56-NF)
 6-43 ANTRB = ALGON(57-NF)
 6-43 ANTRB = ALGON(58-NF)
 6-43 ANTRB = ALGON(59-NF)
 6-43 ANTRB = ALGON(60-NF)
 6-43 ANTRB = ALGON(61-NF)
 6-43 ANTRB = ALGON(62-NF)
 6-43 ANTRB = ALGON(63-NF)
 6-43 ANTRB = ALGON(64-NF)
 6-43 ANTRB = ALGON(65-NF)
 6-43 ANTRB = ALGON(66-NF)
 6-43 ANTRB = ALGON(67-NF)
 6-43 ANTRB = ALGON(68-NF)
 6-43 ANTRB = ALGON(69-NF)
 6-43 ANTRB = ALGON(70-NF)
 6-43 ANTRB = ALGON(71-NF)
 6-43 ANTRB = ALGON(72-NF)
 6-43 ANTRB = ALGON(73-NF)
 6-43 ANTRB = ALGON(74-NF)
 6-43 ANTRB = ALGON(75-NF)
 6-43 ANTRB = ALGON(76-NF)
 6-43 ANTRB = ALGON(77-NF)
 6-43 ANTRB = ALGON(78-NF)
 6-43 ANTRB = ALGON(79-NF)
 6-43 ANTRB = ALGON(80-NF)
 6-43 ANTRB = ALGON(81-NF)
 6-43 ANTRB = ALGON(82-NF)
 6-43 ANTRB = ALGON(83-NF)
 6-43 ANTRB = ALGON(84-NF)
 6-43 ANTRB = ALGON(85-NF)
 6-43 ANTRB = ALGON(86-NF)
 6-43 ANTRB = ALGON(87-NF)
 6-43 ANTRB = ALGON(88-NF)
 6-43 ANTRB = ALGON(89-NF)
 6-43 ANTRB = ALGON(90-NF)
 6-43 ANTRB = ALGON(91-NF)
 6-43 ANTRB = ALGON(92-NF)
 6-43 ANTRB = ALGON(93-NF)
 6-43 ANTRB = ALGON(94-NF)
 6-43 ANTRB = ALGON(95-NF)
 6-43 ANTRB = ALGON(96-NF)
 6-43 ANTRB = ALGON(97-NF)
 6-43 ANTRB = ALGON(98-NF)
 6-43 ANTRB = ALGON(99-NF)
 6-43 ANTRB = ALGON(100-NF)

INPUT LISTING		AUTOFLOW CHART SET - FWC/SCL RADSIM	
CARD NO.	*****	CONTENTS	
4170	DL 75 N=2+1	UC7SCN68	
4177	GAIN = ALUGRGN(1) - ALURGN(1)	UC7SCN69	
4178	NK = N-1	UC7SCN70	
4179	ANGLE = XLRG + (LLPPT(N)-1)*FTSPC	UC7SCN71	
4180	WHILE(0,74) NK, GAIN, ANGLE	UC7SCN73	
4181	74 FLCMAT (JAX, 12, 1:X, #13.7, 14X+13.7)	UC7SCN	
4182	75 CONTINUE	UC7SEN75	
4183	C	UC7SCN76	
4184	WHILE(0,75)	UC7SCN77	
4185	76 FLCFORMAT(1H1+21X,*MAIN LINE NULL AND FIRST 20 SIDE-LINES TO RIGHT OF*)UC7SCN78		
4186	* (ADDITIONAL MAIN LINE*)	UC7SCN79	
4187	*/3SX,*ANK*,1SX,*REL. GAIN*,1SX,*TRUE ANGLE*,1SX,*REL. ANGLE*		
4188	*/ 57X,* (DEG 1*,16X,* (DEG 1*)+16X,* (DEG 1*) /)		
4189	C	UC7SCN82	
4190	***** INITIALIZE RIGHHAND SLANNER *****	UC7SCN83	
4191	NULFLG = 0	UC7SCN84	
4192	NLN = 1	UC7SCN85	
4193	NWSTRT = LLEFT(1)+1	UC7SCN86	
4194	C	***** FIND SIDE-LINES TO RIGHT OF MAIN LINE *****	UC7SCN87
4195	DL 65 NTHPT=NWSTRT,NPTS	UC7SCN88	
4196	ULLUVI = DV(NTHPT) - DV(NTHPT-1)	UC7SCN89	
4197	ULLUV2 = DV(NTHPT+1) - DV(NTHPT)	UC7SCN90	
4198	IF (ULLUVI .LT. 0.0 .AND. ULLUV2 .LT. 0.0) CL TO 82	UC7SCN91	
4199	***** FIND RIGHHAND MAIN LINE NULL *****	UC7SCN92	
4200	IF (NULFLG .LT. 0 .OR. ULLUV1 .GT. 0.0 .OR. ULLUV2 .LT. 0.0) GO TO 85	UC7SCN93	
4201	NULFLG = 1	UC7SCN94	
4202	***** COMPUTE ANGLE OF RIGHHAND MAINLINE NULL *****	UC7SCN95	
4203	AMNLKT = XLRG + (NTHPT-1)*FTSPC	UC7SCN96	
4204	WHILE (0,14) AMNLKT	UC7SCN98	

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INPUT LISTING

AUTOFLOW CHART SET - FWD/SCL RADSIM

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CARD NO.	*****	CONTENTS	*****
4234	NULLFLG = 0		UC7SCN28
4235	C		UC7SCN29
4236	L***** FIND SIDE-LOBES TO LEFT OF MAIN LOBE *****		UC7SCN30
4237	DL = NXPT-1,NWSTP		UC7SCN31
4238	NXPT = NWSTP - NXPT		UC7SCN32
4239	DELDV1 = DV(NXPT) - DV(NXPT-1)		UC7SCN33
4240	DELDV2 = DV(NXPT+1) - DV(NXPT)		UC7SCN34
4241	IF (DELDV1 .LT. 0.0 .AND. DELDV2 .LT. 0.0) GO TO 90		UC7SCN35
4242	L***** FIND LEFTHAND MAIN Lobe NULL *****		UC7SCN36
4243	IF (NULLFLG.LT.1 .OR. DELDV1.GE.0.0 .OR. DELDV2.LT.0.0) GO TO 43		UC7SCN37
4244	L***** COMPUTE ANGLE OF LEFTHAND MAINLOBE NULL *****		UC7SCN38
4245	AMNLFT = XORG + (NXPT-1)*FTSPC		UC7SCN39
4246	NULLFLG = 1		UC7SCN41
4247	WRITE (6, 64) AMNLFT		UC7SCN42
4248	GO TO 93		UC7SCN43
4249	C		UC7SCN44
4250	L***** COMPUTE RELATIVE GAIN AND RELATIVE ANGLE OF LEFTHAND SIDE-LOBES *		UC7SCN45
4251	MU, LNTINDE		UC7SCN46
4252	GAIN = DV(NXPT) - ALORGNT1		UC7SCN47
4253	ANGLE = XORG + (NXPT-1)*FTSPC		UC7SCN48
4254	RELANG=ANGLE - ANGLM		
4255	C		UC7SCN50
4256	WRITE (6, 64) MU,GAIN,ANGLE,RELANG		
4257	DN, FORMAT(15X, 13x, 2(15X,F13.7))		
4258	C		UC7SCN53
4259	NLT = NLB+1		UC7SCN54
4260	L***** EXIT AFTER TWENTY SIDE-LOBES OR DROF THROUGH AT END OF DATA ****		UC7SCN55
4261	IF (NLT .LT. 20) GO TO 100 TO 95		UC7SCN56
4262	MU, LNTINDE		UC7SCN57
4263	C		UC7SCN58
4264	WRITE (6, 64)		UC7SCN59
4265	C		UC7SCN60
4266	MU, LNTINDE		UC7SCN61
4267	CNC		UC7SCN62

S E C T I O N 7
S U P E R V I S O R Y M O D U L E S

This section includes those modules that supervise existing stimulus/transfer function modules to simulate the frequency scanned and time scanned array radar systems. This group includes ANTARY and TSRPAT, which are located in Volume III.

S E C T I O N 8
S U B O R D I N A T E M O D U L E S

This section includes all those modules which are subordinate to the larger stimulus/transfer function modules, peripheral modules or supervisory modules. They include both subroutines and functions. Included in this group are the following modules:

ABORT	IBOOL
ANTINT	IFLD
AZGAIN/ELGAIN	IPACK
BLOCK DATA	PACK
DBLXX	RRAND

The following subordinate modules are related to the bistatic target model and target imaging and are located in Volume I, Part 3:

BISTGT
GAM
BESS
EXPI

EXPI is also located in Volume IV, Part 2.

SUBROUTINE ABORT

1. MODULE IDENTIFICATION:

Name	Classification	Reference Number
ABORT	Subordinate	Not user referenced
ERRMSG	Subordinate	Not user referenced

2. PURPOSE:

This subroutine is used to print coded error messages to the user.

3. INPUT PARAMETERS:

Name	O/R	T	Description
NCODE	R	I	Error message code number. $0 < \text{NCODE} \leq 999$

4. CALLING SEQUENCES:

CALL ABORT (NCODE)

A message is printed which states a fatal error has occurred and execution will terminate.

CALL ERRMSG (NCODE)

A message is printed which states a non-fatal error has occurred, a fix-up procedure done, and execution continued.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

a. Flow Chart: Page 9-81

b. Cross Reference Table: Page 9-218

2254 SUBROUTINE ABORT(INCLUDE) 8-3
 2255 COMMON/SYSX MODULE
 2256 WRITE(6,1001) NCODE,MODULE
 2257 1000 FERMAT(* ERROR : *,13,* OCCURRED DURING EXECUTION OF MODULE : *,
 2258 * 13,*.....FATAL ERROR: JOB WILL TERMINATE*)
 2259 CALL EXIT
 2260 ENTRY ERMSL(INCLUDE)
 2261 WRITE(6,1001) NCODE,MODULE

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CAKO NO	***+	CONTENTS	****
2262		1001 FERMAT(* ERROR : *,13,* OCCURRED DURING EXECUTION OF MODULE : *, * 13,*.....FIX-UP DONE, REFER TO L.P.D. ; JOB WILL CONTINUE*)	
2263		RETURN	
2264		END	
2265			

SUBROUTINE ANTINT

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
ANTINT	Subordinate	(301)

2. PURPOSE:

This subroutine generates an interpolation table from the user provided sampled antenna pattern data. The interpolation table is subsequently used by the functions AZGAIN and ELGAIN to compute antenna gain.

3. INPUT PARAMETERS:

Name	O/R	T	Description
NPT	R	I	Number of user specified antenna gain values
BSIT	O	F	Angle between zero angle of user specified pattern and zero angle in radar coordinates (usually = 0.0)
ANTP(2,75)	R	F	User specified gain pattern array. ANTP(1,J) is the gain of the Jth sample. ANTP(2,J) is the angle of the Jth sample.

4. CALLING SEQUENCES:

CALL ANTINT (NPT, BSIT, ANTP, CDEF)

Where: ANTP contains the Input Antenna Pattern
COEF contains the Output Interpolation coefficients table.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- If no antenna pattern is specified then the coefficients table is set up to represent an omnidirectional antenna of unity gain.

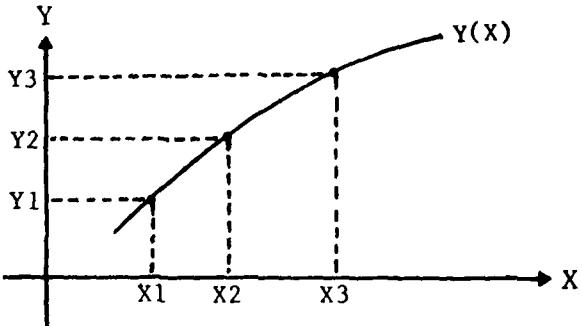
b. Flow Chart: Page 9-140

c. Cross Reference Table: Page 9-226.

6. THEORY OF OPERATION

This module implements a simplified antenna representation which is based on computing the antenna gain as the product of samples from an azimuth and elevation pattern cuts through the peak of the main lobe. The azimuth pattern is true antenna gain in power units. The elevation pattern is normalized to unity gain at the peak of the main lobe.

The parabolic interpolation scheme mechanized herein is described in the following paragraph. Given three points a parabolic curve can be determined which passes through them.



$$Y(X) = X^2 A + XB + C$$

where A, B, and C are the coefficients to be determined

$$A = \frac{XY_{12} - XY_{13}}{X_2 - X_3}$$

$$B = XY_{12} - A * (X_1 + X_2)$$

$$C = Y_1 - (X_1 A + B) * X_1$$

$$XY_{12} = \frac{Y_1 - Y_2}{X_1 - X_2} \quad \text{and} \quad XY_{13} = \frac{Y_1 - Y_3}{X_1 - X_3}$$

In determining the coefficient table elements a double parabolic coefficient is used where possible. This is done by determining 2 sets of coefficients for 2 curves through 4 points and averaging the coefficients. Typically a double parabolic curve fit is smoother than a single parabolic curve fit.

3633 SUBROUTINE ANTINT(NPT,ESIT,ANTP,CDEF)
3634 L
3635 DIMEN 1LN ANTP(2,75),CDEF(4,75)
3636 IF(NPT.GT.2) GO TO 50
3637 CDEF(1,1)=0.0
3638 CDEF(2,1)=0.0
3639 CDEF(3,1)=0.0
3640 CDEF(4,1)=1.0
3641 CDEF(1,2)=0.0001
3642 CDEF(2,2)=0.001
3643 CDEF(3,2)=0.001
3644 CDEF(4,2)=0.01
3645 IF(NPT.NE.2) GO TO 40
3646 CDEF(1,1)=ANTP(2,1)+ESIT
3647 CDEF(4,1)=ANTP(1,1)
3648 CDEF(1,2)=ANTP(2,2)+ESIT
3649 40 CDEF(1,70)=BULL(2)
3650 NPT=2
3651 GO TO 50
3652 GO CONTINUE
3653 CDEF(1,70)=BULL(NPT)

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INPUT LISTING

AUTOFLOW CHART SET ~ FNU/SCL FAUSIM

CARD NO.

CONTENTS

S-7
888

3654 NPT₂=NPT₋₂
 3655 A1=0.0
 3656 B1=0.0
 3657 C1=0.0
 3658 FLG = 1.0
 3659 DO 100 K=1,NPT₂
 3660 L=K+1
 3661 M=K+2
 3662 XY1Z=(ANTP(1,K)-ANTP(1,L))/(ANTP(2,K)-ANTP(2,L))
 3663 XY1D=(ANTP(1,K)-ANTP(1,M))/(ANTP(2,K)-ANTP(2,M))
 3664 AL=(XY1Z-XY1D)/(ANTP(2,L)-ANTP(2,M))
 3665 DL=XY1Z-AL*(ANTP(2,K)+ANTP(2,L)+2.0*ESIT)
 3666 TEMP=ANTF(2,K)+BSIT
 3667 CL=ANTF(1,K)-TEMP*(A2*TEMP+E2)
 3668 CL=ANTP(1,K)-ANTP(2,K)*(A2*ANTP(2,K)+S2)
 3669 C
 3670 CLLF(1,K)=ANTF(2,K)+BSIT
 3671 CLLF(2,K)=FLG*(A1+A2)
 3672 CLLF(3,K)=FLG*(L)+B2
 3673 CLLF(4,K)=FLG*(CL+C2)
 3674 A1=A2
 3675 D1=AL
 3676 CL=CL
 3677 FLG = 0.0
 3678 100 CONTINUE
 3679 C
 3680 CLLF(1,L)=ANTF(2,L)+BSIT
 3681 CLLF(2,L)=+1
 3682 CLLF(3,L)=+1

8-7a

```
3623      CUEF(4,L)=0.1
3624      CUEF(1,M)=ANTP(2,M)*HSIT
3625      CUEF(2,M)=0.0
3626      CUEF(3,M)=0.0
3627      CUEF(4,M)=0.0
3628      C
3629      YU CUEFOUT
3630      WRITE(6,4)INPT,HSIT
3631      45 FORMAT(1H1,*SUBROUTINE ANTPINT    NFT =*,15, *   CUEF =*,1F11.7)
3632      WRITE(6,105) ((ANTP(J,K),J=1,NL),CUEF(L,K),L=1,NL),NFT
3633      105 FORMAT (1H ,*(1FL0.7))
3634      C
3635      ENDLEN
3636      END
```

SUBROUTINE AZGAIN/ELGAIN

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
AZGAIN	Subordinate	Not user referenced
ELGAIN	Subordinate	Not user referenced

2. PURPOSE:

This function is to compute the antenna azimuth or elevation gain for any angle within the range of the user specified antenna data.

3. INPUT PARAMETERS:

Name	O/R	T	Description
ANTANG	R	F	The angle of the antenna main lobe in radar coordinates

4. CALLING SEQUENCES:

CALL G = AZGAIN (AZANGL) * ELGAIN (ELANGL)

Where: GA is the antenna gain corresponding to an azimuth angle of AZANGL and elevation angle of ELANGL.

5. RESTRICTIONS, REQUIREMENTS AND MISCELLANEOUS DATA

- a. The coefficients table must have been successfully initialized by the subroutine ANTINT before the function can be executed.
- b. Flow Charts: Pages 9-159/160
- c. Cross Reference Tables: Page 9-229.

6. THEORY OF OPERATION

The input angle ANGL is tested to determine if it is within the range of the input data. If it is outside the range, the gain value returned is zero. Otherwise, the gain is computed from the gain coefficients (A,B, and C)

that are closest in angle to ANGL.

$$AZGAIN = (\text{ANGR}^{**2}) * A + \text{ANGR} * B + C$$

Note: AZANGL is the angle measured in degrees CCW from any desired reference direction. ELANGL is the angle measured in degrees up from the horizon.

4003	FUNCTION AZGAIN(ANGL)	
4004	C	
4005	COMMON/LCLPAT/ LCLF(4,75),NCLEF	
4006	COMMON /BLK1/ HK1(500)	
4007	EQUIVALENCE (ANTANG,BK1(17))	
4008	DATA KULU/1/	
4009	C	
4010	ANGL=ANGL-ANTANG	
4011	IF (LCLF(1,1)=LE,ANGL,AND,ANGL,LE+CDEF(1,NCLEF)) GO TO 10	
4012	AZGAIN=0.0	
4013	RETURN	
4014	10 IF (ANGR=CDEF(1,KULU)) 20,30,30	
4015	KULU=KULU-1	
4016	GO TO 10	
4017	10 IF (ANGR.LE.LCLF(1,KOLD+1)) GO TO 50	
4018	KOLD=KOLD+1	
4019	GO TO 10	
4020	50 AZGAIN=AUDI (ANGR+CDEF(2,KULU)+CDEF(3,KCLF)+ANGR+CDEF(4,KOLD)) 1	
4021	C	
4100	C	
4101	RETURN	
4102	LND	
4103	FUNCTION ELGAIN(ANGL)	
4104	C	
4105	COMMON/LCLPAT/ LCLF(4,75),NCLEF	
4106	COMMON /BLK1/ HK1(500)	
4107	EQUIVALENCE (ANTANG,HK1(17))	
4108	DATA KULU/1/	
4109	C	
4110	ANGL=ANGL-ANTANG	
4111	IF (LCLF(1,1)=LE,ANGL,AND,ANGL,LE+CDEF(1,NCLEF)) GO TO 10	
4112	ELGAIN=0.0	
4113	RETURN	
4114	10 IF (ANGR.LE.LCLF(1,KOLD)) 20,30,30	
4115	KOLD=KOLD+1	
4116	GO TO 10	
4117	10 IF (ANGR.LE.LCLF(1,KOLD+1)) GO TO 50	
4118	KOLD=KOLD+1	
4119	GO TO 10	
4120	50 ELGAIN=(ANGR+CDEF(2,KOLD)+CDEF(3,KCLF)+ANGR+CDEF(4,KOLD))	
4121	C	
4122	C	
4123	RETURN	
4124	LND	

SUBROUTINE BLOCK DATA

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
BLOCK DATA	Subordinate	None

2. PURPOSE:

This non-executable module initializes the labeled common BLKRND which contains the random number array used by the random number generator.

3. INPUT PARAMETERS:

None

4. CALLING SEQUENCES:

None

This module is used only at load time to initialize the labeled area.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

a. The numbers used to initialize the random number array were derived from tables of random numbers published by the RAND Corporation: A Million Random Digits with 100,000 Normal Deviates, the Free Press of Glencoe, New York, 1955.

b. Flow Chart: Page 9-124

c. Cross Reference Table: Page 9-224

3210	BLOCK DATA	890	8-11
3211	COMMON/CLKEND/ JDMY1,IRND,IADD1,JEND,IOUM(1),RNNU1(65),RNNU2(64)	900	
3212	DATA JDMY1,IADD1/1,1/	910	
3213	DATA RNNU1/15154181997,2750966464,30323512272,20066227364,	920	
3214	* 14051007293,10402190240,26306499212,11266717040,	930	
3215	* 1801624773,1144273156,14404991345,067771280,	940	
3216	* 62503434137,33025570091,11012391622,1340130061,	950	
3217	* 31267410086,13462139250,20403855902,24,1977490,	960	
3218	* 14557020095,30512809719,12630506319,17722700814,	970	
3219	* 64722597022,16900286091,10283828091,10288044600,	980	
3220	* 2614690400,13570004754,111,8309520,2913423721,	990	
3221	* 13164662096,29908960258,03604486630,2451342654,	1000	
3222	* 2967307942,16416,51777,32749370939,71110173576,	1010	
3223	* 19781470043,20743061171,21119359579,19674491267,	1020	
3224	* 180244311326,60840120356,27142309994,16021175936,	1030	
3225	* 10410917113,23+164,0791,22825036652,10,007454494,	1040	
3226	* 0170,00000,17000000073,16041482734,28473484721,	1050	
3227	* 17160281537,29260744156,8633554400,366495374,	1060	
3228	* 16000001259,58E2873659,14224711880,12001451790,	1070	
3229	* 8100+1,880/	1080	
3230	DATA RNNU2/120000150000,000000000000,143000000000,	1090	
3231	* 15000000000,13458647055,0173+737400,0173+737400,	1100	
3232	* 01700000000,32320800000,1547139,797,070,2799917,	1110	
3233	* 14+76007,144,29317491972,7114043693,16,31,710823,	1120	
3234	* 2917000+246,26156574010,20135000000,14001007040,	1130	
3235	* 2507726024,0,1374070070,13070007591,304002122192,	1140	
3236	* 0017000000,16114261242,149718,10867,10,00000,	1150	
3237	* 10,10407399,18938138207,01,00074697,15,002214195,	1160	
3238	* 01577062400,16742167695,11016043767,11117411600,	1170	
3239	* 00,19,42,7160,5000000,1600000,2000000,32300420700,	1180	
3240	* 170,31+1632,25322444250,2007050175+1,43,1081553,	1190	
3241	* 30224145581,07655423387,30626402591,13101024674,	1200	
3242	* 30533512969,07218771539,00229536670,29190604401,	1210	
3243	* 0012200000,29107016500,16034007415,0009750100,	1220	
3244	* 098146000,128504776974,30256195160+100+2780,061,	1230	
3245	* 1,17+114000,10556707007,101400702000,97790171197,	1240	
3246	* 160,	1250	

SUBROUTINE DBLKX

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
DBLKX	Subordinate	Not user referenced
SDBLKX	Subordinate	Not user referenced

2. PURPOSE:

This subroutine is used to transfer a defined block of data from one array to another array.

3. INPUT PARAMETERS:

a. DBLKX

Name	O/R	T	Description
NST	R	I	First element of the input array to be transferred. Also, the first element of the output array to be used.
NWORD	R	I	Number of elements to be transferred.

b. SDBLKX

Name	O/R	T	Description
NST	R	I	First element of the input array to be transferred.
NWORD	R	I	Number of elements to be transferred.
LOC	R	I	First element of the output array to be used.

4. CALLING SEQUENCES:

CALL DBLKX (NST, NWORD, X, Y)

Where X contains the Input Waveform
 Y contains the Output Waveform

```

Y(NST+J) = X(NST+J)    J=1, NWORD
CALL SDBLKX (LOC, NST, NWORD, X,Y)
Where:   X contains the Input Waveform
          Y contains the Output Waveform
Y(LOC+J) = X(NST+J)    J=1, NWORD

```

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. All input data to this subroutine is provided through the calling argument list. This subroutine is not directly available to the program user, but is used by other subprograms for data transfer.
- b. Flow Chart: Page 9-122
- c. Cross Reference Table: Page 9-223.

3140	SUBROUTINE SUBLX(NST,NWORD,X,Y)	UC70BL01
3144	DIMENSION X(1),Y(1)	UC70BL02
3200	K=NST	UC70BL03
3201	DO 70 J=1	UC70BL04
3202	ENTRY SUBLX(LUC,NST,NWORD,X,Y)	UC70BL05
3203	K=LCC	UC70BL06
3204	20 CONTINUE	UC70BL07
3205	NST=NST+1,NWORD=1	UC70BL08
3206	DO 10 J=NST,NSTUP	UC70BL09
3207	Y(J)=X(K)	UC70BL10
3208	K=K+1	UC70BL11
3209	20 CONTINUE	UC70BL12
3210	RETURN	UC70BL13
3.11	END	

FUNCTION IBOOL

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Name
IBOOL	N/A	-

2. PURPOSE:

This function was used when checking out RADSIM on IBM computers. It has been replaced by the standard Honeywell intrinsic function B001.

3. INPUT PARAMETERS: N/A

4. CALLING SEQUENCES: N/A

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

a. Flow Chart: Page 9-119

b. Cross Reference Table: Page 9-223

3198	SUBROUTINE DBLKX(NST,NWORD,X,Y)	UC7DBL01
3199	DIMENSION X(1),Y(1)	UC7DBL02
3200	K=NST	UC7DBL03
3201	GO TO 20	UC7DBL04
3202	ENTRY SUBLKX(LOC,NST,NWORD,X,Y)	UC7DBL05
3203	K=LUC	UC7DBL06
3204	20 CONTINUE	UC7DBL07
3205	NSTOP=NST+NWORD-1	UC7DBL08
3206	DO 10 J=NST,NSTOP	UC7DBL09
3207	Y(J)=X(K)	UC7DBL10
3208	K=K+1	UC7DBL11
3209	10 CONTINUE	UC7DBL12
3210	RETURN	UC7DBL13
3211	END	

FUNCTION IFLD

1. MODULE IDENTIFICATION:

Name	Classification Code	Reference Number
IFLD	N/A	-

2. PURPOSE:

This function was used when checking out RADSIM on IBM computers. It has been replaced by the standard Honeywell intrinsic function FLD.

3. INPUT PARAMETERS: N/A

4. CALLING SEQUENCES: N/A

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

a. Flow Chart: Page 9-123

b. Cross Reference Table: Page 9-224

3212 FUNCTION IFLD(IST,NBITS,IWORD)
3213 IFLD=FLD(IST,NBITS,IWORD)
3214 RETURN
3215 END

UC7DBL14
UC7IFD01
UC7IFD02
UC7IFD03
UC7IFD04

FUNCTION IPACK

1. MODULE IDENTIFICATION:

<u>Name</u>	<u>Classification Code</u>	<u>Reference Number</u>
IPACK	Subordinate	Not User Referenced

2. PURPOSE:

This function subprogram is used to pack two or more groups of bits into a standard computer word (36 bits).

3. INPUT PARAMETERS:

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
ISTR	R	I	The lowest bit into which data transfer is to occur. The bit number is counted starting with the LSB. ISTR = 0 corresponds to the LSB and ISTR = 35 corresponds to the MSB.
IDATA	R	I	The data which is to be packed into the output word.
IWORD	R	I	The word into which the data is to be packed.

4. CALLING SEQUENCES:

CALL IOUT = IPACK (ISTR, IDATA, IWORD)

IOUT = IWORD \oplus (IDATA*(2**ISTR)) \oplus = inclusive or

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA

- a. The field (bit locations) of the output word which is to receive the input data must contain zeros before execution of the function.
- b. If the data to be placed in the output word is larger than the allocated field then either the data in a higher field will be destroyed or if it is the highest field then some of the most

significant bits of IDATA will extend past the standard word length and be lost.

c. Flow Chart: Page 9-118

d. Cross Reference Table: Page 9-223

6. THEORY OF OPERATION

The input data, IDATA, is multiplied by the power of two equivalent to the number of bit positions that it must be shifted in order to line up with its field in the output word. Once the data has been shifted to the proper position, then it is merged into the output word, IWORD, by using an inclusive OR operation.

This function is not directly available to the simulation user, but is used by subprogram within the simulation.

SACD	FUNCTION IPACK(ISTRP, IDATA, IWORD)	UC7IPK01
.1.1	ITLMP=IDATA*(2**ISTRP)	UC7IPK02
S120	IPACK = IDULU(UTK(ITLMP, IWORD))	UC7IPK03
S124	RETURN;	UC7IPK05
S130	END.	UC7IPK06

SUBROUTINE PACK

1. MODULE IDENTIFICATION:

<u>Name</u>	<u>Classification Code</u>	<u>Reference Number</u>
PACK	SUBORDINATE	Not user referenced

2. PURPOSE:

This subroutine takes a word in integer format and converts the lower 13 bits of the word into two 8 bit ASCII characters. The ASCII characters are subsequently transmitted to a remote plotting terminal via TSS. Remote plotter accuracy assumed to be 12 bits maximum.

3. INPUT PARAMETERS:

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
IWD	R	I	Output array word location pointer.
IBIT	R	I	Bit displacement to be used in placing the characters in the output word

4. CALLING SEQUENCES:

CALL PACK (IDAT, IWD, IBIT, IARY, \$IIII)

Where: IDAT is the Input word
IARY is the Output array
IIII is the statement number to which control is transferred if the output array is full (68 characters)

5. RESTRICTIONS, RECOMMENDATIONS, MISCELLANEOUS DATA

- a. The maximum array length is restricted to 68 characters to be compatible with TSS.
- b. The maximum allowable accuracy of the word is 13 bits, i.e. bits 0 through 24 must be zero.
- c. Flow Chart: Page 9-88
- d. Cross Reference Table: Page 9-219

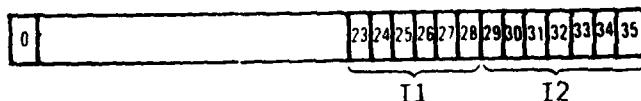
6. THEORY OF OPERATION

The input word IDAT is shown pictorially as follows:



Bit 0 is the MSB and Bit 35 is the LSB.

This word is divided into two characters, I1 and I2 as illustrated by the following:



Next I2 is tested to determine if any TSS command characters have occurred. If so, the value of I2 is incremented by +1 or -1 as follows:

<u>TSS Character</u>	<u>Actual No.</u>	<u>Increment</u>
DC1 (XON)	21_8	+1
CAN	30_8	+1
EOT	4_8	+1
RUBOUT	177_8	-1
SOH	1	-1
ETX	3	-1

Since I1 is 6 bits in length a rubout (177_8) cannot occur. Therefore, the remaining TSS characters to protect against have values which are less than 32_{10} . Accordingly, I1 is tested and if its value is less than 32_{10} then bit 7 of I1 is set "on" to preclude occurrence of the undesired character.

Finally, I1 and I2 are packed into the output word pointed to by IWD. The parameter, IBIT, specifies the displacement of I1 from bit 0 of the output word, IARY (IWD).

```

2414      SUBROUTINE PACK(IADT,IWD,IBIT,IARY,*)
2420      DATA 1ROT/0177/,1BIT7/0100/,IXDN/021/,ICAN/030/
2421      DATA 1EUT/4/,1Z/0172/,ICONA/1/,ICOUN/3/
2422      DIMENSION IARY(1)
2423      I=IARY(IWD)
2424      11=FLD(23,6,1DAT)
2425      12=FLD(29,7,1DAT)
2426      1E(11+11+52,AND,11+GT,0) 11=11+1BIT7
2427      1E(12+10,1EUT,OK,1Z-EQ,ICONA,OK,12-EQ,ICOUN) 1Z=1Z-1
2428      1E(12+10,IXDN,OK,12-EQ,ICAN,OK,12-EQ,1EUT) 1Z=1Z+1
2429      1E(12+10,1Z) 1Z=1Z+1
2430      FLDT(11+9,IARY(IWD))=11
2431      1E11=1E11+9
2432      FLDT(11+9,IARY(IWD))=12
2433      1E11=1E11+9
2434      1E(11+10,5) RETURN
2435      1E11=0

```

8-20

LINE NO.	STATEMENT	AUTOFLOW CHART SET - FWD/SCC - RADSIM	
LINE NO.	*****	CONTENTS	*****
2430	IWD=JWD+1		
2431	1E(11+10,5) RETURN 1		
2432	FLDT(11+9,IARY(IWD))=12		
2433	1E11=0		

FUNCTION RRAND

1. MODULE IDENTIFICATION:

<u>Name</u>	<u>Classification Code</u>	<u>Reference Number</u>
RRAND	Subordinate	101, 102 (Parameter initialization only)

2. PURPOSE:

This function generates random numbers for use in various subprograms of the simulation model. Samples from the uniform, Gaussian and Rayleigh distributions can be generated. In addition, two statistical target models are incorporated which are based on the Chi-square distribution with 2 and 4 degrees of freedom.

3. INPUT PARAMETERS: (User supplied data through namelist NL101)

<u>Name</u>	<u>O/R</u>	<u>T</u>	<u>Description</u>
MAD1	0	I	The starting address for selecting random numbers from the random number array ($1 \leq MAD \leq 128$)
UMEAN	0	F	Mean value of the uniform distribution
UUEXT	0	F	Width of the uniform distribution
XMEAN	0	F	Mean value of the Guassian distribution
SIGMA	0	F	Standard deviation of the Guassian and Rayleigh distributions, and average cross section for target models
NTYPE	R	I	Control integer which specifies the type of distribution to be generated

Name	O/R	T	Description
NTYPE	R	I	NTYPE = 1 Uniform distribution (floating point output) = 2 Rayleigh = 3 Gaussian = 4 Uniform distribution (integer 0 to 2^{35}) = 5 Not used = 6 Swerling Target Models #1 and #2 = 7 Swerling Target Models #3 and #4 = 8 Sine
NRAND	R	I	Array containing random numbers which are used to generate the output variates

Variables initialized during execution of the initializer load module based on user supplied data. These intermediate values are generated in order to minimize execution time of the function, i.e., to avoid repeating the same calculations for each entry to RRAND.

```

SIG2SQ = 2.0 *SIGMA * SIGMA
UL      = UMEAN - 0.5 * UUEXT
UEXT    = UUEXT/2 ** 35

```

4. CALLING SEQUENCE:

VAR = RRAND (NTYPE)

VAR will contain the random sample generated by the function from the NTYPE probability distribution.

5. RESTRICTIONS, REQUIREMENTS, MISCELLANEOUS DATA:

- a. Before any call can be made to the function RRAND the input data must be loaded using namelist 101. Any subsequent changes in random variate distributions are also made through namelist 101.
- b. For convenience and to minimize program steps the array IRAND was equivalenced to the array NRAND but displaced by one location. This structure allows an address of zero to be used, i.e., an

address of zero will access IRAND(0) which overlays NRAND(1). If this were not done, a test would have to be performed on MAD1 to ensure that an address of zero did not occur.

- c. A list of random numbers suitable for initializing the array NRAND are included at the end of this section.

d. Flow Chart Page 9-120

e. Cross Reference Table Page 9-223

6. THEORY OF OPERATION:

For each call to the function RRAND a number IRND is selected from the random number table IRAND. The address of the number selected from the table is MAD1 which is also a random number. The number IRND is added to the random number JRND which was generated by the previous execution of the function. The sign bit is set to zero to ensure a positive number. By adding the two random numbers and truncating the overflow, a new random number is generated which is also called IRND. IRND is placed in the random number table location previously occupied by the original IRND. In this manner the random number table is updated by generating new random numbers and inserting them in the table. From this random number IRND, 7 bits are selected to determine the new address MAD1 to be used in the next call to the function. The 7-bit address field allows the addresses to range from 0 to 127. The random number IRND just generated is an integer having an uniform distribution from 0 to 2³⁵ - 1. Once the random number is generated JRND is set equal to IRND for use in the subsequent executions of the function. In order to convert this number to a floating point number r having a uniform distribution from 0 to 1.0, the following conversion is used.

$$r = \text{FLOAT}(IRND)/2^{35}$$

From this uniform distribution other probability distributions can be generated by using transformations which map a uniform distribution into the desired distribution. The following is a list of the transformations used in the function.

a. Uniform distribution $a \leq x \leq b$

$$x_n = (b - a)r_n + a$$

b. Rayleigh distribution $P(x) = \frac{x}{\sigma^2} e^{-\frac{x^2}{2\sigma^2}}$

$$x_n = \sqrt{-2\sigma^2 \ln r_n}$$

c. Gaussian distribution $P(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{x^2}{2\sigma^2}}$

$$x_n = \sqrt{2\sigma^2 \ln r_n} * \cos 2\pi r_{n+1}$$

d. Swerling Target Models #1 & #2 $P(x) = \frac{1}{\sigma} e^{-\left(\frac{x}{\sigma}\right)^2}$

$$x_n = -\bar{\sigma} \ln r_n \quad \bar{\sigma} = \text{average cross section}$$

This distribution characterizes a target with a large number of independent scatterers of approximately equal cross section (Swerling cases 1 and 2).

e. Swerling Target Models #3 & #4 $P(x) = \frac{4\sigma}{\bar{\sigma}^2} e^{-\left(\frac{x}{\bar{\sigma}}\right)^2}$

$$x_{2n} = \frac{-\bar{\sigma}}{2} (\ln r_n + \ln r_{n+1}) = \text{average cross section}$$

This distribution characterizes a target with one dominant scatterer plus smaller scatterers or one large reflector subject to small changes in orientation (Swerling Cases 3 and 4).

3207 FUNCTION KRANE(INTYPE) 8-25
UC7RNY01
 3208 COMMON/LKANE/IDMY1, JKNL, MA01, JN01, UMEAN, UEXT, XMEAN,
 3209 *SIGMA, UUM+SIG250,UL,UEXT,NKND(129) UC7RNY03
 3210 DIMENSION IKND(128) UC7RNY04
 3211 DATA JKEP1/0/,IMULT/1220703125/
 3212 DATA IMAX/4294967296/,N2P1o/0553o/
 3213 DATA L1Z/2.4203E30F-12/
 3214 EQUIVALENCE (JFAND1,NFAND1) UC7RNY05
 3215 LU KEND=IKND(MA01) UC7RNY06
 3216 JEND=KEND+JKNL+IMULT 210
 3217 JKNL = JFAND1,NS+JEND UC7RNY07
 3218 IKND(MA01)=JKNL UC7RNY08
 3219 MA01 = FLD(1,0,7,JEND) UC7RNY09
 3220 IF(IDMY1.eq.1) WRITE(6,1001) JEND,ERNL,MA01,MA02,KEND,KND,
 3221 * JEND,JKNL UC7RNY10
 3222 1001 FORMAT(1H + 4F15.015)
 3223 DL = 10, EXUL=300,400,500,600,700,800,900,1000 250
 3224 Z00_KNAD = FLDAT(JKNL)*UEXT + DL UC7RNY11
 3225 JN01 = JKNL UC7RNY12
 3226 RETURN UC7RNY13
 3227 J00_KRANL = SCKTESEG250*ALEG(FLDAT(JKNL)*UEXT) UC7RNY14
 3228 JN01 = JKNL UC7RNY15
 3229 RETURN UC7RNY16
 3230 900 CONTINUE 320

8-25a

```

3161      400  IZ=FLD(1+17*KEND)-N1P16
3162      IZ=FLD(18,17*KEND)-N2P16
3163      IZ=I1+I2+IZ*I2
3164      IF(IJ<LT+IMAX) GOTO 20
3165      JRND=IKND
3166      GOTO 10
3167      20  S=1.0/FLAT(15)
3168      VCLC=S*FLAT((I1*I2-I2*I1))
3169      VSINE=S*2.0*FLAT(I1*I2)
3170      INTTYPE=2,S1 GO TO 405
3171      SRAND=VSUS
3172      DUM=VSINE
3173      JKND=IKND
3174      RETURN
3175      400  DRMS=Sqrt(SIGMA*ALOG(FLAT(JRND)*C1))
3176      KRANE=DUM*VCLC + XMEAN
3177      DUM=DUM*VSINE + XMEAN
3178      JKND=IKND
3179      RETURN
3180      500  KRAND=SQR(JRND)
3181      JRND=IKND
3182      RETURN
3183      600  KRAND=DUM
3184      RETURN
3185      700  KRAND=-SIGMA*ALOG(FLAT(IRND)*C1)
3186      JKND=IKND
3187      RETURN
3188      800  IF(IREPT>L0+1) GO TO 801
3189      SUM=0.0
3190      801  SUM=SUM+ALOG(FLAT(IRND)*C1)
3191      IREPT=IREPT+1
3192      IF(IREPT>NL+2) GO TO 10
3193      IREPT=0
3194      KRAND=-SIGMA*SUM/2.0
3195      JKND=IKND
3196      RETURN
3197      END

```

UC7RNY38
UC7RNY39
UC7RNY40
UC7RNY41
UC7RNY42
UC7RNY43
UC7RNY44
UC7RNY45
UC7RNY46
UC7RNY47
UC7RNY48
UC7RNY49
UC7RNY50
UC7RNY51
UC7RNY52
UC7RNY53
UC7RNY54
UC7RNY55
UC7RNY56
UC7RNY57
UC7RNY58
UC7RNY59

LIST OF RANDOM NUMBERS

The following list of random numbers is suitable for initializing the random number array NRAND used by the function subprogram RRAND. The numbers were derived from tables of random numbers published by RAND Corporation:
A Million Random Digits with 100,000 Normal Deviates,
the Free Press of Glencoe, New York, 1955.

```
*NL101  NRAND= 12068158044,06847664659,15416782760,19382343178,  
33122308420,25052201840,13988647055,C17347374CE,C7289355507,  
16534467415,24386072834,29317493972,C7114843643,16232718423,  
C616041E880,1641C917E13,23416520791,26825638452,10800745449,  
29107616508,23120785669,32320902560,15471392797,076E3759917,  
C3669736170,29170504246,26866574818,20335880812,14861357546,  
C3451463822,25072568248,21374670078,13676667951,30463132192,  
05804776974,20172084006,16184261842,14974210467,10283018420,  
30256545185,18310257399,1893818E207,01286074657,19662214195,  
10832795361,01577045480,16742867655,116E6E48767,18174114680,  
18174114680,30892487160,30892487160,28360548700,333E84157C9,  
10556707007,17235921632,25322444850,30007056175,13488881553,  
10140208896,3022414E581,C7655423387,32626402551,131C1024674,  
C5779017119,30533512969,07218771539,00229536870,291986044C1,  
C1702686304,15134181597,27509E64464,3C323512272,30068227398,  
17006458873,14051007893,16402190290,26306590212,11260717646,  
16841482774,16801629773,11349273156,194C4991345,06977712830,  
26473264721,C2883434137,23025570C91,11012391622,13431365861,  
17160292937,31267410086,13462135250,26463E85502,24215774296,  
29620744156,11557820695,3C512809719,12630506319,17722780814,  
08883554436,04722597022,16500280091,1E243E24C41,16388044606,  
C3664953728,25212648408,13570004754,11188305528,29134237821,  
16068801392,131E4942096,2990896E258,C35E49E6686,24513426529,  
05883873859,25262307992,1641E251777,32149370939,2111617E576,  
14824731880,19395173043,20743061171,21319355579,19074491967,  
18081451743,19244390324,C6E4F123356,271423C9954,15825176938,
```

S E C T I O N 9

R A D S I M C O M P U T E R P R O G R A M

F L O W C H A R T S

PUBLISHED IN PART 2 OF THIS VOLUME.

SECTION 10

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and Appendix B in Volume IV, Part 1)

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<u>PROGRAM/ SUBROUTINE / FUNCTION</u>	<u>MODULE NUMBERS</u>	<u>DESCRIPTION & LISTING PAGE</u>	<u>FLOW CHART PAGE</u>	<u>CROSS REF. PAGE</u>
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<u>PROGRAM/ SUBROUTINE FUNCTION</u>	<u>MODULE NUMBERS</u>	<u>DESCRIPTION & LISTING PAGE</u>	<u>FLOW CHART PAGE</u>	<u>CROSS REF. PAGE</u>
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S E C T I O N 11
R E C U R S I V E C O M P U T A T I O N
O F S I N E / C O S I N E P A I R S

Many computer programs require the evaluation of sine and cosine functions for angles that are uniformly spaced over the interval from 0° to 360° , for example, DFT subroutine. In many cases the CPU time required to execute these computer programs can be significantly reduced by the use of the following digital oscillator to generate sine/cosine pairs. The Z-plane representation of the digital oscillator is shown in Figure 11-1.

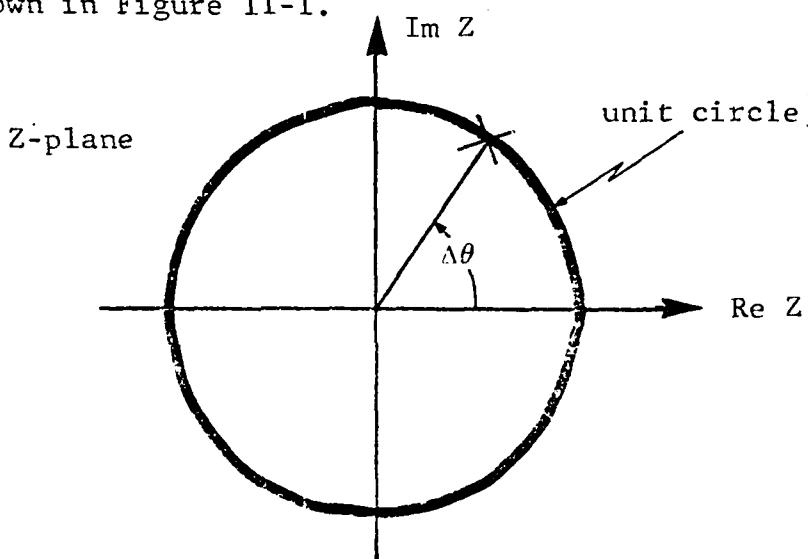


Figure 11-1 Z-PLANE REPRESENTATION OF THE DIGITAL OSCILLATOR

The variable $\Delta\theta$ is the angular increment for which the sine/cosine pairs are to be calculated. The digital oscillator block diagram is shown in Figure 11-2.

The stimulus $[\cos \theta_0 + j \sin \theta_0]$ is applied only when $n=0$ and is zero otherwise. Before execution of the digital oscillator routine, the storage registers (A & B) used to generate the unit delays must be cleared.

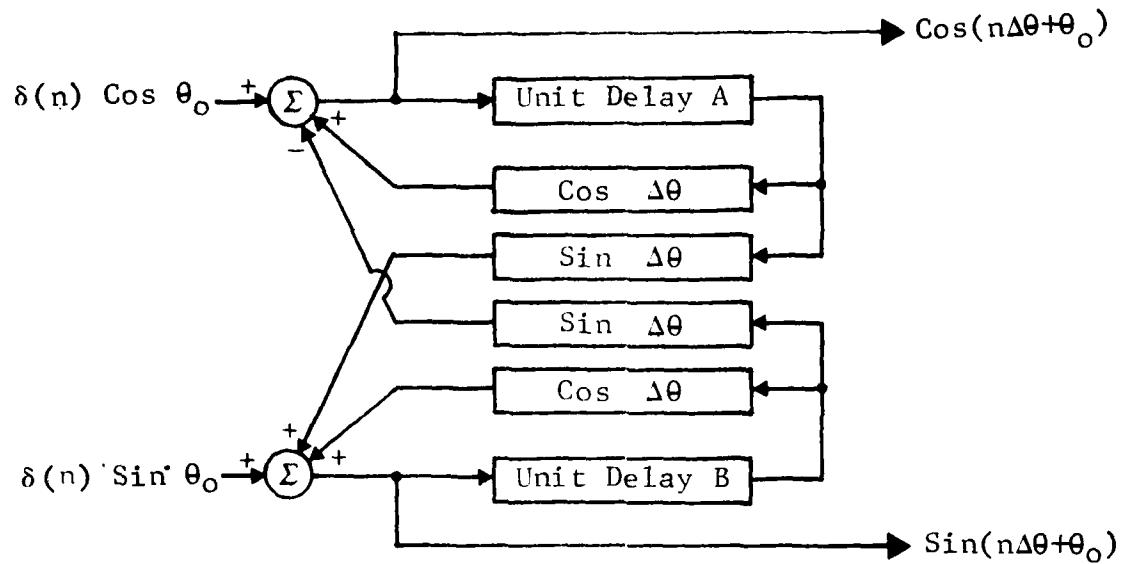


Figure 11-2 DIGITAL OSCILLATOR BLOCK DIAGRAM

n = number of executions of the digital oscillator routine.

The Fortran statements for implementing the digital oscillator are the following:

```

A = Cos (θ0)
B = Sin (θ0)
DELC = Cos (Δθ)
DELS = Sin (Δθ)

Loop
n=1, N
    TEMP = A
    A = A * DELC - B * DELS
    B = TEMP * DELS + B * DELC
}
{A and B contain the
{sine/cosine of [θ0+(n-1)Δθ]}
```

where $\Delta\theta$ = angle increment,
 θ_0 = starting angle.

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